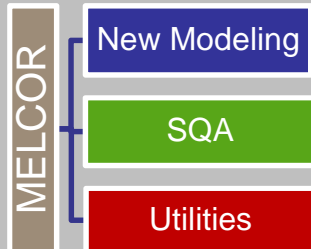


*Exceptional service in the national interest*



# MELCOR Code Development Status

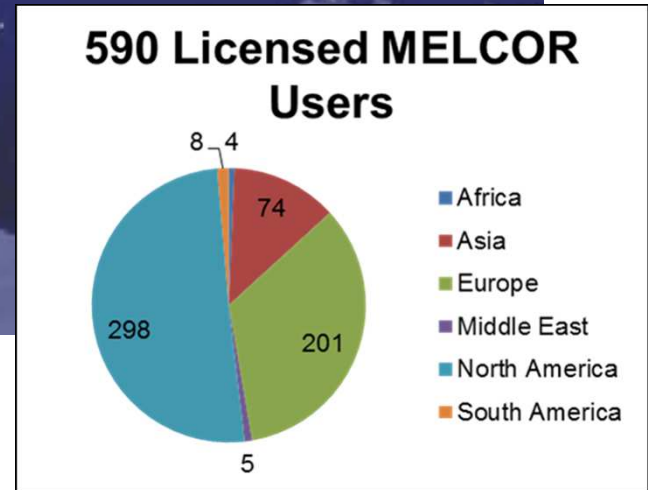
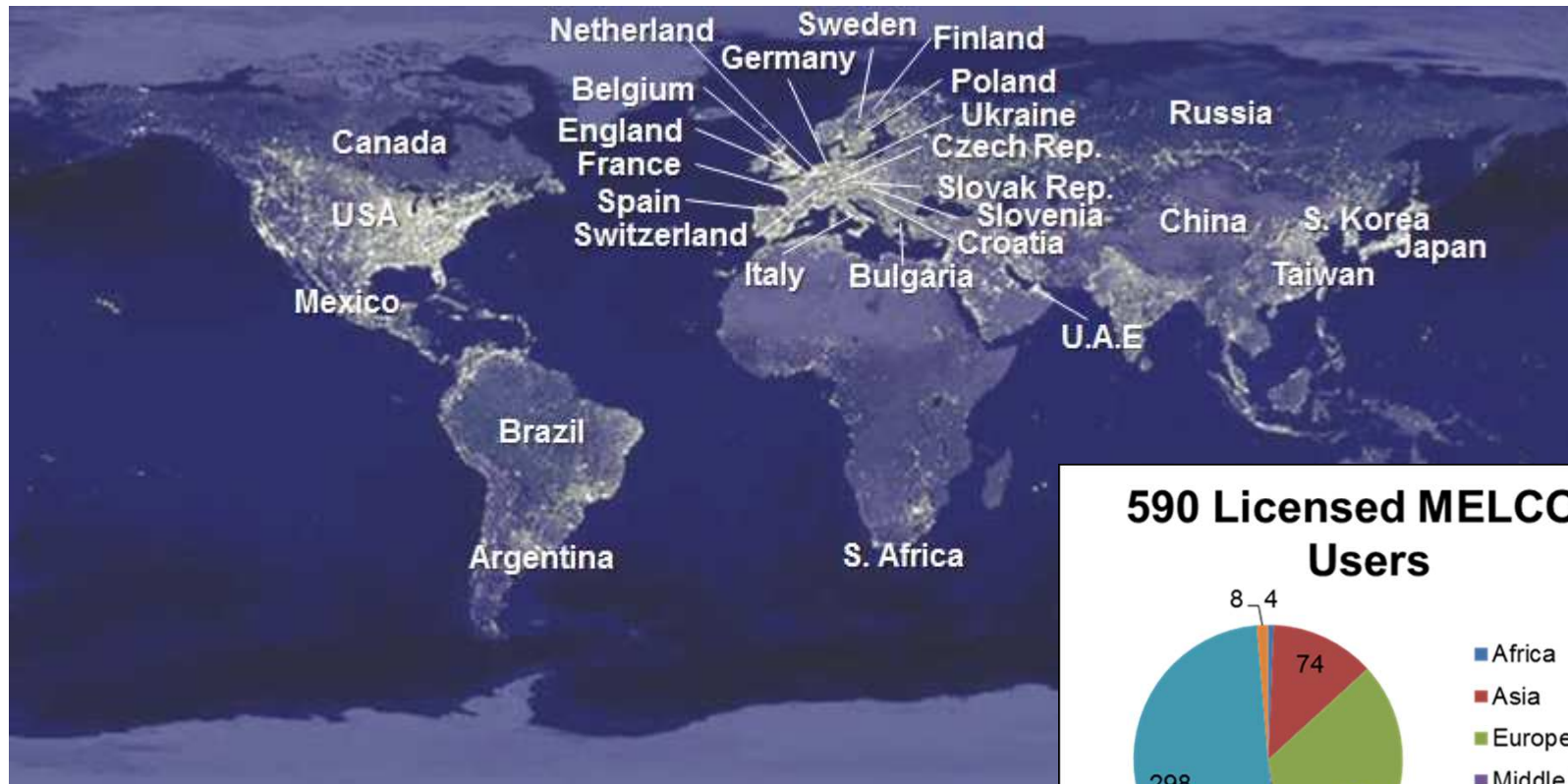
## EMUG 2016

Presented by Larry Humphries  
llhumph@sandia.gov



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# International Use of MELCOR



# MELCOR Workshops & Meetings

- 2015 Asian MELCOR User Group (AMUG)
  - Hosted by CRIEPI (Japan)
  - November 2015
- 2016 European MELCOR User Group (EMUG)
  - Hosted by Imperial College London & AMEC
  - April 6-7, 2016
- 2016 CSARP/MCAP/MELCOR Workshop
  - September 12, 2016
  - Bethesda, MD
  - Focus will be on CF package & new models
- 2016 Asian MELCOR User Group (AMUG)
  - Hosted by SPICRI & NRSC (Beijing)
  - October 17 – 21, 2016
  - MELCOR/MACCS Workshop



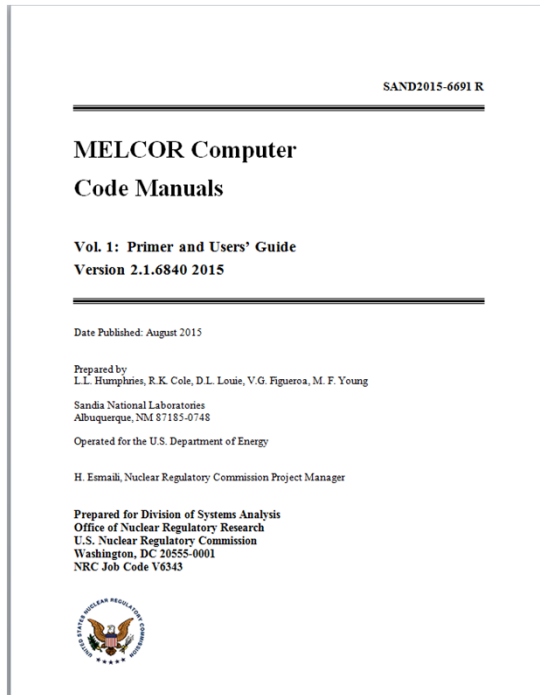
# 2016 MELCOR Workshop

## Preliminary Agenda



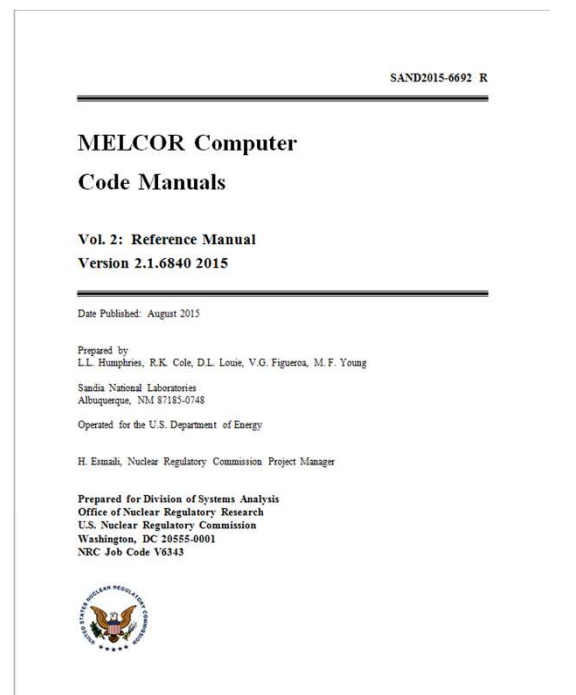
- Workshop Introductions & Overview (30 min) Humphries
  - *Review of the MELCOR code development and introduction of workshop.*
- 2 MELCOR overview (30 min) Humphries
  - *Very general overview of MELCOR code and discussion of how data utilities are used.*
- 3 Data & Control Utilities (90 min) Phillips
  - *Discussion of MELCOR tabular functions, control functions, and EDF utility.*
- 4 Recent Control Function Enhancements (60 min) Humphries
  - *Use of vector control functions, vector arguments, and user-defined functions.*
- 5 Practical CF Modeling (90 min) Ross
  - *Practical examples of CF modeling in a plant application and the use of SNAP in visualizing control functions.*
- 6 New MELCOR models -1 (45 min) Beeny
  - *Use of the new homologous pump model and second lower head (core catcher) with working examples and exercises.*
- 7 New MELCOR Models – 2 (45 min) Humphries
  - *Working with the radiation enclosure model, Zukauskas HTC, multi-rod model, Na working fluid with working examples and exercises.*
- 8 Workshop Wrap-up (30 min) Humphries
  - *Workshop Q/A, presentation of certificates, workshop evaluations.*

