



Estia

focusing reflectometer

lay-out

beam extraction

shielding and

optics

ESS workshop on neutron optics and shielding

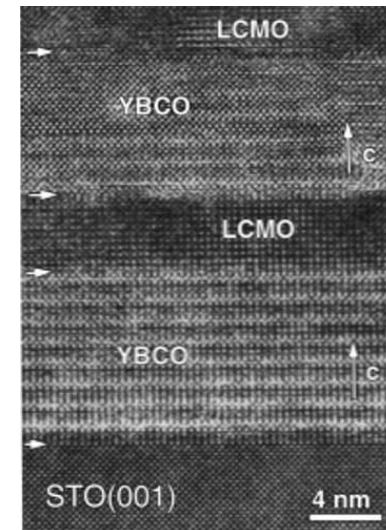
03., 04. 09. 2014, Lund, Sweden

Estia

focusing reflectometer

main science case:

determination of structural and magnetic
depth-profiles near the surface



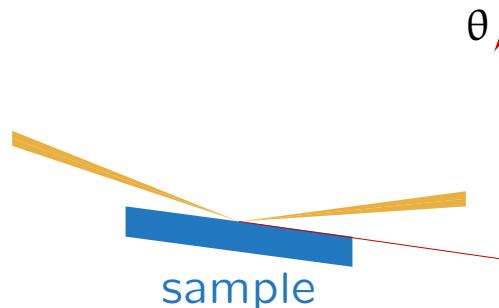
typical samples:

thin coatings on $1 \times 1 \text{ mm}^2$ to $10 \times 50 \text{ mm}^2$ substrates



geometry:

angle of incidence $\theta = 0.1^\circ \dots 20^\circ$
 \Rightarrow sample height = $2 \mu\text{m} \dots 10 \text{ mm}$



Selene guide

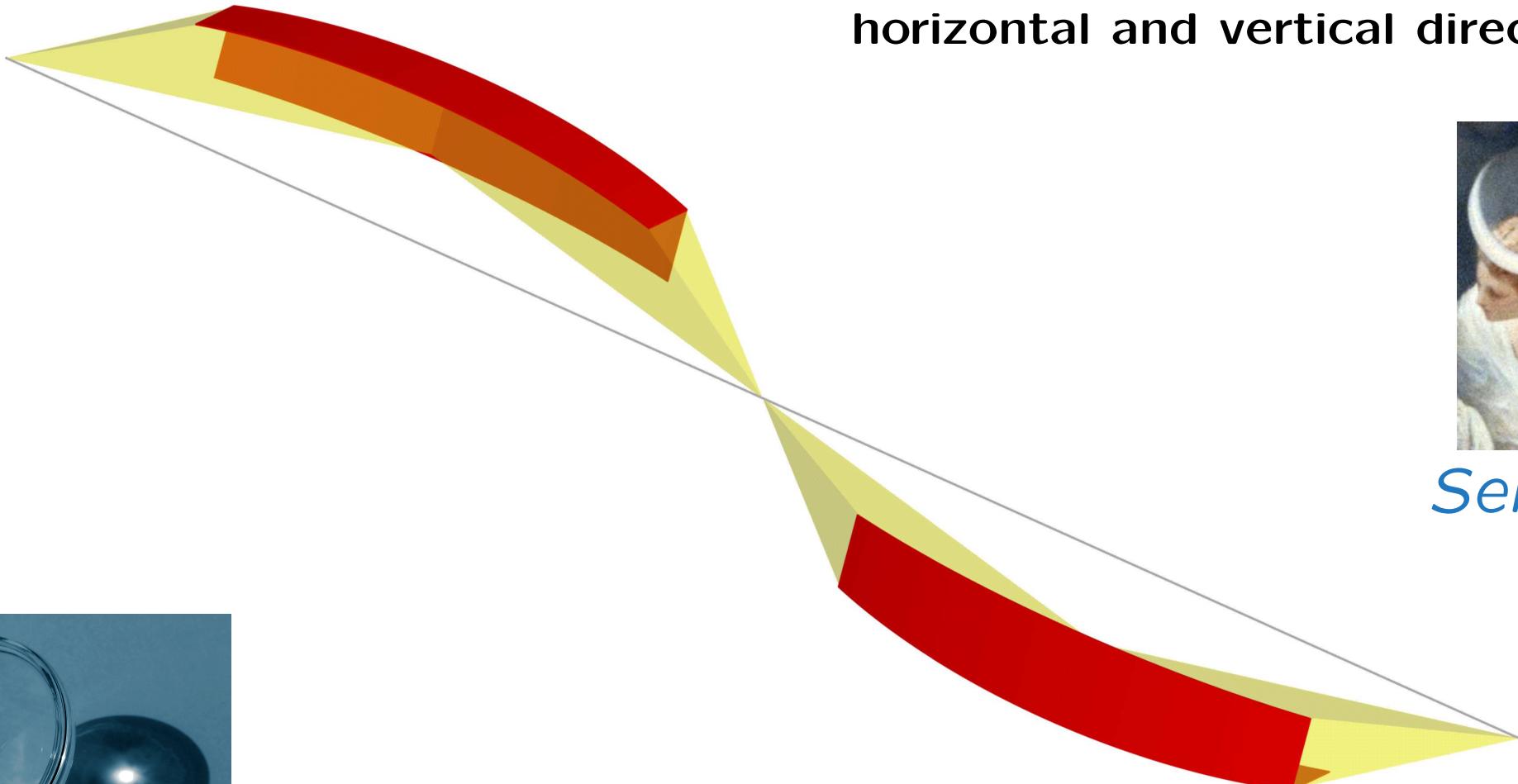
point-to-point focusing

with

2 subsequent elliptical reflectors

for

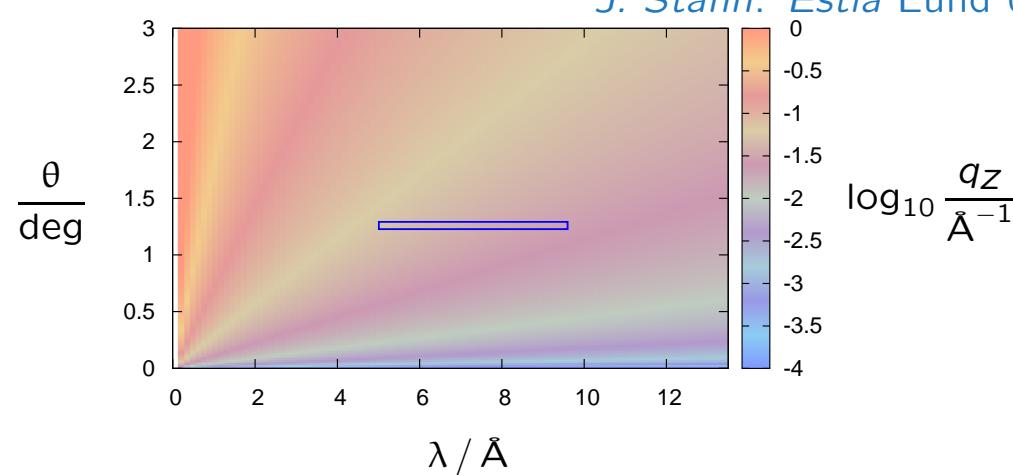
horizontal and vertical direction



Selene



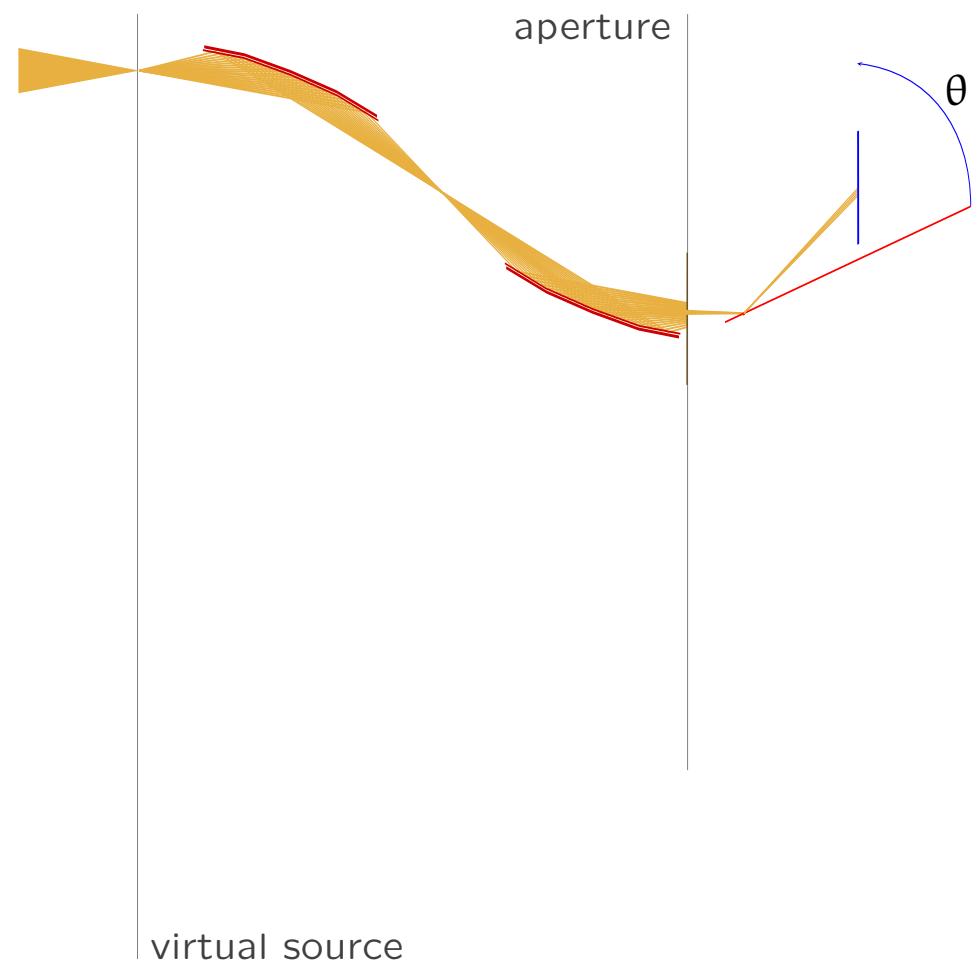
operation modes



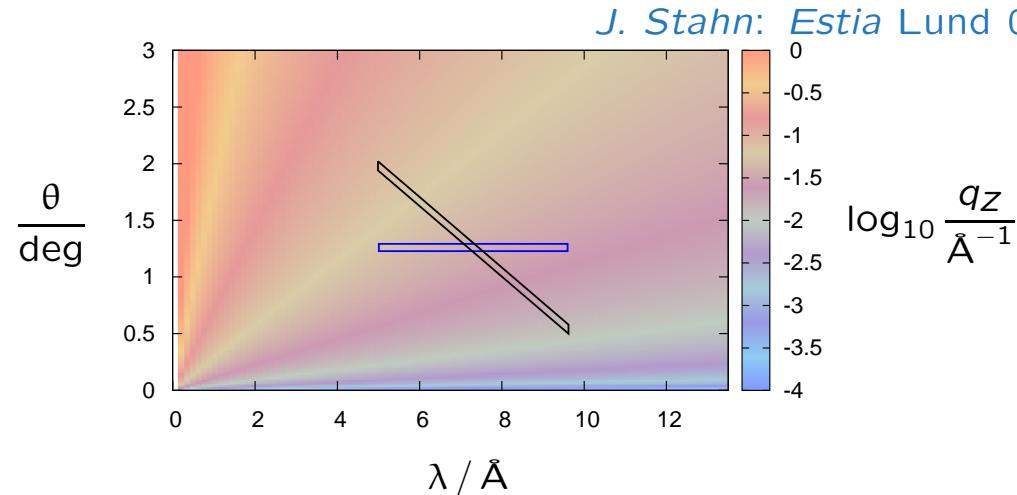
almost conventional reflectivity

= TOF

- defined foot-print
- off-specular reflectivity



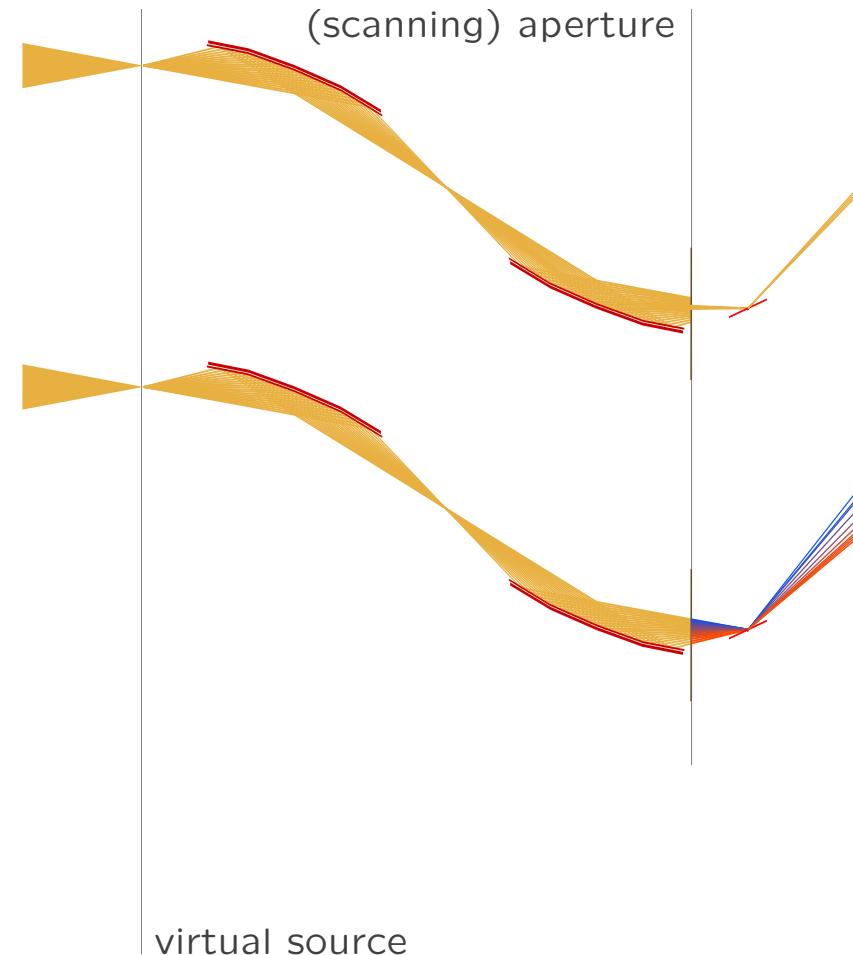
operation modes



almost conventional reflectivity

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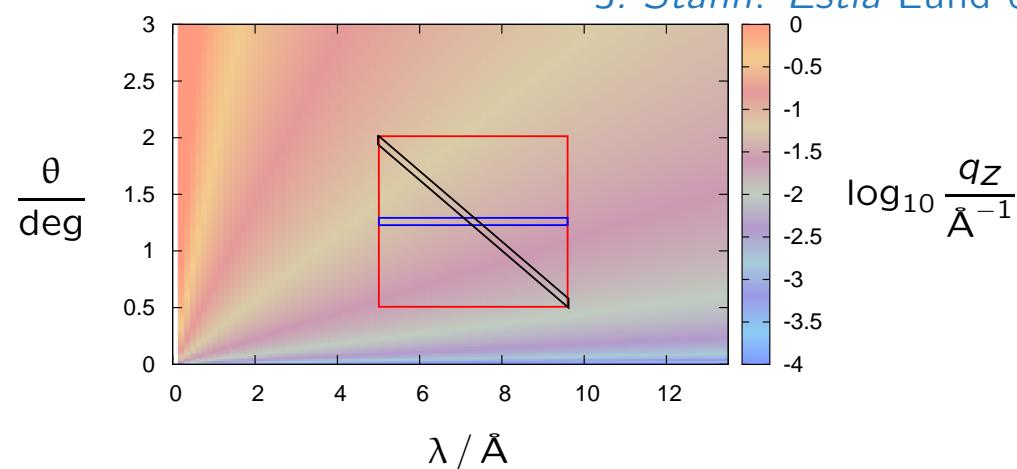