# MELCOR Documentation



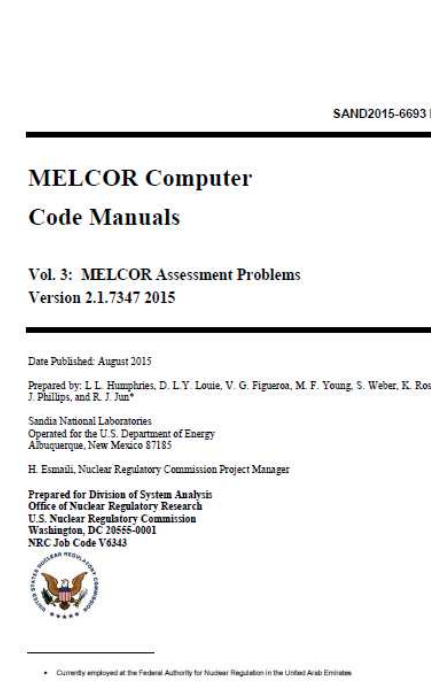
## Volume I: User Guide

R&A Complete  
SAND2015-6691 R



## Volume II: Reference Manual

R&A Complete  
SAND2015-6692 R



## Volume III: Assessments

R&A Complete  
SAND2015-6693 R

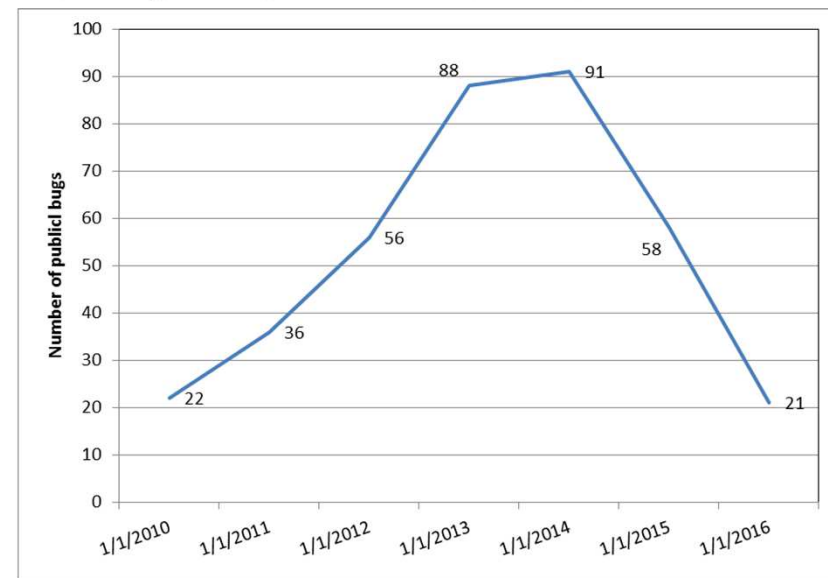
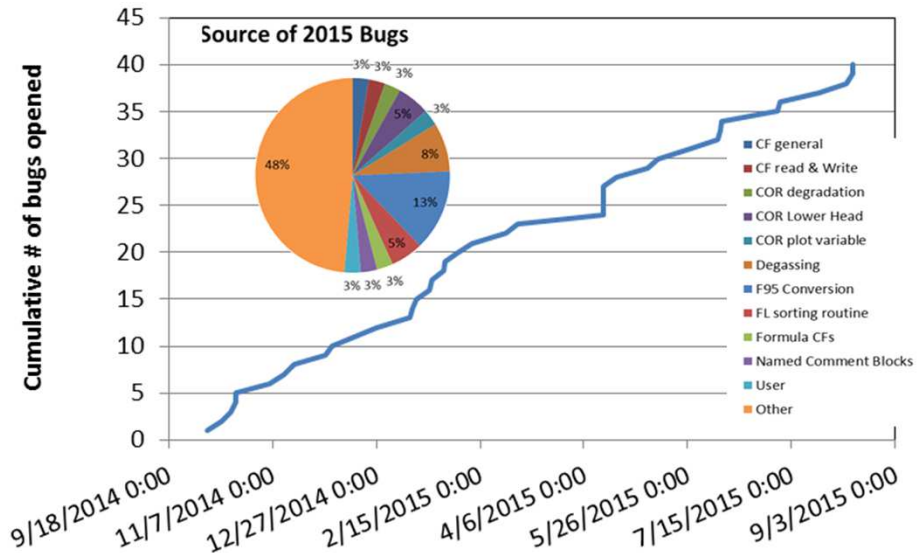
# MELCOR Debugging Trends

## ■ Statistics

- Approximately 40 public bugs are reported each year.
  - There are additional private bugs that are resolved.
- More than 50 bugs were resolved in 2015
  - F95 Conversion 13%, Degassing 8%, etc.

## ■ Important bugs recently resolved

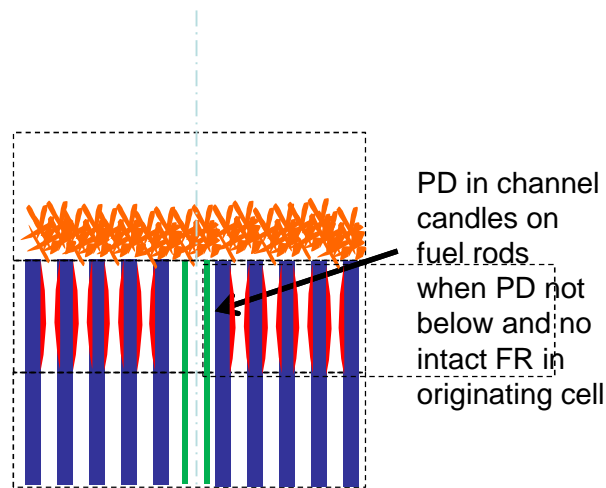
- Lipinski dryout model not used above the core support plate
  - Occurrence of PD would stop convective heat removal in a COR cell
- Revised candling model for B4C
  - Metallic zircalloy from canister rubble candled onto intact rods, leading to oxidation and fuel rod failure (next slide)
- Improvements to quench model
  - Pool Atmosphere interaction
  - Temporal relaxation of quench velocity



# Revised Candling Model from PD to Cell below with intact Rods

PD from cell with no intact FR

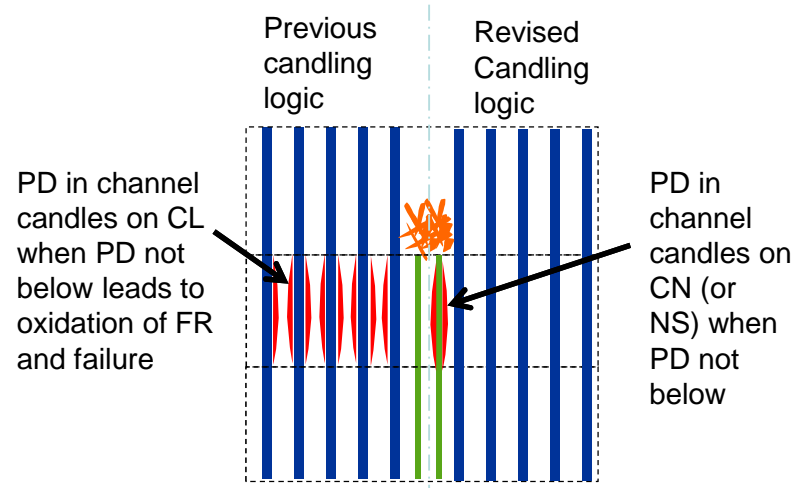
No Change



- Fuel Rods (FU+CL)
- Canister (CN+CB)
- Conglomerate (candling)
- ✖ Particulate Debris (PD+PB)

PD from cell with intact FR

Candles on NS, CN, or CB



- Fuel Rods (FU+CL)
- Canister (CN+CB)
- Conglomerate (candling)
- ✖ Particulate Debris (PD+PB)



# New Model Development Tasks (2014-2015)

- Completed
  - Homologous pump model
  - Multi-HS radiation enclosure model
  - Aerosol re-suspension model
  - Zukauskas heat transfer coefficient (external cross-flow across a tube bundle)
  - Simplistic bubble swell model
  - Core Catcher (multiple containment vessels)
  - Multiple fuel rod types in a COR cell
  - New debris cooling models added to CAV package
    - Water-ingression
    - Melt eruption through crust
  - Miscellaneous models and code improvements
    - COR\_HTR extended to heat structures
    - LAG CF
    - MACCS Multi-Ring Release
    - Valve Flow Coefficient
    - MACCS release types
- In Progress
  - Spreading model implemented into CAV package (almost completed)
  - Vectorized Control Functions
  - CONTAIN/LMR models for liquid metal reactors
  - CVH/FL Numerics
  - MAEROS Extensions



# Homologous Pump Model



- Transient Pump operation characterized by
  - Rotational speed
  - Volumetric flow rate
  - Dynamic head
  - Hydraulic torque
- Pump characteristic curves or four quadrant curves
  - Any one of the above quantities can be expressed as a function of any other two
    - Dynamic head and hydraulic torque are expressed as functions of volumetric flow and rotational speed ratios
      - Eight curves for the dynamic head
      - Eight curves for hydraulic torque
  - Empirically developed by manufacturer
  - Similarities to RELAP and TRACE models
- Curve Definitions
  - Built-in pump curves
    - Semi-scale
    - Loft
  - User defined curves
    - Uses tabular function (32 TFs for full coverage)
    - If user does not define all modes, error occurs when pump enters undefined domain
  - Universal correlation
    - Systematic approach for predicting pump performance where data does not exist
    - Fits to several data sets (including LOFT & Semiscale)
    - Only valid in normal operating mode
    - Lahssuny, Jedral. Universal Correlations for Predicting Complete Pump Performance Characteristics. 2004.

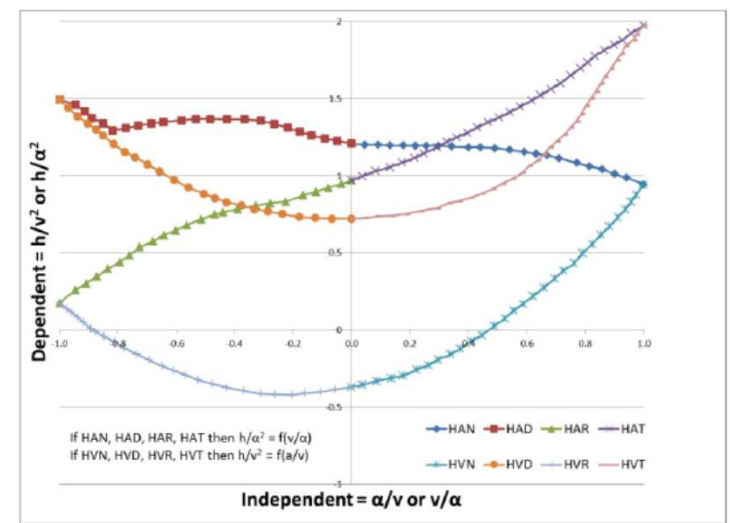


Figure 1. Semiscale single-phase head curve

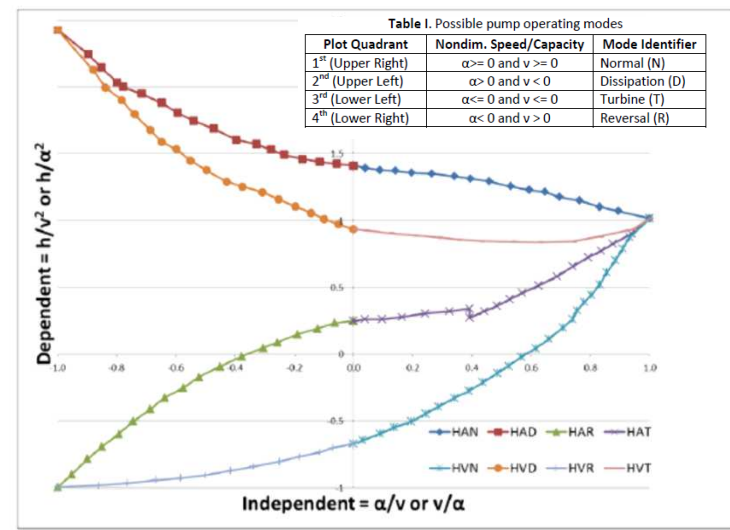


Table 1. Possible pump operating modes

Plot Quadrant	Nondim. Speed/Capacity	Mode Identifier
1 <sup>st</sup> (Upper Right)	$\alpha < 0$ and $v >= 0$	Normal (N)
2 <sup>nd</sup> (Upper Left)	$\alpha > 0$ and $v < 0$	Dissipation (D)
3 <sup>rd</sup> (Lower Left)	$\alpha <= 0$ and $v <= 0$	Turbine (T)
4 <sup>th</sup> (Lower Right)	$\alpha < 0$ and $v > 0$	Reversal (R)

Figure 4. LOFT single-phase head curve

$$\alpha = \frac{\omega}{\omega_R} \text{ and } v = \frac{Q}{Q_R}, \text{ for rated speed and capacity } \omega_R, Q_R$$