λ - θ -encoding

= $\text{TOF}(\theta)$

- o wider q_z -range
- o constant $\Delta q/q$

operation modes



almost conventional reflectivity

= TOF

- defined foot-print
- off-specular reflectivity

λ - θ -encoding

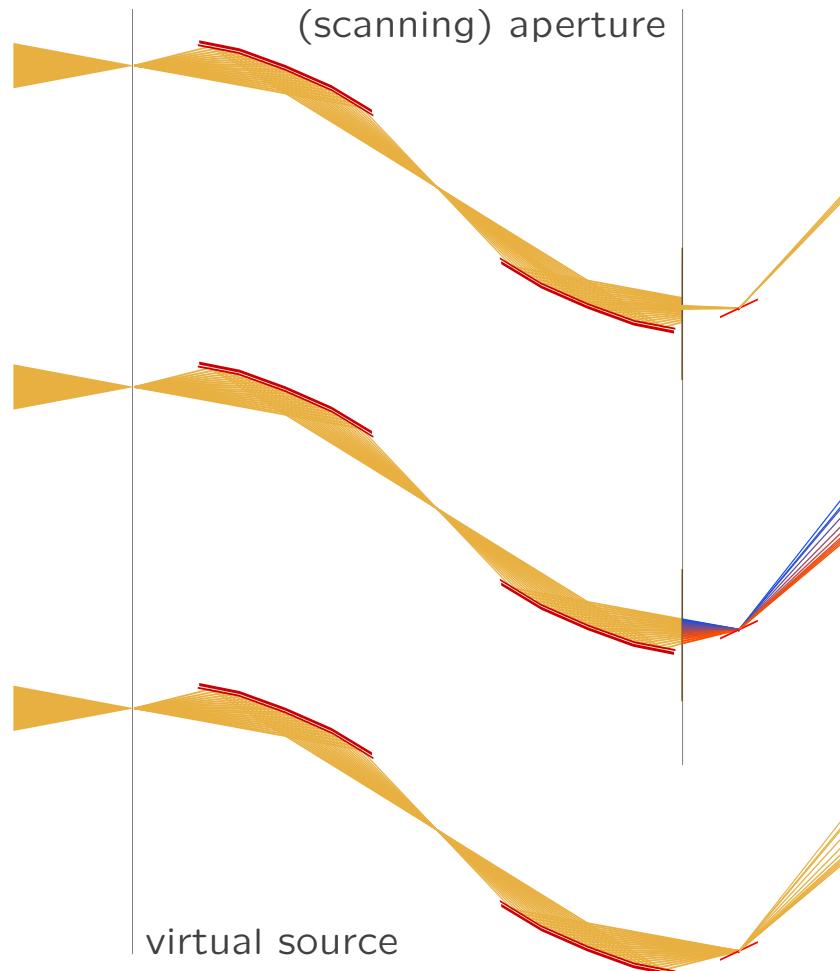
= $\text{TOF}(\theta)$

- wider q_z -range
- constant $\Delta q/q$

high-intensity specular reflectivity

= $\text{TOF} \times \theta$ -dispersive

- split-second t -resolution
- screening of parameter space



Estia — new lay-out

horizontal scattering plane

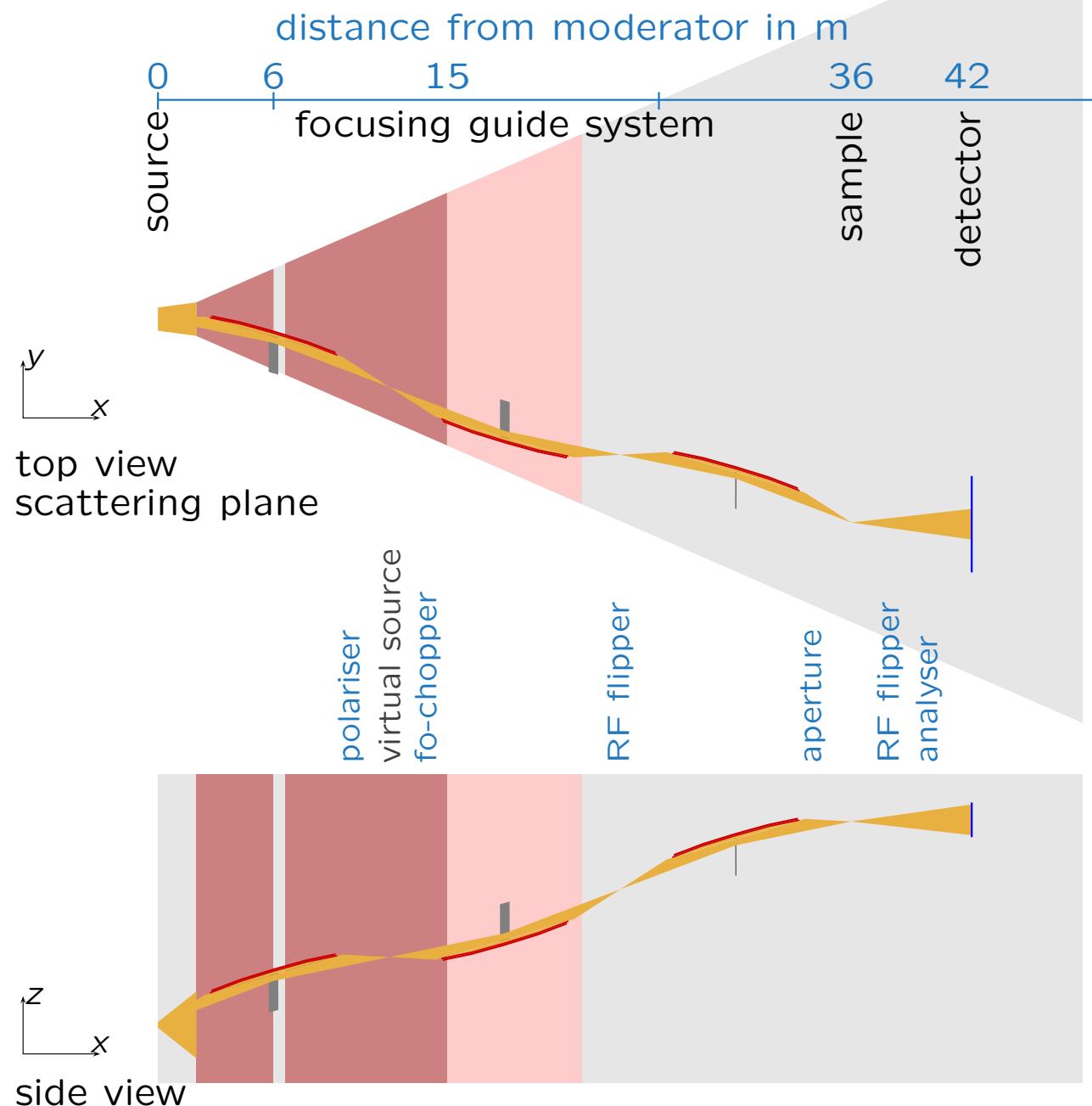
sample size $< 10 \times 50 \text{ mm}^2$

feeder + Selene guide

beam-direction:

Selene: parallel off-set

feeder: inclination
& declination



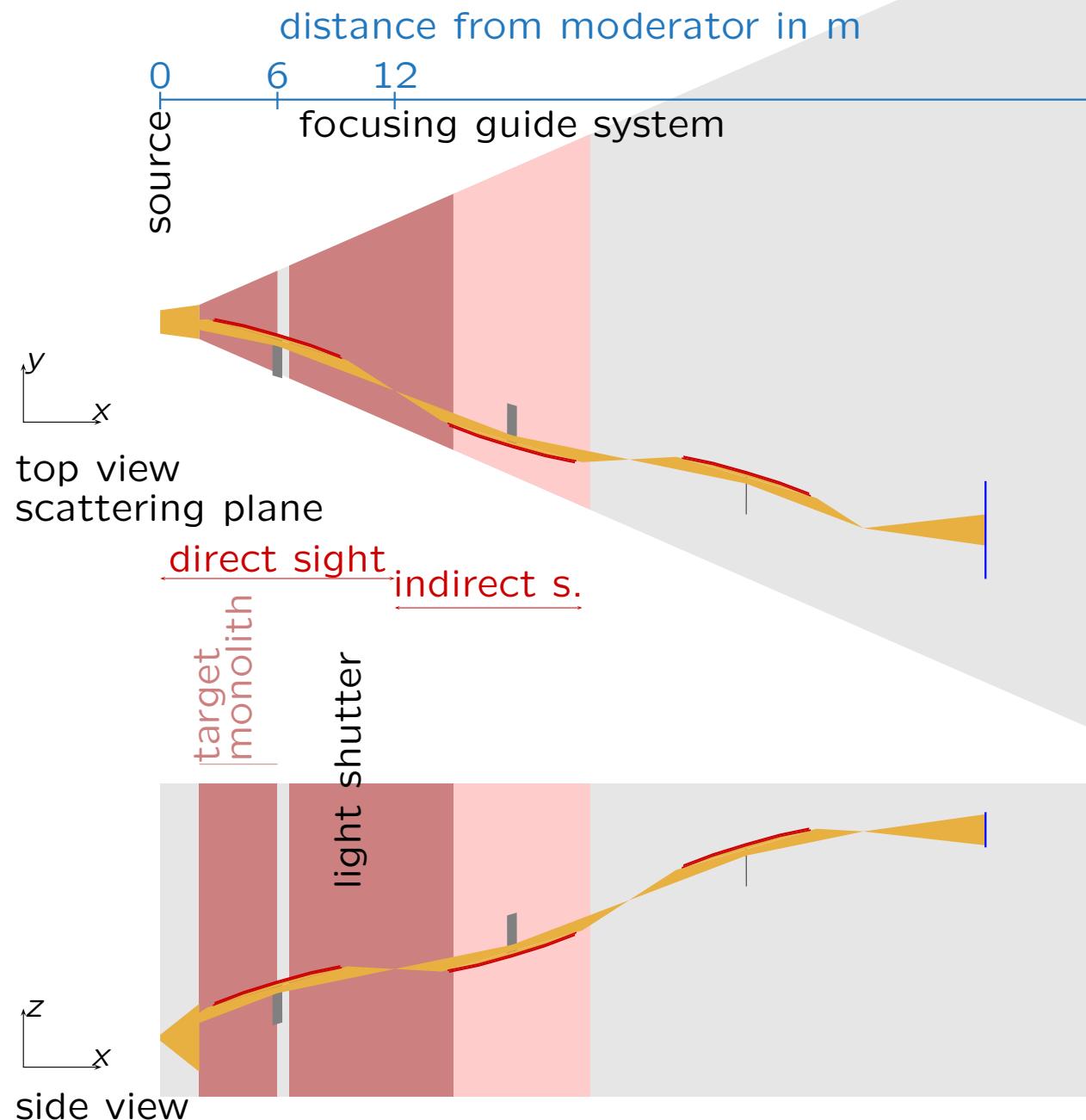
moderator and beam-extraction

moderator-size:

the smaller the better
i.e. $\approx 3\text{ cm}$ high

feeder:

1/2 Selene guide
12 m focal-point-distance



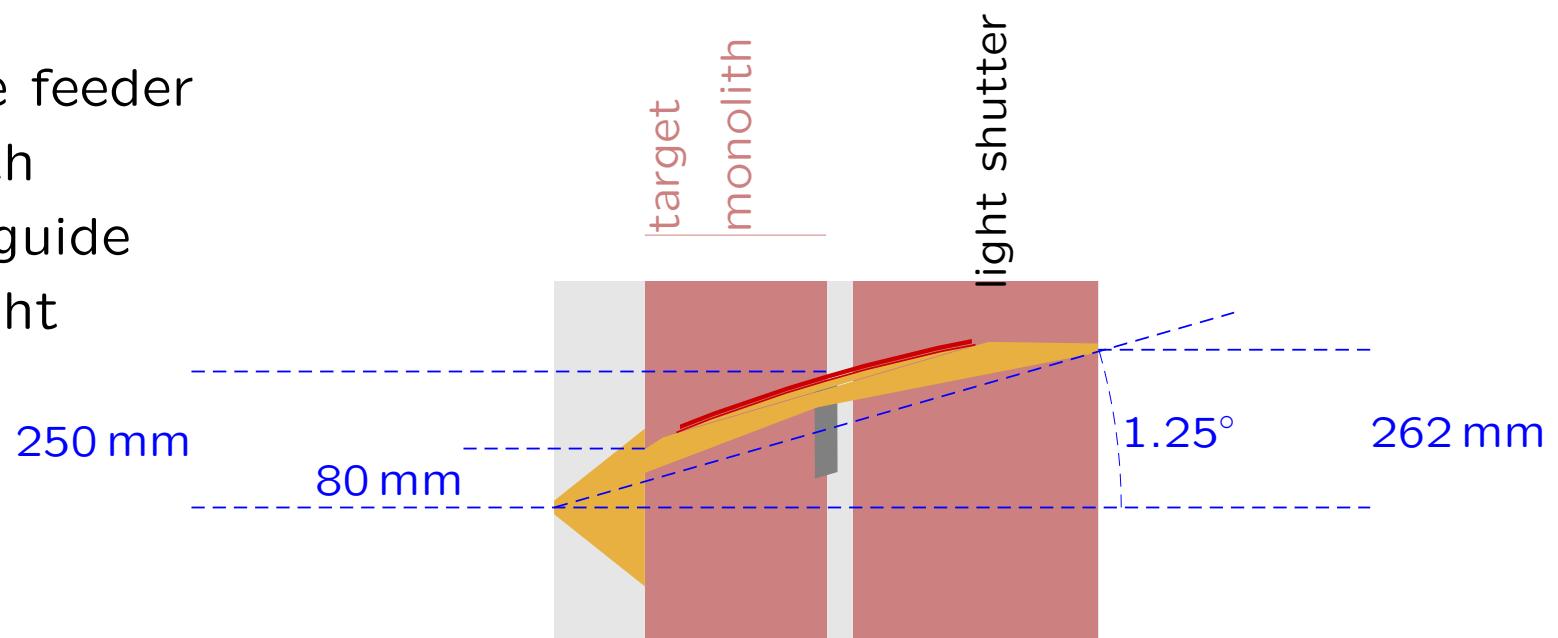
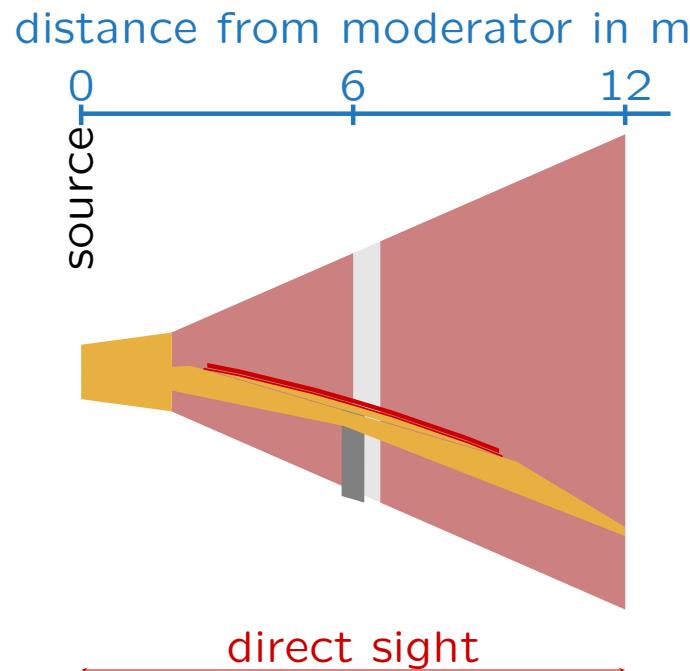
moderator and beam-extraction

geometry

entrance aperture ($x = 2\text{ m}$)
 $\approx 70 \times 70\text{ mm}^2$

exit aperture ($x = 11\text{ m}$)
 $\approx 15 \times 15\text{ mm}^2$

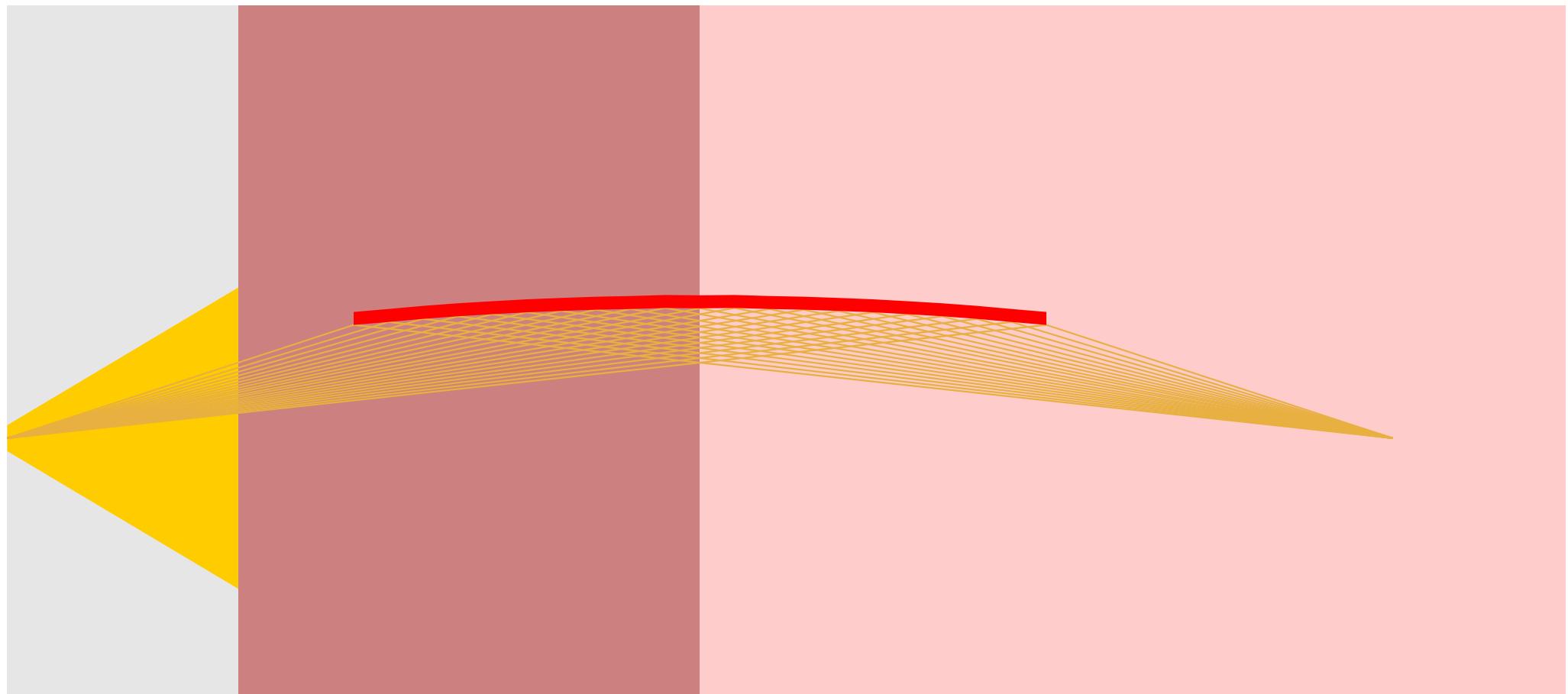
inclination of the feeder
in conflict with
– dognut guide
– inset height