# Homologous Pump Model

- MELCOR specific implementation
  - Equations cast in polar form which reduces to two closed curves
    - Simplifies programming
      - Independent variable is always positive and bounded
      - Octants are ordered in monotonically increasing fashion, simplifying interpolation
    - Dynamic head
    - Hydraulic torque
- Data output
  - Single phase and fully-degraded pump head, single-phase and fully-degraded hydraulic torque, dissipation losses
- Data input
  - Flow path associated with pump
  - Rated pump data
    - Impeller speed, volumetric flow rate, head, hydraulic torque, density of pumped fluid, motor torque, ratio of initial speed to impeller speed
  - Single/2-phase homologous pump performance curves
    - Optional built-in data for Semi-scale, LOFT, and “universal correlation”
  - Pump friction torque as a polynomial in pump speed
  - Pump inertia as a polynomial in pump speed
  - Pump speed and motor torque controls
  - Pump trips

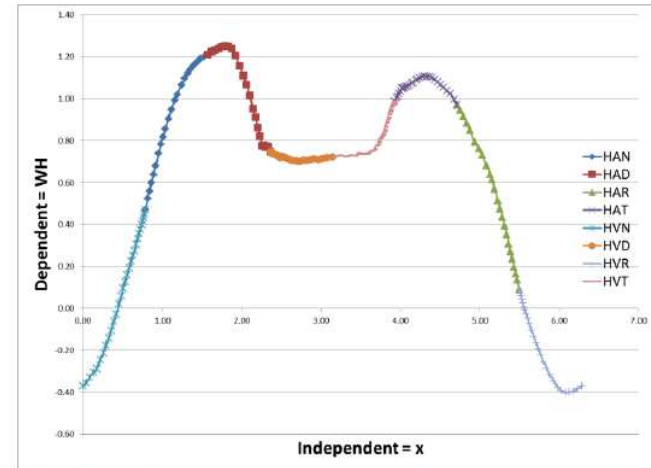


Figure 6. Polar homologous single-phase head curve, Semiscale, compare to figure 1

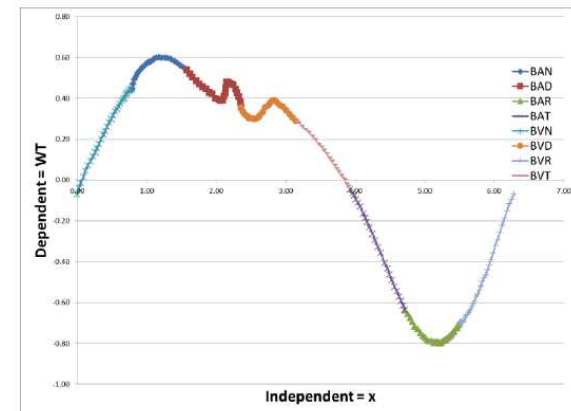


Figure 7. Polar homologous single-phase hydraulic torque curve, Semiscale, compare to figure 2

$$\alpha = \frac{\omega}{\omega_R} \text{ and } v = \frac{Q}{Q_R}, \text{ for rated speed and capacity } \omega_R, Q_R$$

# Multi HS Radiation Enclosure Model

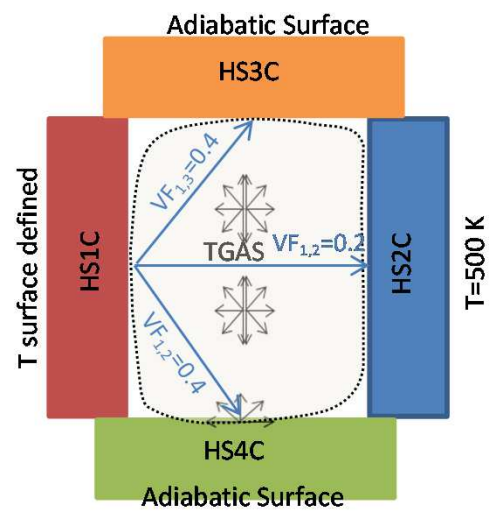
- Previous HS radiation model
  - Radiation defined only for surface pairs
  - Radiation to gas performed independently for each surface
    - Does not account for transmissivity of gas
- New enclosure model
  - Multiple enclosure networks, each with multiple heat structures defined by the user.
    - Memory dynamically allocated
  - User defines all surfaces exchanging radiant heat
    - Matrix of view factors connecting surfaces
  - Participating gas
    - Transmissivity accounts for reduction in radiation between surfaces
    - Only 1 CV associated with all surfaces
    - User supplies beam length (similar to COR package)

$\tau_{j,i}$  is the transmissivity through gas

$$J_i = (1 - \epsilon_i) \cdot \sum_j [F_{ij} \cdot \tau_{j,i} \cdot J_j] + \epsilon_i \cdot \sigma \cdot T_i^4 + \rho_i \epsilon_m E_{bm}$$

$$G_i = \sum_j [A_j \cdot F_{ji} \cdot \tau_{j,i} \cdot J_j] / A_i + \epsilon_m E_{bm}$$

$$q_i = A_i (J_i - G_i)$$



HS_RAD	4	NET3	!EM	BeamL	VF
1	HS1C	LEFT	EM1	0.5	0.0 0.2 0.4 0.4
2	HS2C	LEFT	EM2	0.5	0.2 0.0 0.3 0.5
3	HS3C	LEFT	-	0.5	0.4 0.3 0.2 0.1
5	HS4C	LEFT	-	0.5	0.4 0.5 0.1 0.0

TF_ID	TEMP	1.0	0.0	!T	Surface Defined
TF_TAB	4				
1	0.0	500.0			
2	500.0	1500.0			
3	1000.0	1500.0			
4	30000.0	1500.0			

# Multi HS Radiation Enclosure

## 3HS Example



- Identical HS definition

- HS1 and HS1A
  - TBC(t)=500+t\*2 t<500
  - TBC(t)=1500-(t-500)\*2 t>500
- HS2 and HS2B adiabatic BC
- HS3 and HS3B adiabatic BC
- Emissivity = 0.1 = EM1

- Surface-Surface radiation pairs

```

HS_RD 3 ! ( n
1 'HS1' LEFT 'HS2' LEFT 0.4 EM1 EM1
2 'HS1' LEFT 'HS3' LEFT 0.5 EM1 EM1
3 'HS2' LEFT 'HS3' LEFT 0.5 EM1 EM1
  
```

Radiation to gas

```

HS_LBR 0.1 Gray-Gas-A 0.5
No accounting for transmission through gas
  
```

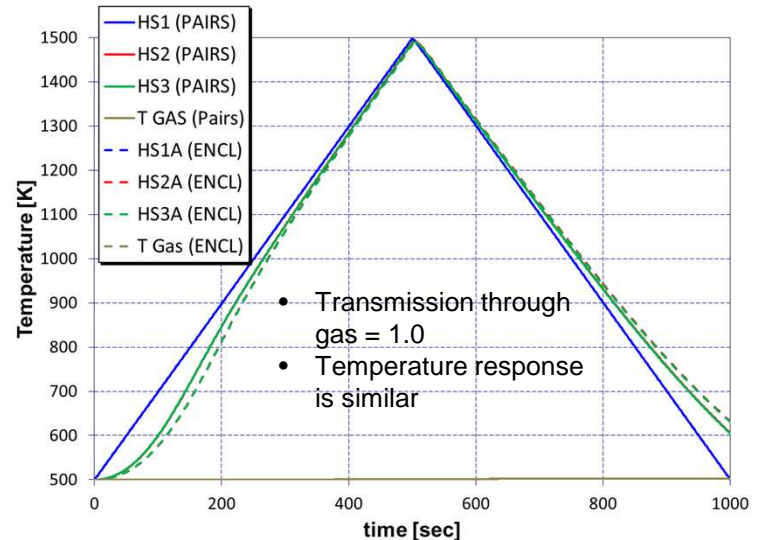
- Enclosure Model

- View factors and beam length
 

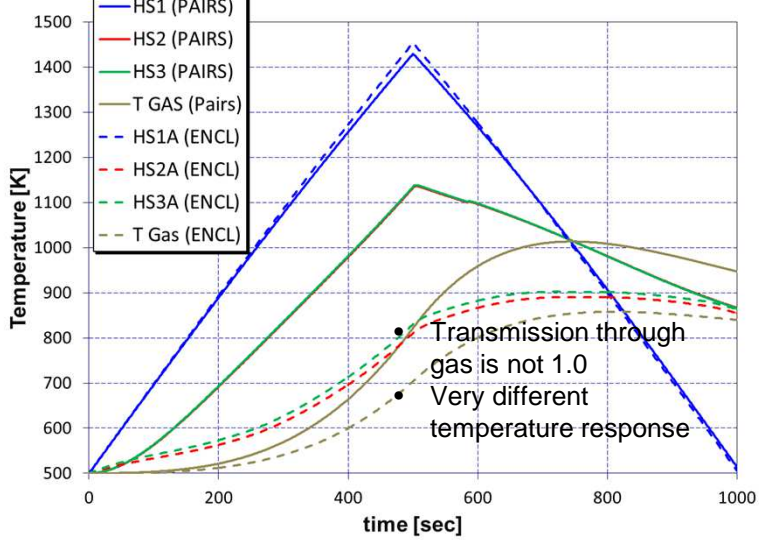
```

HS_RAD 3 NET2 !EM BeamL VF
1 HS1A LEFT EM1 0.5 0.1 0.4 0.5
2 HS2A LEFT EM1 0.5 0.4 0.1 0.5
3 HS3A LEFT EM1 0.5 0.5 0.5 0.0
      
```

Beam Length = 0.0 (no participating gas)



Beam Length = 0.5 m (participating gas)



# Re-suspension Model

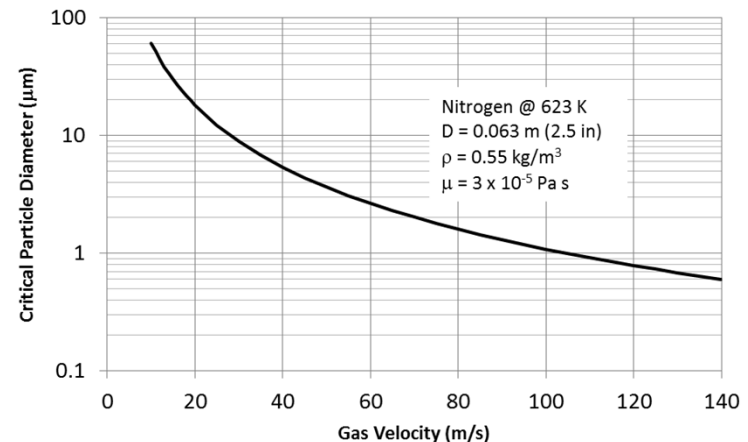
- Deposited material can be re-suspended
  - All sections for which the lower section boundary particle diameter is greater than a critical diameter
  - Critical diameter is calculated from gas flow conditions

$$D_{\text{crit}} = \frac{4 \times 10^{-5}}{\pi \tau_{\text{wall}}} \text{ (m)}, \quad \tau_{\text{wall}} = \frac{f \rho v^2}{2} \text{ (N/m}^2\text{)}$$

Wall shear stress

$$f = \frac{0.0791}{\text{Re}^{0.25}}$$

- Uses CV velocity
- Critical diameter can be specified by user
  - Control function
  - Constant value
- By default, surfaces do not re-suspend
- Wet surfaces cannot re-suspend.
  - Pools and surfaces with condensed water
- Relaxation time for resuspension
- Reference
  - “Liftoff Model for MELCOR,” Mike Young
  - SAND2015-6119
- Validation against Tests
  - STORM tests (SR11 and SR12)
  - Validation against LACE tests



## Examples

To fully activate resuspension, specify a value of `FractResuspend` as 1.0, and let MELCOR determine the critical diameter:

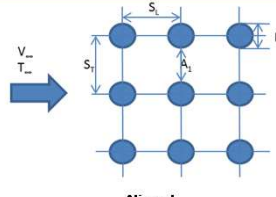
HS\_LBAR 1. ! Left surface  
 HS\_RBAR 1. ! Right surface

# Zukauskas Heat Transfer Coefficient

- Heat transfer for external cross-flow across a tube bundle
  - Aligned or staggered
- Implemented as option for HS boundary condition (HS\_LB & HS\_RB IBCL=2 or ZUKAUSKAS).
- Correction factor  $C_2(N_L)$  can be specified or determined from number of rows
- Option to smooth at discontinuities

$$Nu_D = C_2(N_L) C Re_{D,max}^m Pr^n \left( \frac{Pr}{Pr_s} \right)^{0.25}$$

Aligned:

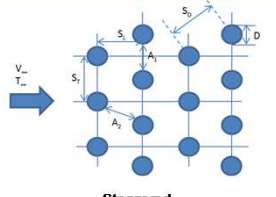
$$V_{max} = \frac{S_T}{S_T - D} V$$


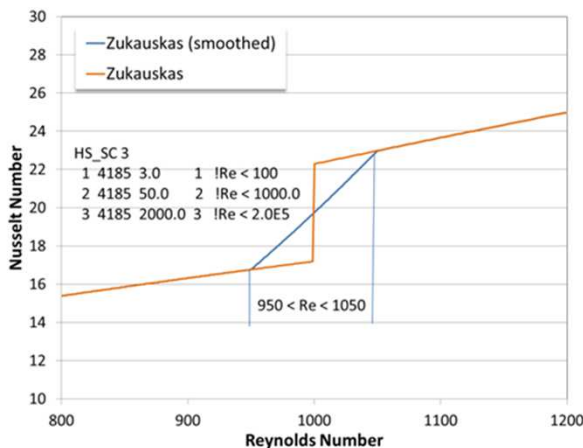
Staggered:

$$if S_D = \left[ S_L^2 + \left( \frac{S_T}{2} \right)^2 \right]^{1/2} < \frac{S_T + D}{2}$$

$$V_{max} = \frac{S_T}{2(S_D - D)} V$$

else

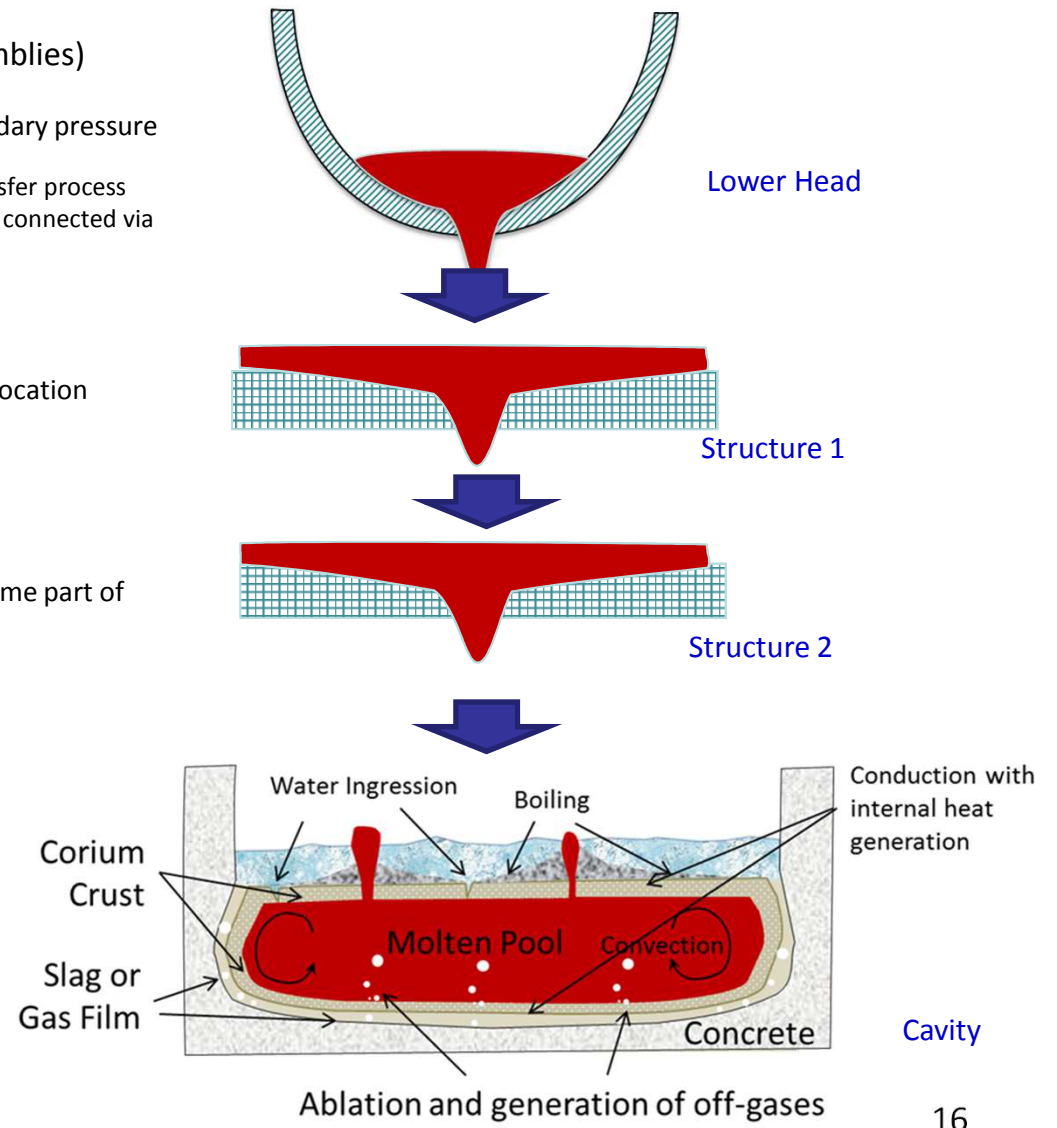
$$V_{max} = \frac{S_T}{S_T - D} V$$




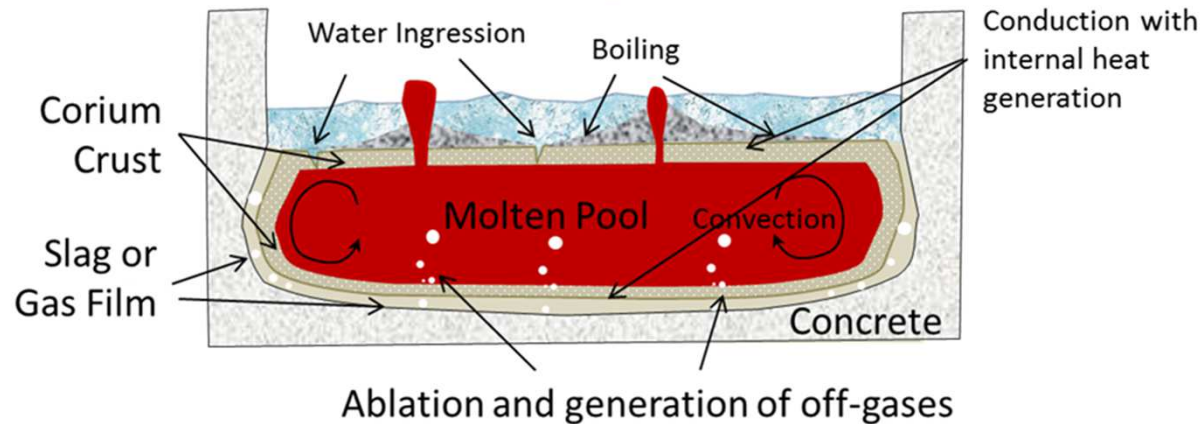
	$Re_{D,max}$	Condition	C	m	n
Aligned	$10 < Re_{D,max} < 100$		0.8	0.4	0.36
	$100 < Re_{D,max} < 1000$	Pr < 10	0.51	0.5	0.37
		Pr > 10	0.51	0.5	0.36
	$1000 < Re_{D,max} \leq 2 \times 10^5$		0.27	0.63	0.36
	$2 \times 10^5 < Re_{D,max} \leq 2 \times 10^6$		0.021	0.84	0.36
Staggered	$10 < Re_{D,max} < 100$		0.9	0.4	0.36
	$100 < Re_{D,max} < 1000$	Pr < 10	0.51	0.5	0.37
		Pr > 10	0.51	0.5	0.36
	$1000 < Re_{D,max} \leq 2 \times 10^5$	$S_T/S_L < 2$	$0.35(S_T/S_L)^{1/5}$	0.6	0.36
		$S_T/S_L > 2$	0.4	0.6	0.36
	$2 \times 10^5 < Re_{D,max} \leq 2 \times 10^6$		0.022	0.84	0.36

# Core Catcher / Ex-Vessel Structure Model

- New model for simulating core catcher assembly (assemblies) outside the lower head.
  - Can also be used to simulate multiple lower heads or secondary pressure vessels
    - Debris relocated from lower head to core catcher via transfer process
    - Allow for multiple core catcher objects (pressure vessels) connected via transfer processes
- 2-D core catcher nodalized through the wall
  - Through-wall and transverse heat conduction
  - CV volumes serve as boundary conditions
  - Available volume between structures can constrain melt relocation
  - Heat transfer between debris and 'upper' (inner) structure
    - Radiation
    - Possible contact
  - Material composition of structure varies through mesh
    - Allows insulation or other non-structural material
  - Allow for vessel structure to melt and molten material become part of molten debris.
    - Simple eutectics
  - Homogeneous molten debris
  - Crust between molten debris and structure
  - Special features (like penetrations) modeled
- Multiple failure criteria
  - Failure by melt-through
  - Failure by control function
  - Secondary Pressure Vessel
    - Larson-Miller Creep
    - Yield Stress
- Work completed in September 2015



# New Modeling for Top-Quenched Debris in Cavity



- Quenching of the upper crust at the top of the corium debris can lead to a considerable density change ( $\sim 18\%$  volume) leading to cracking and formation of voids
  - Water ingression reduces conduction path to molten pool and increases surface area of contact
- Molten corium extruded through crust by entrainment from decomposition gases as they escape through fissures and defects in the crust.
  - Enhance the coolability of the molten corium
    - by relocating enthalpy from the internal melt through the crust
    - more coolable geometry that is more porous and permeable to water



# MELCOR Debris Spreading Model

- By default, corium relocated to the cavity will spread instantaneously
- Users are able to specify a spreading radius through a CF or TF
- Current model development adds an internally calculated spreading radius.
  - Balance between gravitational and viscous forces

## CAV\_SP – Definition of Parametric Debris Spreading Optional

This record may be used to model the spreading of debris in the cavity. Users can define a maximum debris radius as a function of time through a tabular function, control function, channel of an external data file, or an internal model.

### (1) SOURCE

Source of data for maximum debris radius as a function of time

1 or 'TF'

Use data from tabular function.

-1 or 'CF'

Use data from control function.

2 or 'CHANNELEDF',

Use data from channel of external data file NameCF\_TF\_EDF.

0 or 'MODEL',

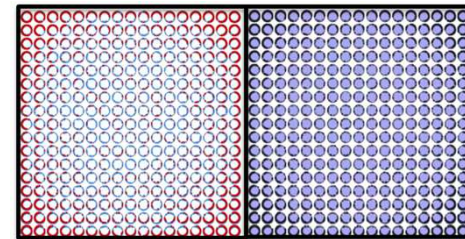
This option allows the code to internally calculate the debris radius as a function of time. However, this option requires the initial debris radius (RADTINI).