moderator and beam-extraction

shielding

ideal trajectory

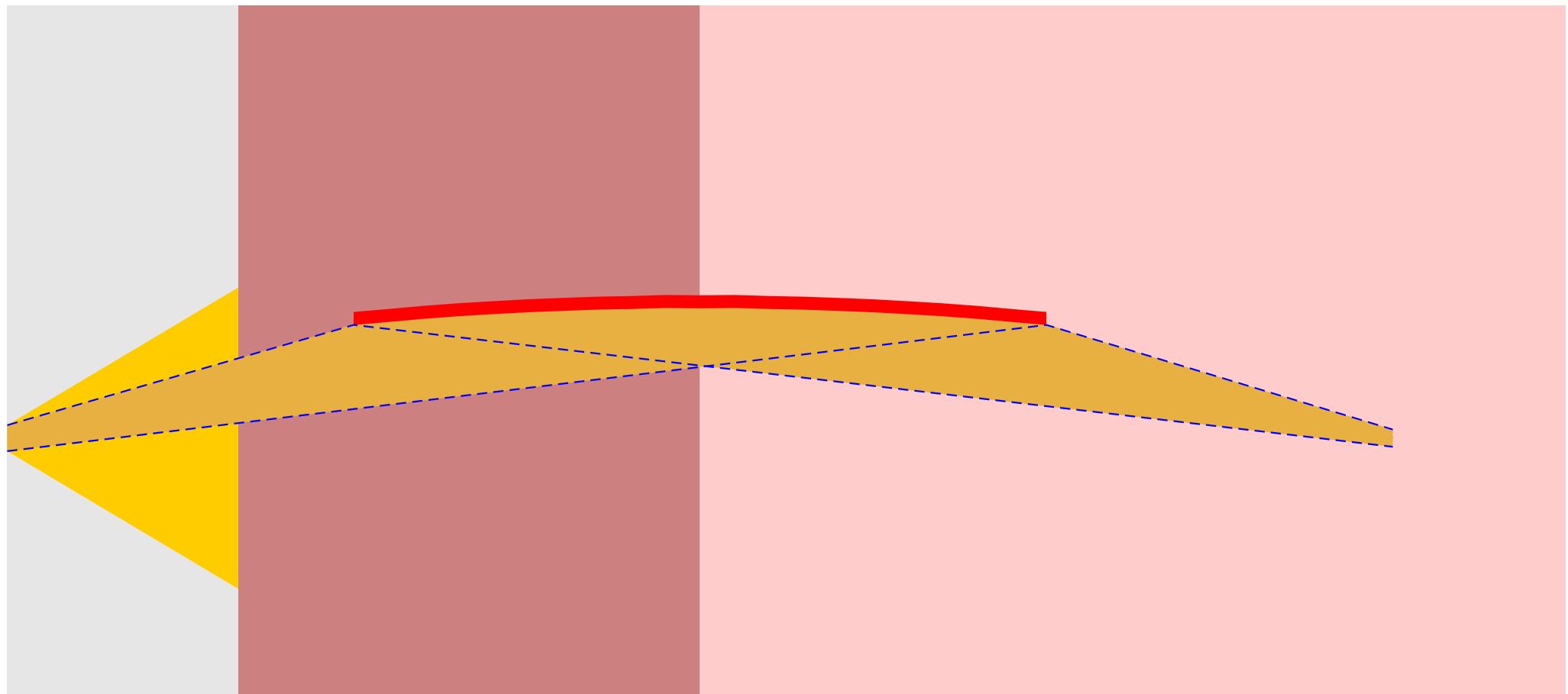


moderator and beam-extraction

shielding

finite moderator (30 mm)

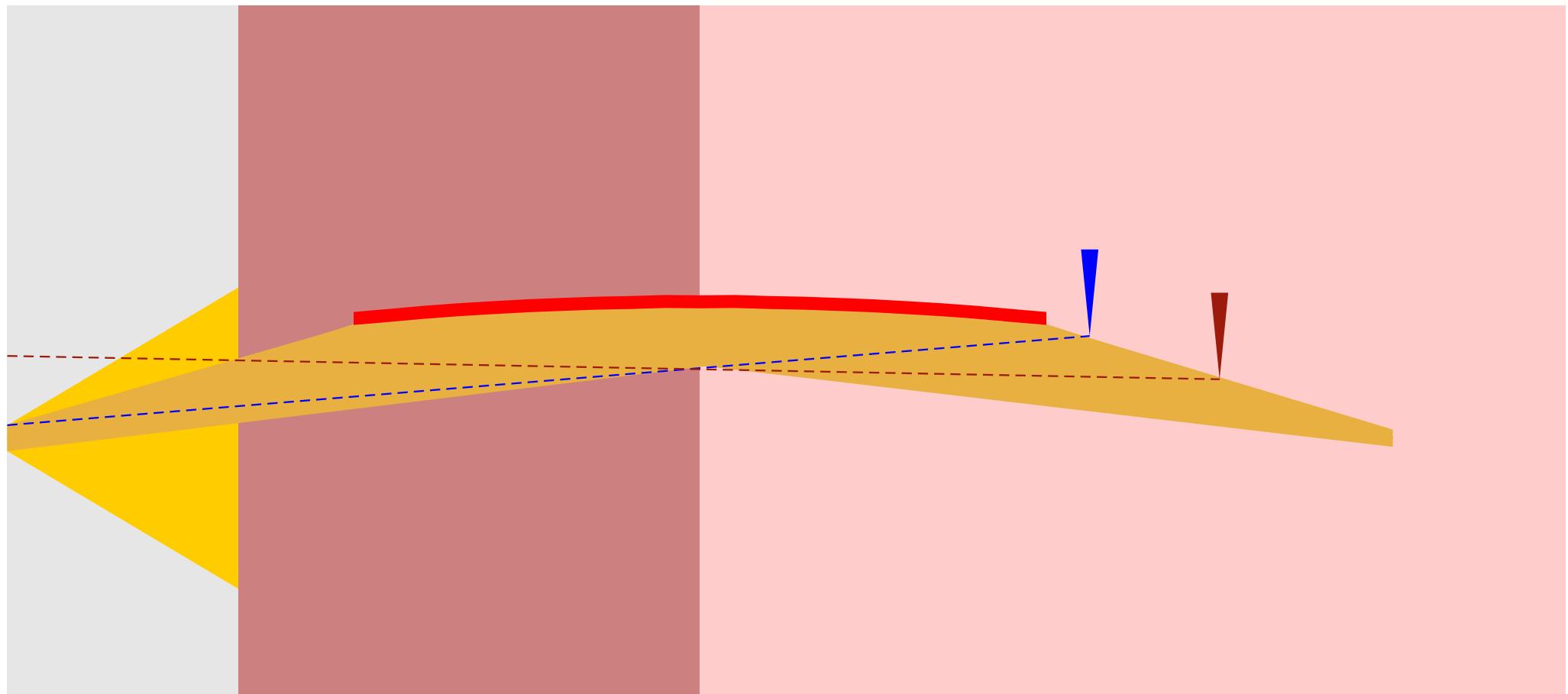
finite virtual source (20 mm)



moderator and beam-extraction

shielding

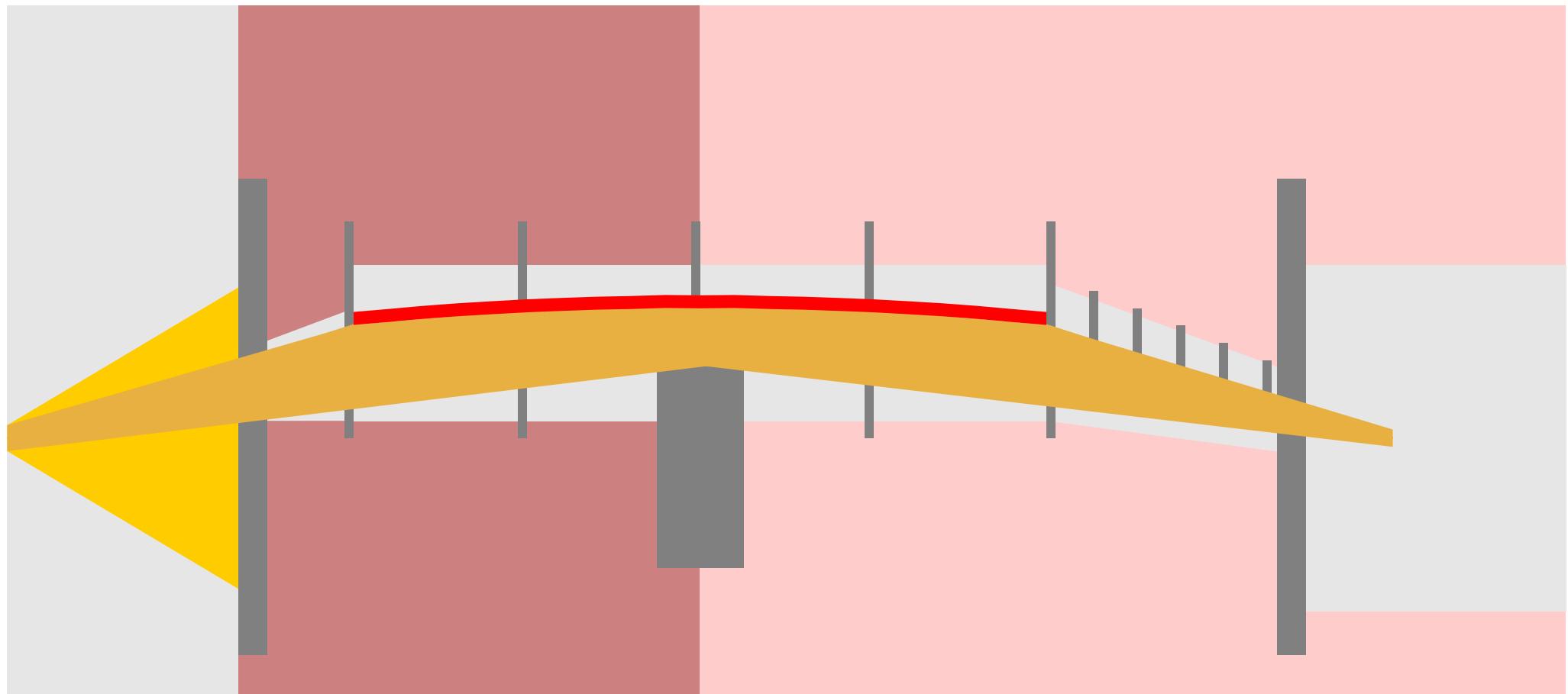
direct line-of-sight to moderator / target environment