If SOURCE = 0, the following record is required:

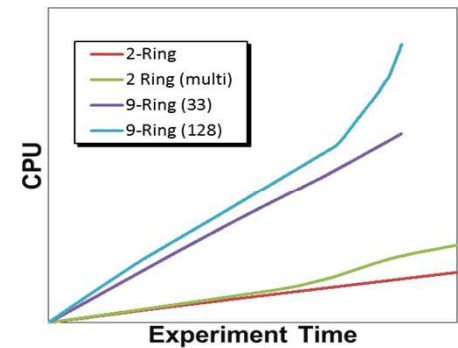
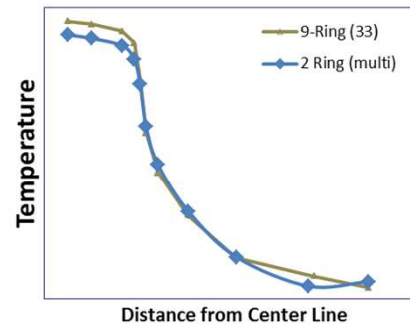
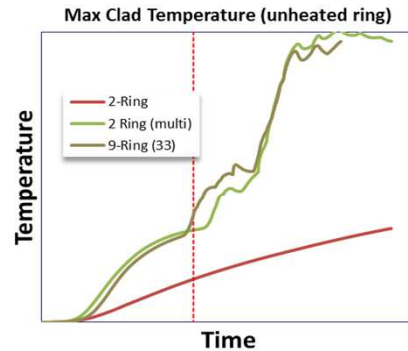
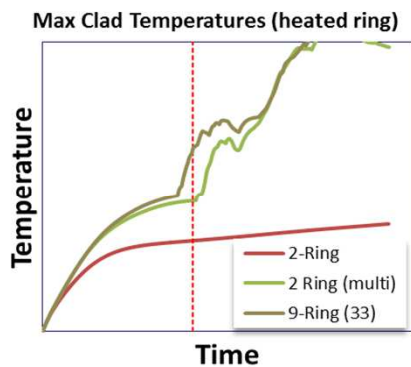
(2) RADTINI - Initial time-dependent debris radius for the internal model

# Multi-Rod Model

- Motivation
  - It is desirable to model an entire assembly within a single MELCOR ring
- Challenge
  - When hot assembly reaches ignition, heat transfer to cold assembly is problematic



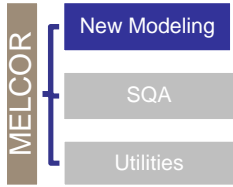
Hot Assembly Cold Assembly



- Validation
  - Validation was performed against the Sandia PWR Spent Fuel Pool Experiments
  - Comparisons between 2-ring (2 rods) model; 2-ring, (9 rods) model; and 9-ring model.
- CPU time is greatly reduced for multi-rod model
- Simplified input requirements
- Fuel rod degradation modeling has not been completed

# DOE Models: CONTAIN/LMR Models for

- Phase 1 – Implement sodium as replacement to the working fluid for a MELCOR calculation
  - Implement properties & Equations Of State (EOS) from the fusion safety database
  - Implement properties & EOS based on SIMMER-III
- Phase 2 – Review of CONTAIN/LMR and preparation of design documents
  - Detailed examination of LMR models with regards to implementation into MELCOR architecture
  - Implementation of CONTAIN/LMR models into CONTAIN2
- Phase 3 – Implementation and Validation of:
  - Implementation of CONTAIN/LMR models into CONTAIN2
  - Sodium spray fires (ongoing)
  - Upper cell chemistry (ongoing)
  - Sodium pool chemistry (ongoing)
- Phase 4 – Implementation and Validation of:
  - Condensation of sodium
  - Sodium pool fire models
  - Debris bed/concrete cavity interactions.



# Extensions to the CF Package (September 2016)



- Constant CF Argument
- Vectorized CF arguments
- Ranges
- Vector Control Functions
- Analytic Control Functions



# Constant CF Argument (September 2016)

- In the past, MELCOR had no specific way of identifying a constant control function argument. For example, the constant pi would be referenced as follows:
  - 1 EXEC-TIME 0.00 3.1415
- This was always confusing to new users and requires careful reading to know for sure that the argument is truly a constant or a function of the execution time. A new CF argument can be used to identify this constant value
  - 1 CF-CONST 3.1415

# Vectorized CF Arguments (September 2016)

- Traditionally, MELCOR recognizes scalar control function arguments that can be used as parameters in evaluating the control function. For example, the masses in several control volumes can be summed by including an **itemized list of each control volume**.
- The user can now specify a **vectorized control function argument** that can be recognized by control functions (such as the the 'ADD' control function type) which can greatly reduce the number of arguments required by the control function

```
CF_ID    'CVMass' 1010ADD
CF_ARG 1
1  CVH-MASS('CORE',POOL)    1.0  0.0
2  CVH-MASS('BYPASS',POOL)  1.0  0.0
3  CVH-MASS('LP',POOL)      1.0  0.0
4  CVH-MASS('UP+UH',POOL)   1.0  0.0
5  CVH-MASS('DC',POOL)      1.0  0.0
```

```
CF_ID    'CVMass2' 1010 ADD
CF_ARG 1
1  CVH-MASS(#CVRANGE(1),POOL)  1.0  0.0
```

# Control Function Ranges (September 2016)

- The range is an object that is defined once in the database and then can be referenced by other control function arguments. The range specifies an ordered list of objects such as control volumes, COR cells, materials, or components
- The **hashtag** that precedes the volume specification in the CF argument indicates a range of control volumes rather than a single volume.

## Define a Range:

```

name      type      ndim  Number
CF_RANGE  CVRANGE  CVOLUMES  1    30
CONSTRUCT 2
  1 CVTYPE='PRIMARY'
  2 DC
REMOVE 1
  1 LowerPlenum

```

## Reference that Range:

```

CF_ID      'CVMass2' 1010 ADD
CF_SAI 1.0 0.00
CFVALR (INITIAL VALUE)
CF_ARG 1
  1 CVH-MASS(#CVRANGE(1),POOL) 1.0
  0.0

```

Examples of Keywords that can be used in defining ranges:

Range Type	Keywords
<b>CVRANGE</b>	'ALL' CVTYPE=, BYPASS, CHANNEL
<b>CORCELLS</b>	'ALL' 'LP' 'UC' 'RING1' 'ELEV5'
<b>Others</b>	

# Vector Control Functions (September 2016)

- Control functions can now return a vector of values.

```
CF_VF 5
```

The field on this record indicates that the function returns a vector with 5 elements.

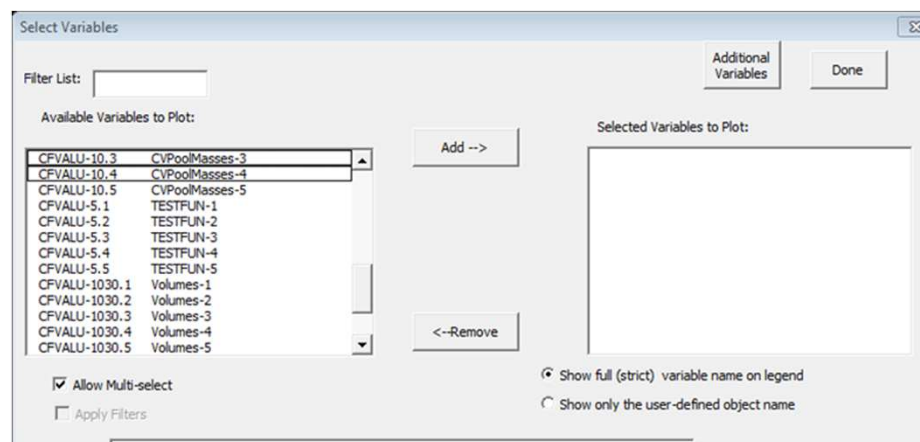
- If the control function is performing a vector calculation on several vector arguments, each with identical length, then by context, the vector length could be interpreted as the length of the arguments and the user can provide a wildcard to identify the assumed length of the vector:

```
CF_ID      'Volumes'      1030      ADD
CF_VF *
CF_ARG 2
  1  CVH-VOLLIQ('#CVVOLUMES(1)')      1.0      0.00
  2  CVH-VOLVAP('#CVVOLUMES(1)')      1.0      0.00
```

- If the user would like to reference a particular element from the vector results (e.g., the 4<sup>th</sup> element of the vector function 'TESTFUN'), that reference is made as follows:

```
CF_ID      'OXIDE-FR71'    71      EQUALS
CF_ARG 1
  1 CF-VALU('TESTFUN')[4] 1.0 0.0
```

- Elements of a vector CF can be referenced from plotting routines like PTFREAD





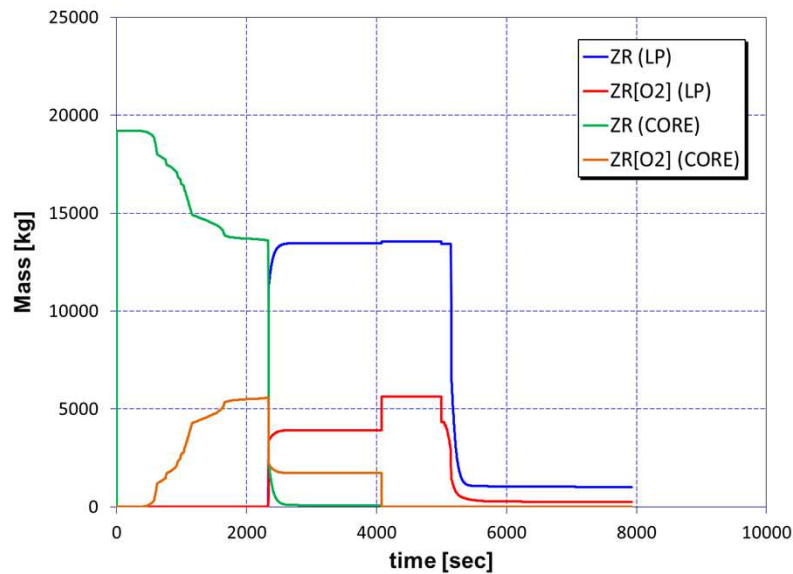
# Analytic Functions

- Rather than passing a fixed number of arrays through an argument list to the analytical function, a new user defined type called tUDFArguments was added to contain all arguments (real arrays, integer arrays, real values, etc.) This data structure contains information regarding the total number of arguments, the dimension of each argument, a text description of each argument, and the range over which each argument may be defined (cell numbers, CVnames, etc.). This information may be useful to the user in debugging the dll.