moderator and beam-extraction

shielding

apertures and beam-stops

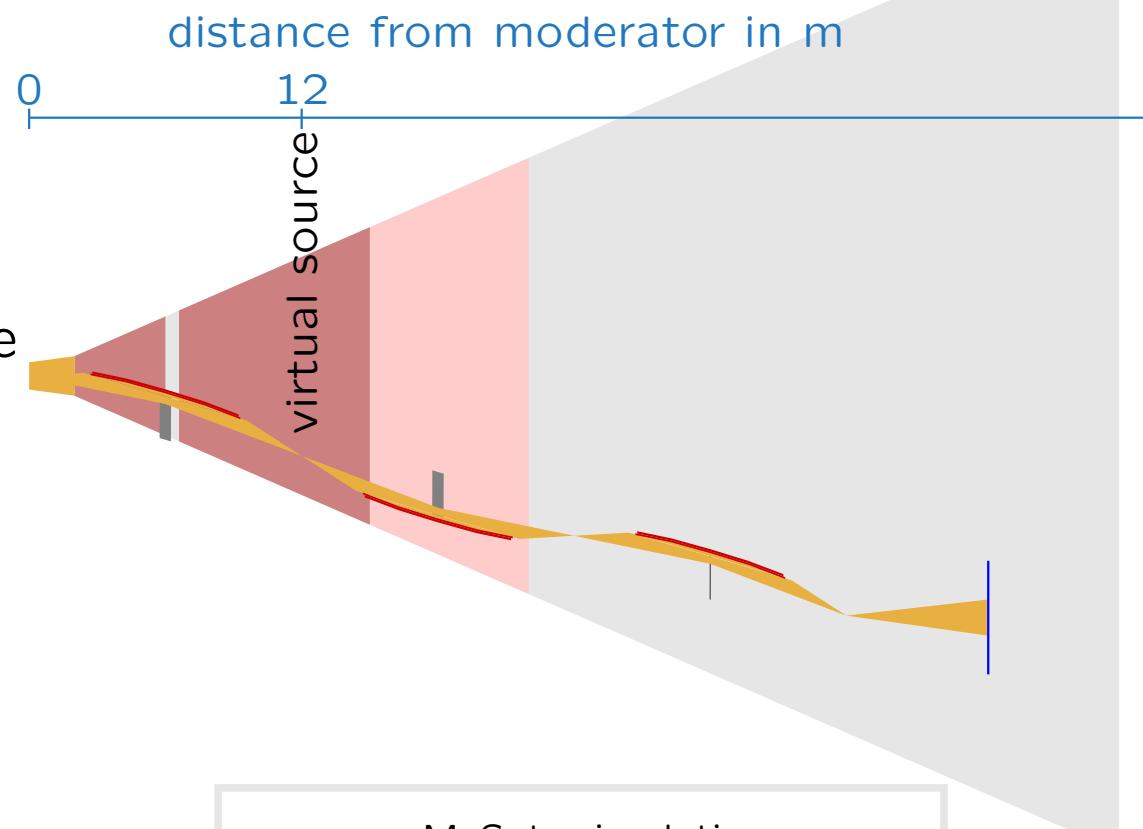
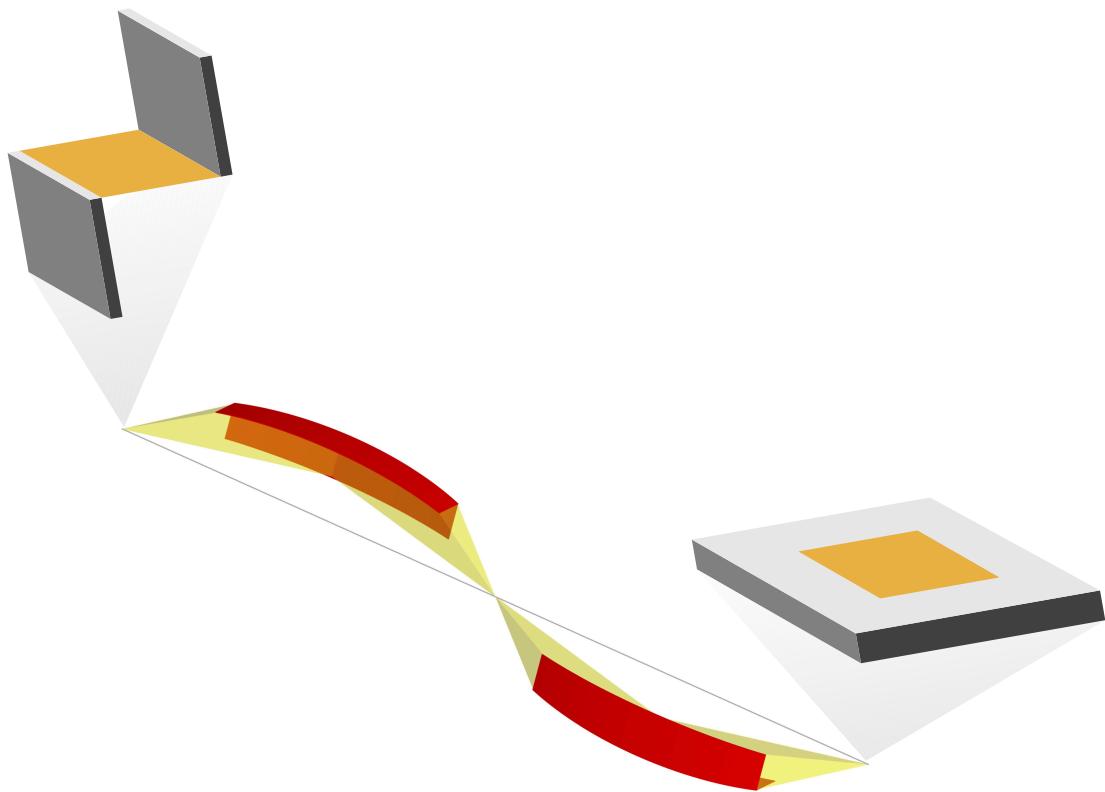


virtual source

a luminous field diaphragm defines

- shape
- size
- orientation

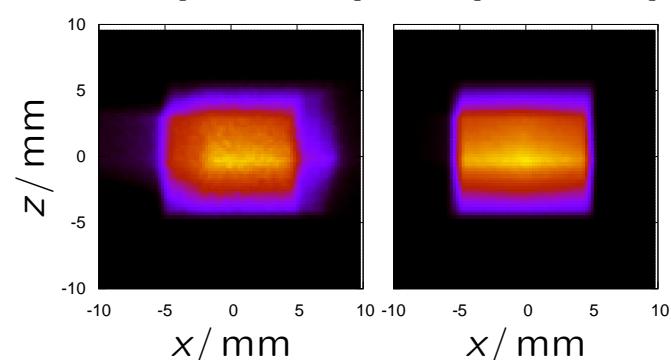
of the beam footprint on the sample



McSats simulations

$$A = 10 \times 10 \text{ mm}^2$$

$$\omega \in [0.2^\circ, 1.7^\circ] \quad \omega \in [6.1^\circ, 7.6^\circ]$$



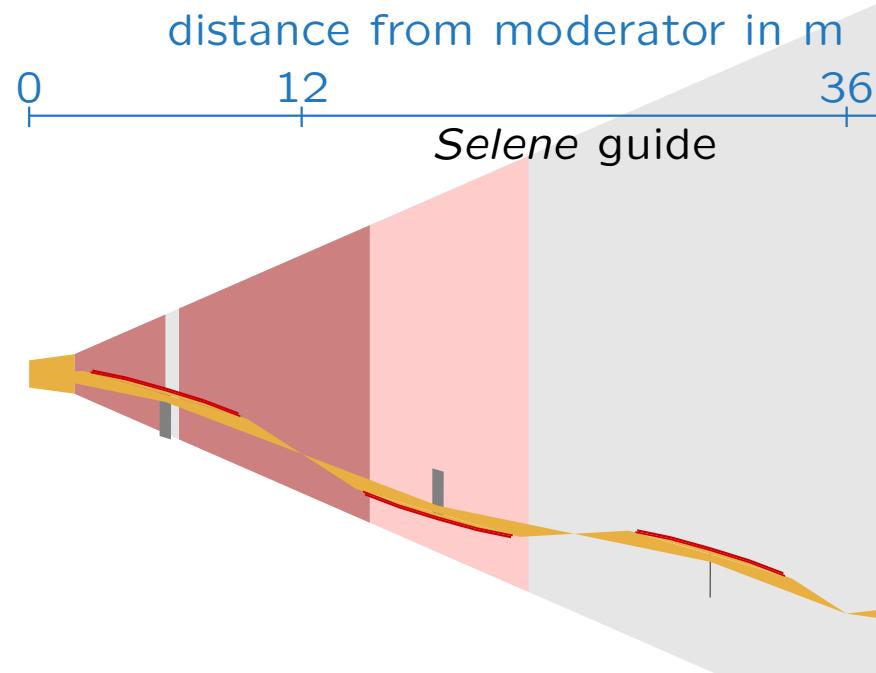
Selene guide

total length: 24 m

accuracy:

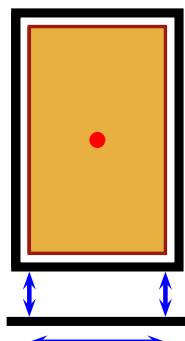
waviness $< 10^{-5}$ rad
position $\approx 1 \mu\text{m}$

⇒ precise alignment
easy realignment
thermalisation (RT)

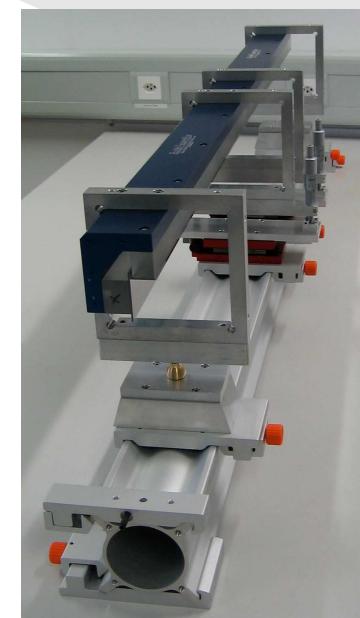
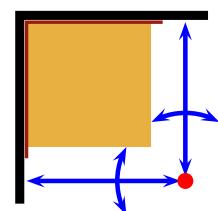


open construction allows for new alignment concepts:

conventional



open guide



optics — polariser

logarithmic (= equiangular)
spiral reflector

λ - and spin-filtering

prototype:

$$\Delta\theta = 1.8^\circ$$

for a $1 \times 50 \text{ mm}^2$ virtual source

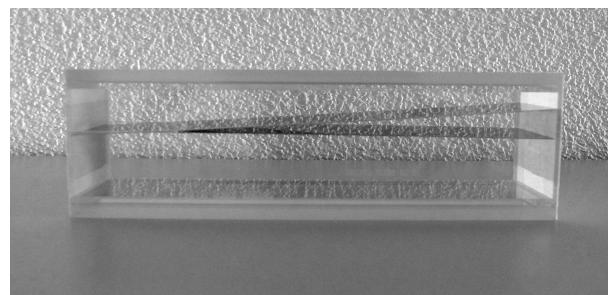
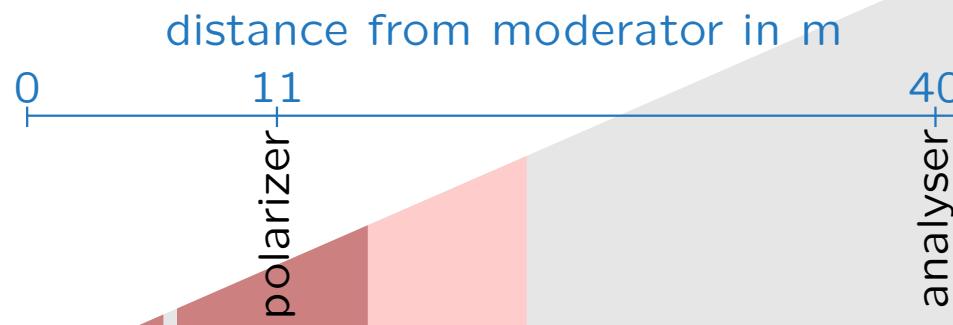
240 mm long

$m = 4.2 + \text{Ni}$ coating

\Rightarrow polarisation $> 4 \text{ \AA}$

$$\lambda < 16 \text{ \AA}$$

build by SwissNeutronics



optics — scanning aperture

located behind the guide

states:

absent / open

⇒ high-intensity mode

in place, stationary

⇒ conventional mode

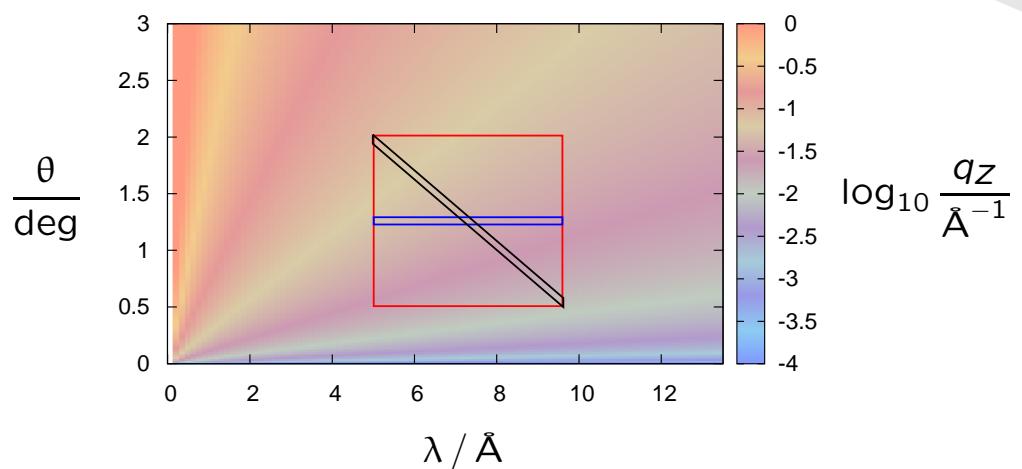
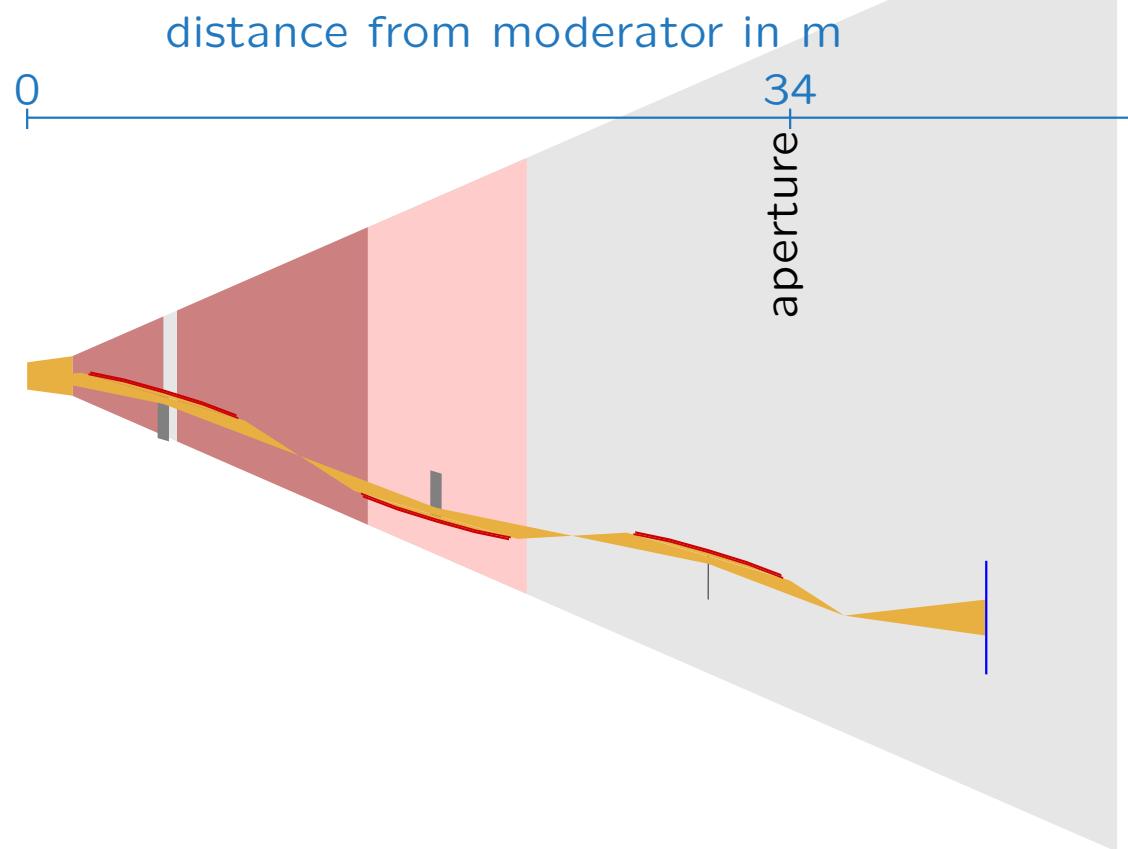
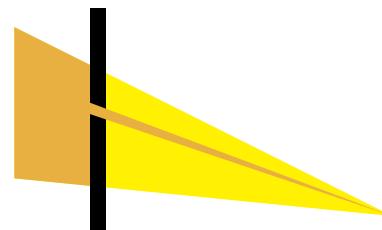
scanning