UDFArguments	{...}
UDFArguments%NARGS	2
UDFArguments%ARGUMENTS	{...}
UDFArguments%ARGUMENTS(1)	{...}
UDFArguments%ARGUMENTS(2)	{...}
UDFArguments%ARGUMENTS(2)%KIND	2
UDFArguments%ARGUMENTS(2)%NDIM	0
UDFArguments%ARGUMENTS(2)%INTARRAY	Undefined pointer/array
UDFArguments%ARGUMENTS(2)%REALSCALAR	0.0000000000000000D+000
UDFArguments%ARGUMENTS(2)%REALARRAY	{...}
UDFArguments%ARGUMENTS(2)%REALARRAY(1)	11423.2178468055
UDFArguments%ARGUMENTS(2)%REALARRAY(2)	174.333207580820
UDFArguments%ARGUMENTS(2)%REALARRAY(3)	11329.6978079948
UDFArguments%ARGUMENTS(2)%REALARRAY(4)	3611.48073217145
UDFArguments%ARGUMENTS(2)%REALARRAY(5)	16817.0733501201
UDFArguments%ARGUMENTS(2)%DESCRIPTION	'CVH-MASS '
UDFArguments%ARGUMENTS(2)%ELEMENT	{...}
UDFArguments%ARGUMENTS(2)%ELEMENT(1)	'DC160 '
UDFArguments%ARGUMENTS(2)%ELEMENT(2)	'UP+UH150 '
UDFArguments%ARGUMENTS(2)%ELEMENT(3)	'CORE110 '
UDFArguments%ARGUMENTS(2)%ELEMENT(4)	'BYPASS111 '
UDFArguments%ARGUMENTS(2)%ELEMENT(5)	'LP120 '

# Application: Plotting summation of variable over a region (September 2016)

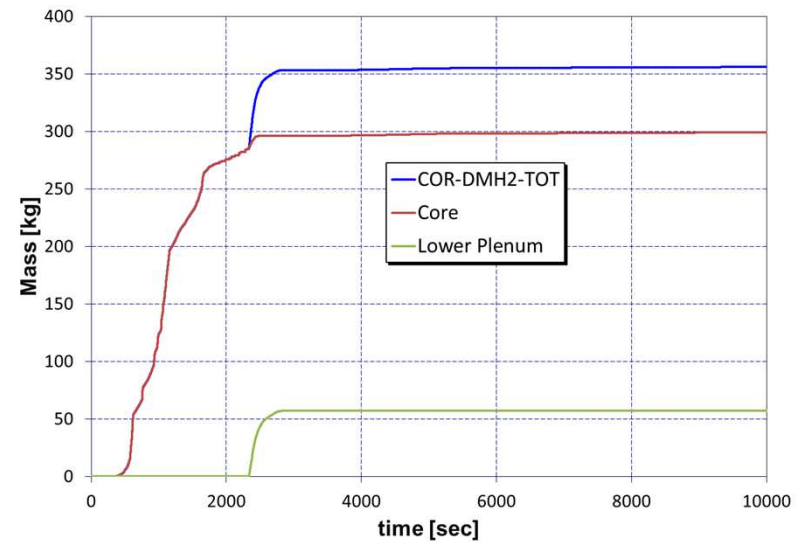
## Zr/ZrO2 Mass in Lower Plenum



```
CF_RANGE L_PLEN CELLS 2 12
CONSTRUCT 1 ADD
  1 LP
```

```
CF_ID 'ZRO2_LP' 302 ADD
CF_SAI 1.0 0.0 0.0
CF_ARG 1
  1 COR-CELLMASS(# L_PLEN (1),# L_PLEN(2) ,ZR[O2]) 1.0 0.0
```

## H2 Mass generated in Lower Plenum



```
CF_ID 'H2_LP' 305 ADD
CF_SAI 1.0 0.0 0.0
CF_ARG 11
  1 COR-H2(#LOWERPLEN(1),#LOWERPLEN(2),'CL') 1.0 0.0
  2 COR-H2(#LOWERPLEN(1),#LOWERPLEN(2),'SH') 1.0 0.0
  3 COR-H2(#LOWERPLEN(1),#LOWERPLEN(2),'NS') 1.0 0.0
  4 COR-H2(#LOWERPLEN(1),#LOWERPLEN(2),'SS') 1.0 0.0
  5 COR-H2(#LOWERPLEN(1),#LOWERPLEN(2),'FM') 1.0 0.0
  6 COR-H2(#LOWERPLEN(1),#LOWERPLEN(2),'PD') 1.0 0.0
  7 COR-H2(#LOWERPLEN(1),#LOWERPLEN(2),'PB') 1.0 0.0
```

# Miscellaneous New Models: COR\_HTR extended to HS

- This feature has been extended to allow specification of a heat transfer path from a COR component to a heat structure. The heat transfer path must be defined 'From' a valid COR component and the heat structure must not have a user specified boundary condition (i.e., IBCL = 0,20,30,80, or 90). Furthermore, if a radiation path is defined, the emissivity must be defined by the user on the appropriate HS Boundary Surface Radiation Data record (HS\_LBR or HS\_RBR).

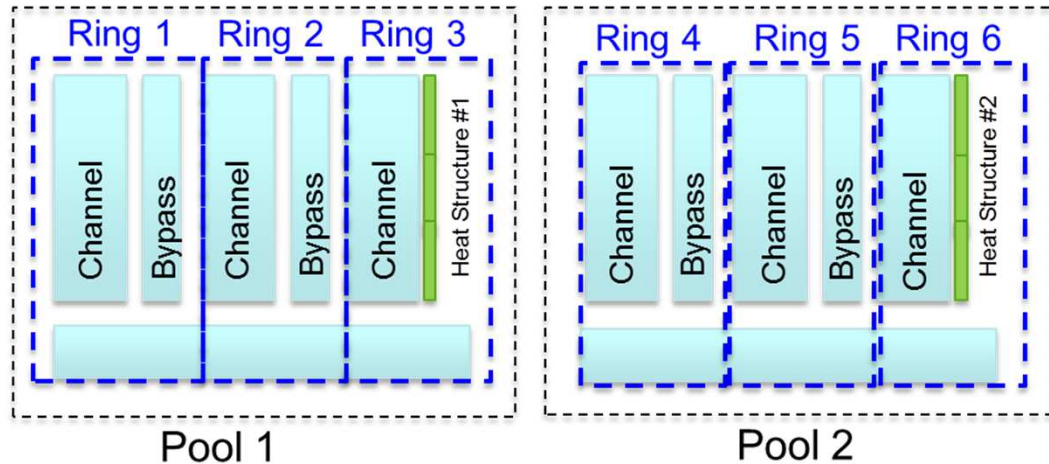
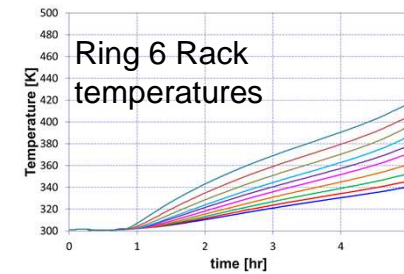
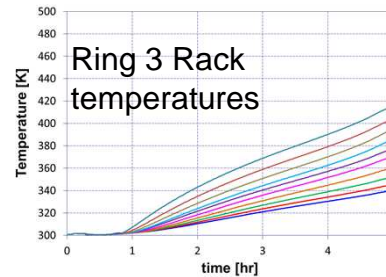
### Example

```

COR_HTR 2 !From: IA IR IC To: IA IR IC FLAG      COEFF
      1 2 4 SS   3 3   SH  CONDUCT-CONST 0.0818
      2 2 4 SS  HS# LEFT HS  CONDUCT-CONST 0.0818
  
```

# COR\_HTR extended to HS (Application)

- Two connected spent fuel pools
- Rods near boundary radiate to concrete wall.
- Modification enables heat transfer to heat structures other than boundary heat structures
- Pool 1 & 2 Rack (and HS) temperatures are equivalent.



## Caveats

- Emissivity of boundary HS can be specified by user for SFP reactor types
  - HS\_LBR record
  - A value of 0.9999 is assumed for boundary heat structures for all other reactor types
- Input is required to connect the HS surface to the COR cell
  - HS\_LBF record
  - Otherwise DTDZ model will not use the structure for calculating local TSVC

# Miscellaneous New Models: Valve Flow Coefficient

## ■ Description

- Valve flow coefficients are typically used in characterizing flow properties of valves.
- By definition, a valve has a  $C_v$  of 1 when a pressure of 1 psi causes a flow of 1 US gallon per minute of water at 60° F (i.e. SG = 1) through the valve.
- Since the pressure drop through a valve is proportional to the square of the flow rate:

$$C_v = Q * \sqrt{\frac{SG}{\Delta P}}$$

- Q=Flow in gpm
- $C_v$  = Valve flow coefficient
- DP = Difference in pressure (psi)
- SG = specific gravity of liquid relative to water at 60 F

## ■ Implementation

- The user indicates that the valve is a 'NoTRIPCV' and then supplies a CF for specifying the value of  $C_v$  for the valve
- The valve must be on a single segment flowpath and takes the pipe diameter from this segment
- Standard engineering units for flow coefficient are gpm/sqrt(psi) are expected.

fl\_vlv 1

1 'TestValve' 'VALVE' NoTRIPCV 'CVvsTime'

# Miscellaneous New Models: Lag Control Function

- The lag function type (designated by the short name LAG) is a basic control theory function for which a function that is passed as an argument,  $a_1(t)$ , is transformed through the following integral equation.

$$f(t) = \int \left( \frac{c_2 \cdot a_1(t) - f(t)}{c_1} \right) dt$$

- Where  $c_1$  is the lag time (seconds) and  $c_2$  is a scaling factor. In differential form, this integral is advanced using the following transform equation.

$$f^{n+1} = \frac{f^n \left( 1 - \frac{dt}{2c_1} \right) + c_2 (a_1^n + a_1^{n+1}) \frac{dt}{2c_1}}{1 + \frac{dt}{2c_1}}$$

- May improve numerical uncertainty

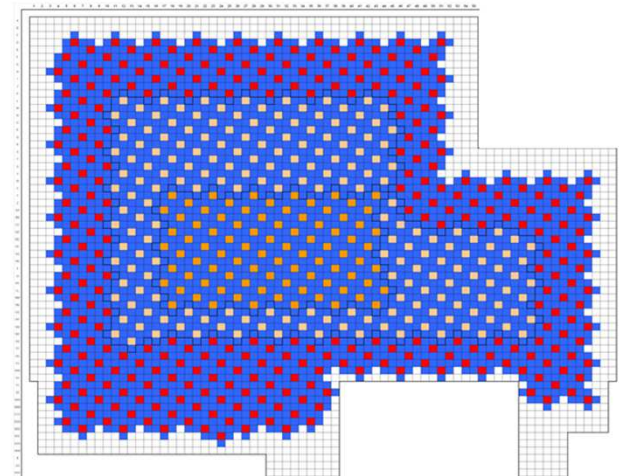
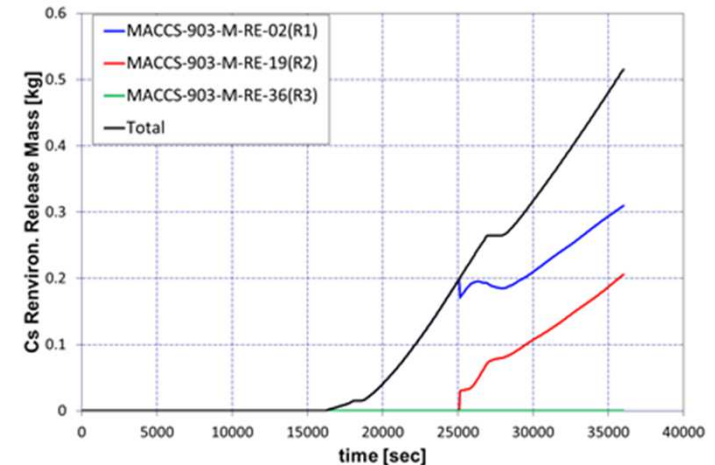
# Miscellaneous New/Improved Models: MACCS Flow Path Types

- Origin of MACCS FP Model
  - Flow paths designated to be used in tracking advection of RadioNuclides
  - Originally intended to track airborne release to atmosphere
    - Did not track RNs in Pool that are transported through FP
    - Did not track RNs trapped in filters associated with FP
    - Did not track RNs that are removed through pool scrubbing
- MACCS FP can also be used for calculating mass conservation of RNs between CVs or in calculating DFs
  - Need to include RNs advected with pool, RNs trapped in filters, and RNs removed through pool scrubbing to obtain total inventory transported from a CV.
  - MACCS FP can be designated as a DF type on field 6 of the FL\_MACCS record.

```
FL_MACCS    2 !NFL  MACCSnam    MACCSn  MCCSFP        DIRFL    DF or MACCS
              1      Leakage      110    FlowPath190   FROM      DF
```

# Miscellaneous New Models: MACCS Multi-ring release

- Motivation
  - Burnup and therefore activity for distinct rings may be vastly different. Recently, MACCS has been modified to allow it to distinguish masses provided by MELCOR by batch (ring). MACCS then will associate different activities for a class, dependent on the ring of origination
  - The problem is that once RN mass is released, it can no longer be distinguished by originating ring.
- New variable for approximating mass release by offload batch (ring)
  - Not really a new model
  - Creation of a plot variable in the binary plot file
  - This is an approximation in obtaining a plot variable
- Previously implemented by KC Wagner through use of control functions.
  - Control function description can be quite lengthy even for a two-ring model





# Temporal Relaxation of the “Rate-of-Change”

## ■ Introduction

- Many physical processes in MELCOR are modeled by correlation based relationships developed from steady-state experiments. These models do not represent the time it takes for these processes to respond if conditions change. As a result, temporal “rate-of-change” aspects of MELCOR simulations are not expected to be highly accurate and numerical instabilities can be magnified when sudden changes occur.
- Temporal relaxation is a simple way to introduce a user-imposed time-scale based model that limits how quickly processes being modeled can change in time. Note that “steady-state” values are not changed, only the temporal rate-of change.