⇒ λ - θ encoding

periode 70 ms

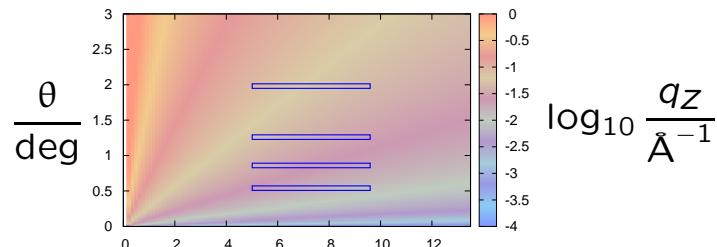
span 60 mm

reset-time 15 ms

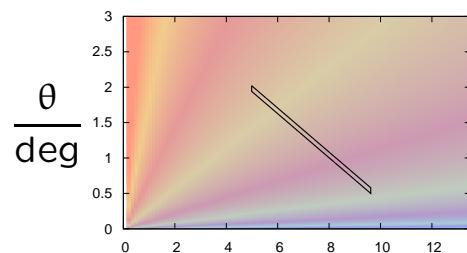


optics — scanning aperture

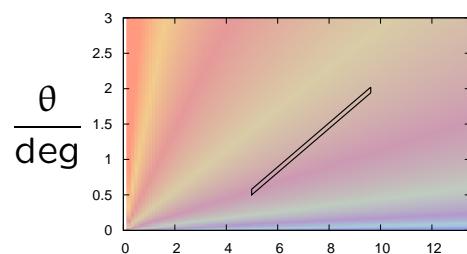
operation modes:



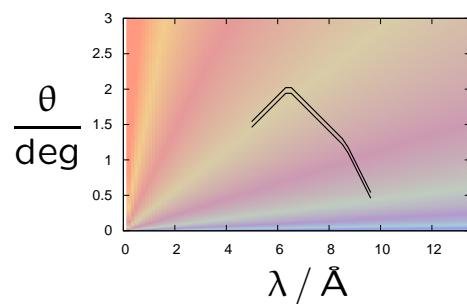
shift in between pulses
(see Freia)



linear scan during each pulse
large Δq_z



linear scan during each pulse
small Δq_z



fancy stuff
adapt q_z to $I(\lambda, \theta)$ and $R(q_z)$

optics — scanning aperture

needs to be developed!

max. speed:

6 ms^{-1}

max. path length:

60 mm

example:

praline-picking robots
running 24/7

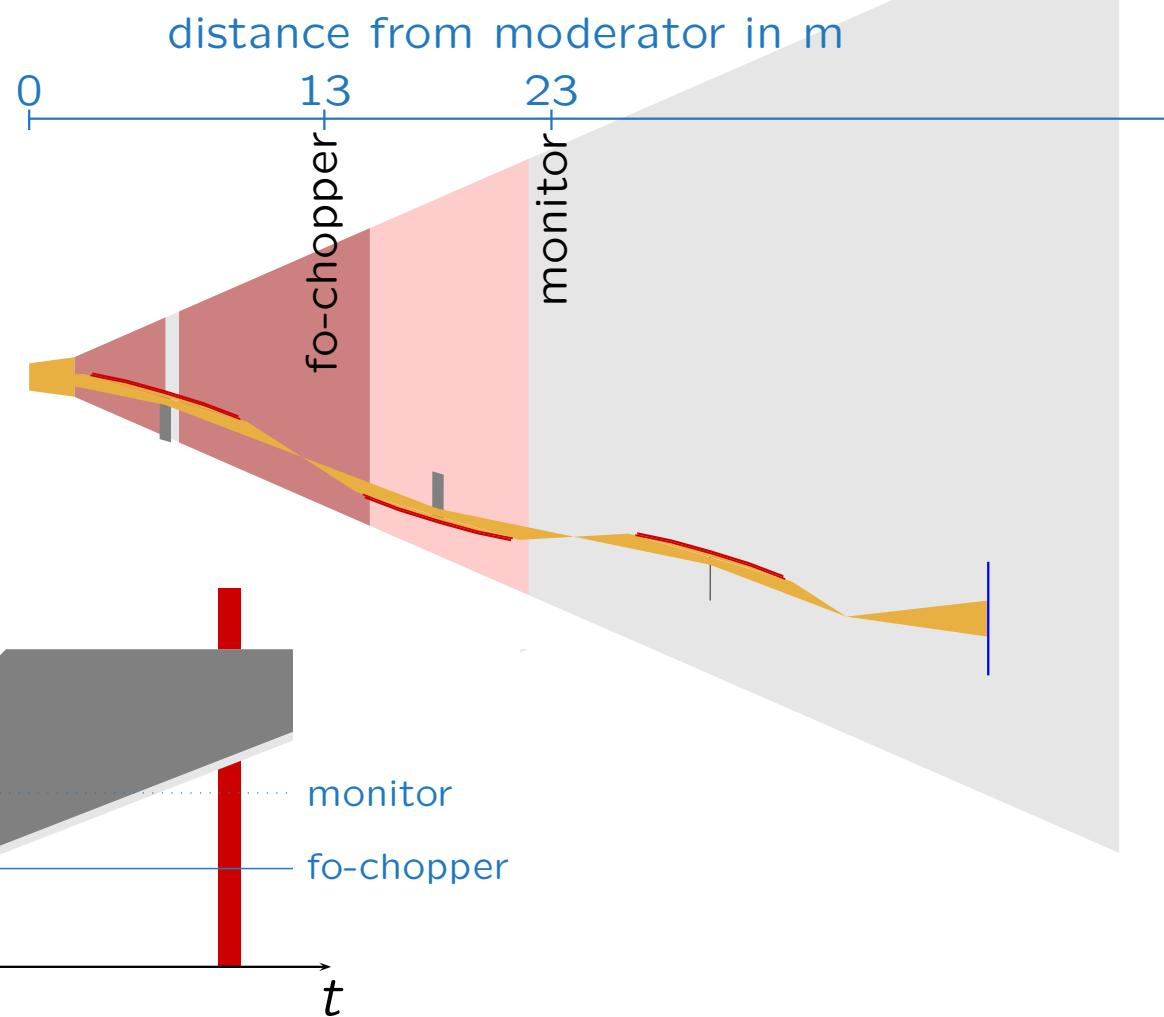
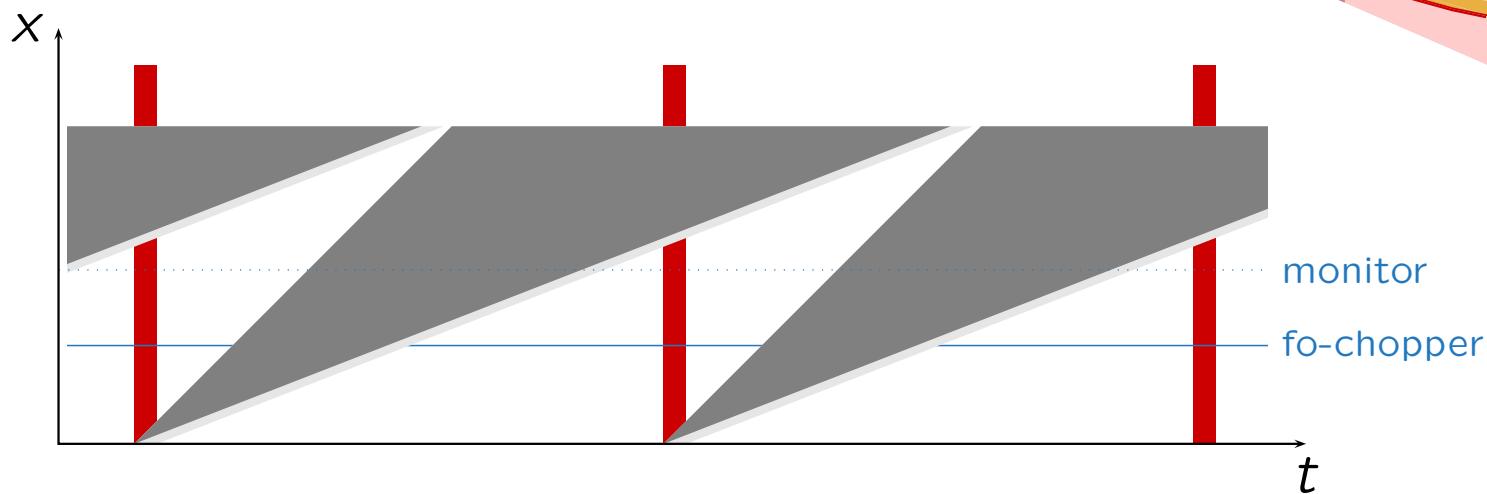


chopper — frame-overlap

beam-size $\approx 20 \times 20 \text{ mm}^2$

$v = 7 \text{ s}^{-1}$

2 openings à 57°



fo-filter for higher harmonics in combination with polariser