## ■ Fundamental Equation

- $f^{n+1} = \omega f^* + (1 - \omega) f^n$

Where

$$\omega = \min[1.0, dt/\tau_{rel}]$$

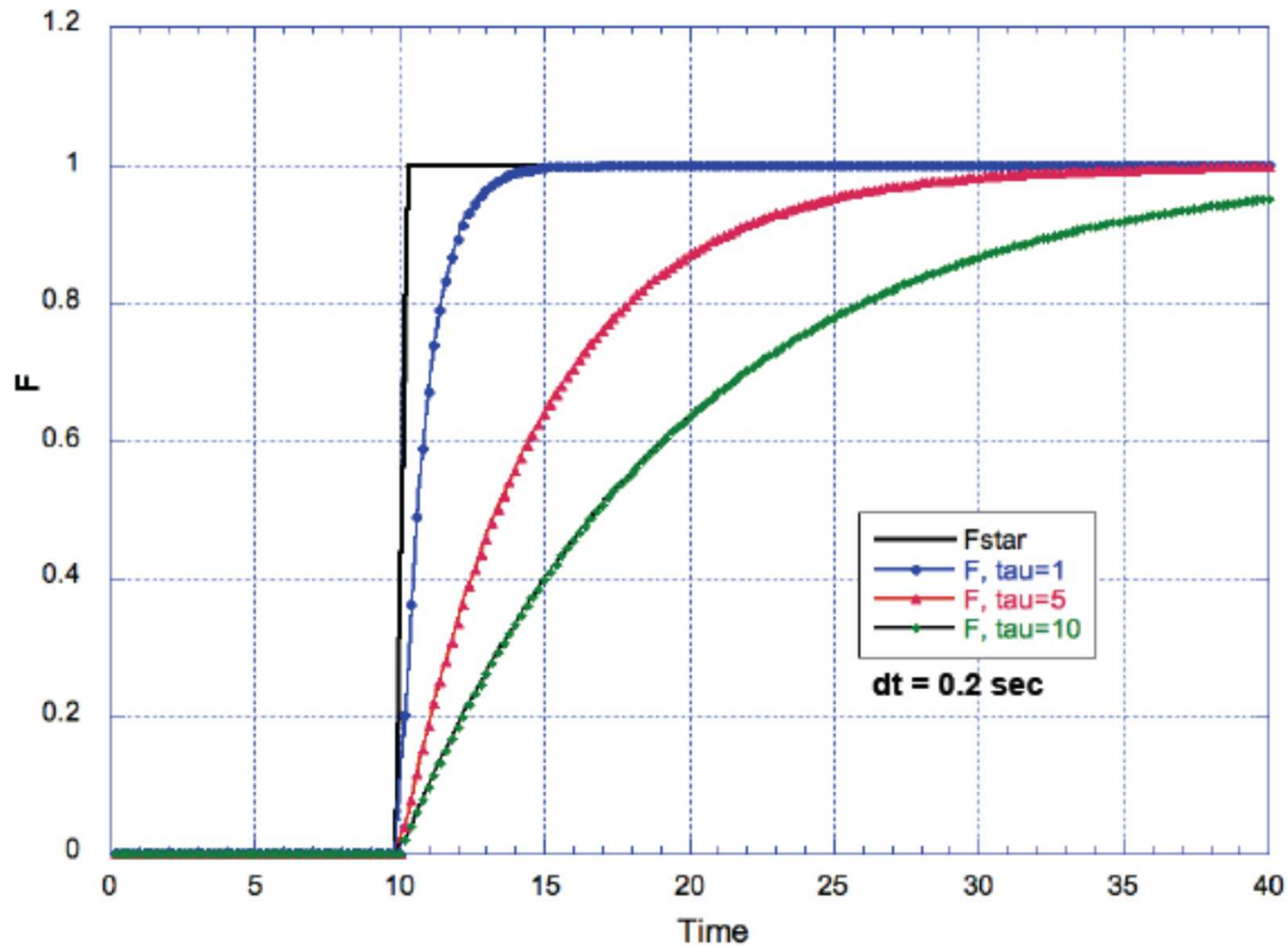
$f^{n+1}$  = value of  $f$  at time step  $n + 1$

$f^n$  = relaxed value of  $f$  at time step  $n$

$f^*$  = unrelaxed value of  $f$  at time step  $n + 1$

$\tau_{rel}$  = temporal relaxation time scale

# Example plot for different temporal relaxation time-scales



# Setting the Time-Scale for Temporal RELaxation (TSTREL)

- There are two ways to set the values for TSTREL:

- Specify using EXEC\_AUTOTS card

```
EXEC_AUTOTS 1 2.0 1.0
```

!Automatic calculation of TSTREL as  $\text{MAX}(2.0 * \text{DTMAX}, 1.0)$

- Set values in the EXEC\_TIME table

EXEC_TIME 2 !	INDEX	TIME	DTMAX	DTMIN	DTEDT	DTPLT	DTRST	DCRST	TSTREL
	1	0.00	0.10	1.0E-04	50.0	1.0	200.0	1.0E+10	1.0
	2	100.	0.20	1.0E-04	50.0	1.0	200.0	1.0E+10	0.5

- The default value of TSTREL is 1.e-9 sec., which yields no relaxation.

# Synopsis of Temporal Relaxation applied to different physical models

$$f^{n+1} = \omega f^* + (1 - \omega) f^n$$

- Heat Transfer: How quickly the heat/mass transfer rates can increase

$$f = \text{heat transfer rate (J/m}^2\text{s)}$$

- Oxidation: How quickly the chemical reaction rate can increase

$$f = \text{chemical reaction rate (kg/s)}$$

- Quench Velocity: How quickly the quench velocity value can change

$$f = \text{quench front velocity } \left(\frac{m}{s}\right)$$

- Valve Opening: How quickly the “fraction open” value in flow paths can change.

$$f = \text{quench front velocity } (-)$$

# New HS Plot Variables (Non-dimensional variables)

New Control Function	Description
HS-RE-POOL(NameHS, Sn)	Reynolds number for pool at boundary Sn surface of heat structure NameHS.
HS-RE-ATM(NameHS, Sn)	Reynolds number for atmosphere at boundary Sn surface of heat structure NameHS.
HS-PR-POOL(NameHS, Sn)	Prandtl number for pool at boundary Sn surface of heat structure NameHS.
HS-PR-ATM(NameHS, Sn)	Prandtl number for atmosphere at boundary Sn surface of heat structure NameHS.
HS-PRS-POOL(NameHS, Sn)	Wall Prandtl number for pool at boundary Sn surface of heat structure NameHS.
HS-PRS-ATM(NameHS, Sn)	Wall Prandtl number for atmosphere at boundary Sn surface of heat structure NameHS.
HS-NU-POOL(NameHS, Sn)	Nusselt number for pool at boundary Sn surface of heat structure NameHS.
HS-NU-ATM(NameHS, Sn)	Nusselt number for atmosphere at boundary Sn surface of heat structure NameHS.

# New HS Plot Variables (Energy terms)

New Control Function	Description
HS-Q-ATMS(NameHS, Sn, TYPE*)	Heat transfer to atmosphere at boundary Sn surface of heat structure NameHS from all modes of heat transfer.
HS-Q-POOL(NameHS, Sn, TYPE*)	Heat transfer to pool at boundary Sn surface of heat structure NameHS from all modes of heat transfer.
HS-Q-DECAY(NameHS, Sn, TYPE*)	Heat transfer to boundary Sn surface of heat structure NameHS from decay heat associated with radionuclides deposited on the surface.
HS-Q-BCFIX (NameHS, Sn, TYPE*)	Heat transfer to boundary Sn surface of heat structure NameHS to accommodate fixed temperature boundary condition.
HS-Q-RAD (NameHS, Sn, TYPE*)	Radiation heat transfer to boundary Sn surface of heat structure NameHS.
HS-Q-RADG (NameEncl,TYPE*)	Radiation heat transfer to intermediate gas in control volume associated with the enclosure NameEncl.
HS-Q-TOTAL (NameHS, Sn, TYPE*)	Total heat transfer at boundary Sn surface of heat structure NameHS from all modes of heat transfer.

\*TYPE indicates whether the value returned is a heat flux, heat rate, or cumulative (integral) heat

- TYPE = 'FLUX'      heat flux (W/m<sup>2</sup>),
- TYPE='RATE'      heat rate (W)
- TYPE='INT'        integral heat transfer (J)

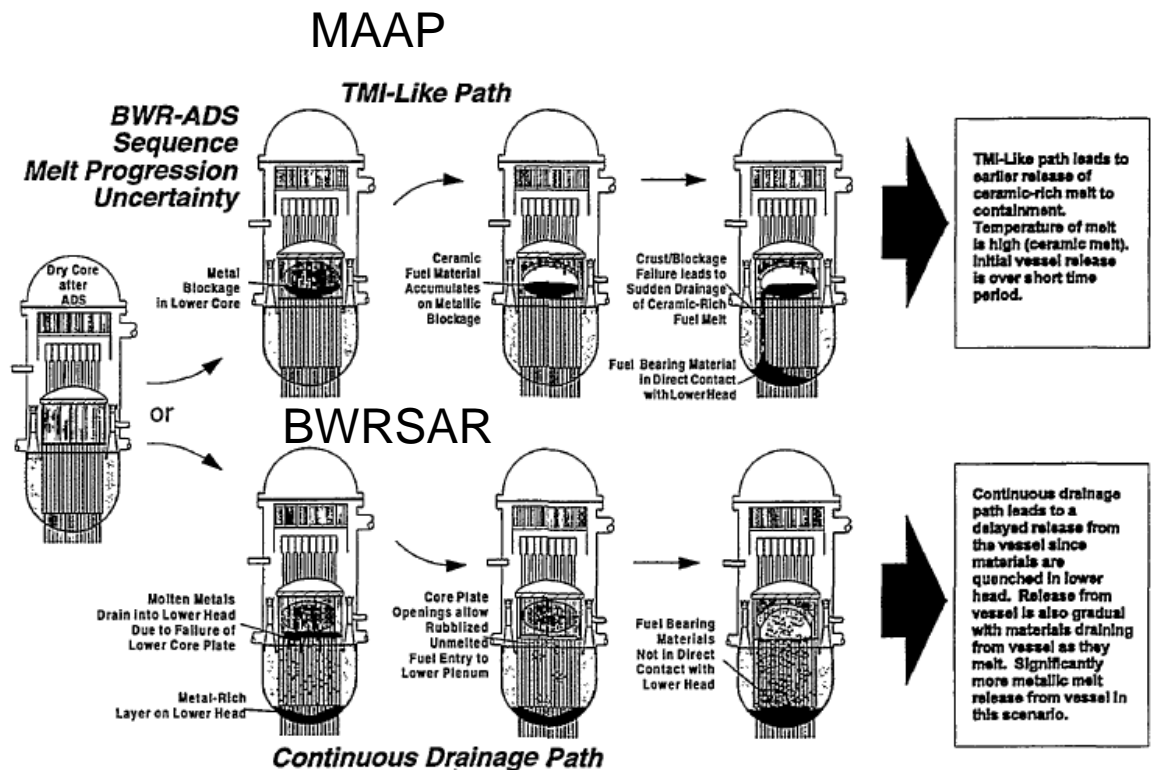
# NRC/DOE MELCOR-MAAP-ASTEC Crosswalk Post-Fukushima Cooperation with EPRI/IRSN

- MAAP code is very TMI-centric

- Core-wide blockage
- Less hydrogen
- Large melt mass

- MELCOR not biased towards TMI-2

- Blockage determined by conditions
- More hydrogen
- Often partly molten fuel slumping



**Final Results of the  
XR2-1 BWR Metallic Melt  
Relocation Experiment**  
Manuscript Completed: April 1997  
Date Published: August 1997

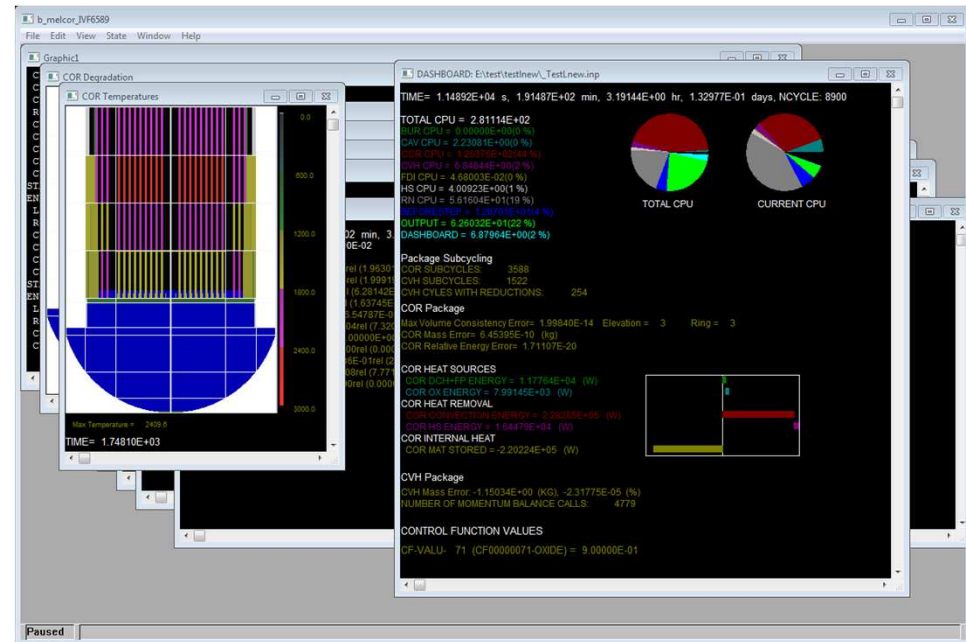
NUREG/CR-6527  
SAND97-1039  
Prepared by  
R. O. Gannit, SNL  
L. L. Humphries, SAIC

# MELCOR Dashboard

```

E:\test\testnew\b_melcor_IVF6587.exe
Records of Restart File: DEMON.v2-0_RST
NCYCLE= 0 TIME= 0.00000E+00
RESTART REQUESTED FROM LAST AVAILABLE CYCLE
Restart requested from NCYCLE= -1 Read from NCYCLE= 0
RESTART REQUESTED FROM LAST AVAILABLE CYCLE
START: CREATING HTML OUTPUT FILE...
END: CREATING HTML OUTPUT FILE 1.14 <SEC>
Listing written TIME= 0.00000E+00 CYCLE= 0
/SMESSAGE/ TIME= 0.00000E+00 CYCLE= 0
CAU0001 - MESSAGE FROM CAVITY PACKAGE
CAVITY CAVITY GOING TO SLEEP
CYCLE= 0 T= 0.000000E+00 DI<MAX>= 1.000000E+00 CPU= 0.000000E+00
CYCLE= 100 T= 9.960397E+01 DI<MAX>= 1.000000E+00 CPU= 2.839218E+00
CYCLE= 200 T= 1.996040E+02 DI<MAX>= 1.000000E+00 CPU= 4.446028E+00
Restart written TIME = 2.006040E+02 CYCLE= 201
CYCLE= 300 T= 2.996040E+02 DI<MAX>= 1.000000E+00 CPU= 6.084039E+00
CYCLE= 400 T= 3.996040E+02 DI<MAX>= 1.000000E+00 CPU= 7.612849E+00
START: CREATING HTML OUTPUT FILE...
END: CREATING HTML OUTPUT FILE 0.90 <SEC>
Listing written TIME = 4.006040E+02 CYCLE= 401
Restart written TIME = 4.006040E+02 CYCLE= 401
keyboard input sensed - enter RETURN and then complete message with second RETU
RN
  
```

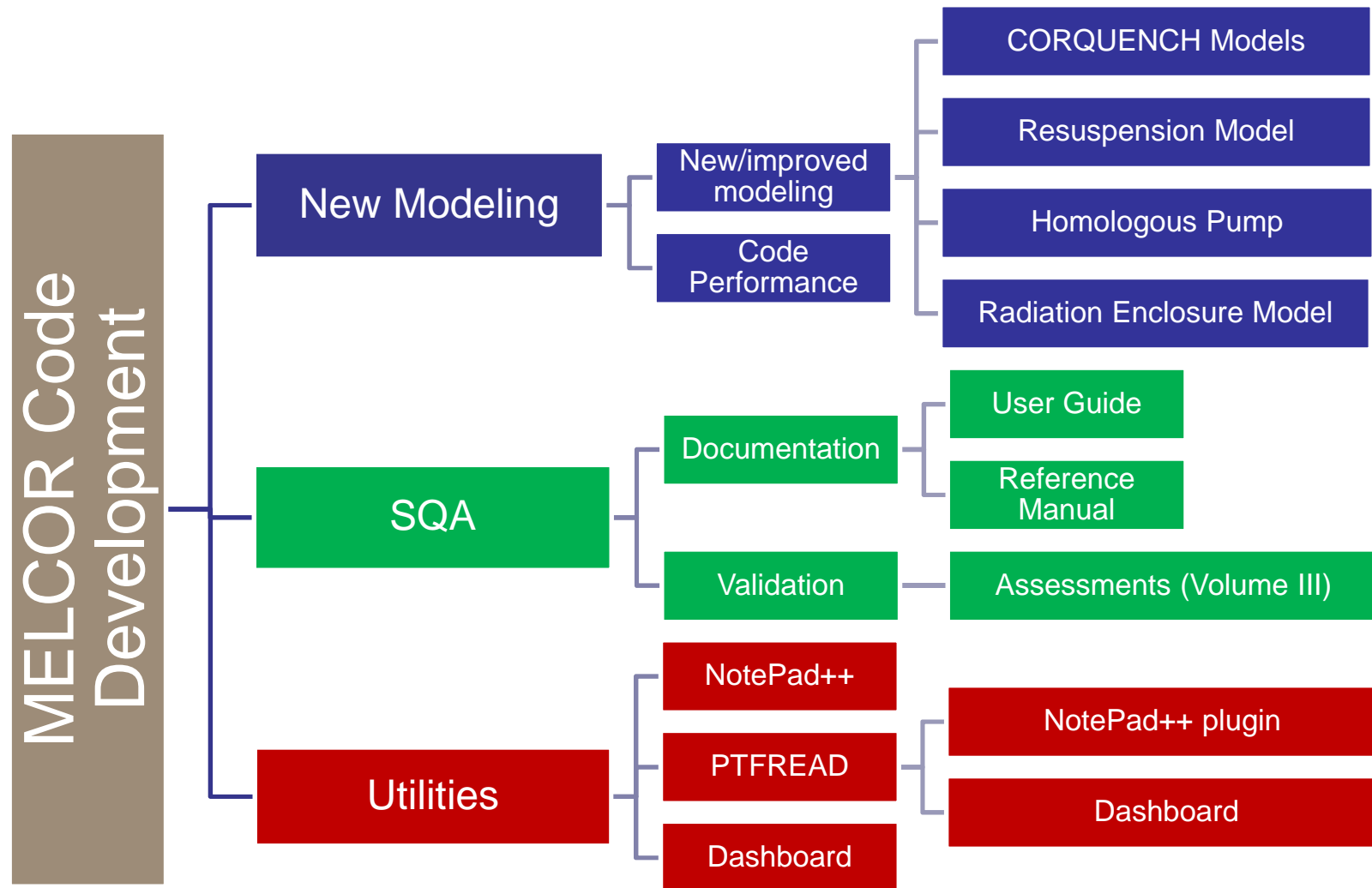
Console Application



QuickWin Application

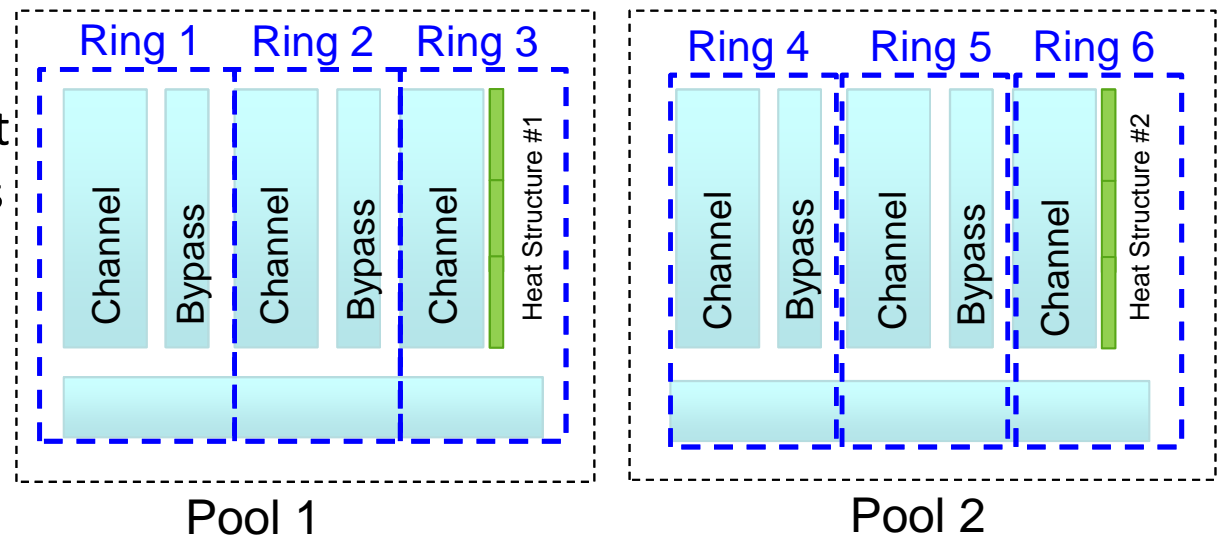


# Questions?



# COR\_HTR extended to HS (Application)

- Two connected spent fuel pools
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## Caveats

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