

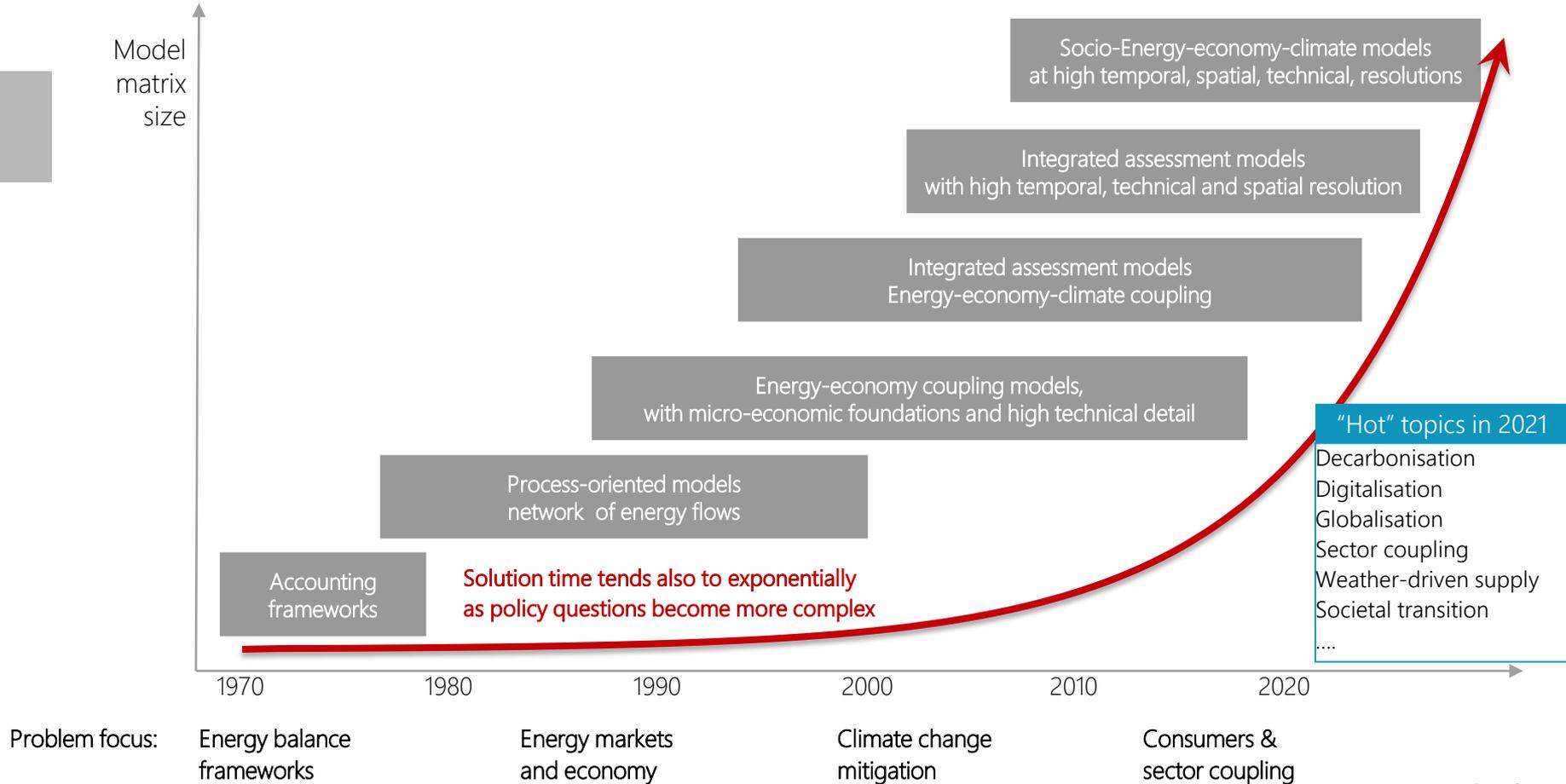


Evangelos Panos :: Paul Scherrer Institute

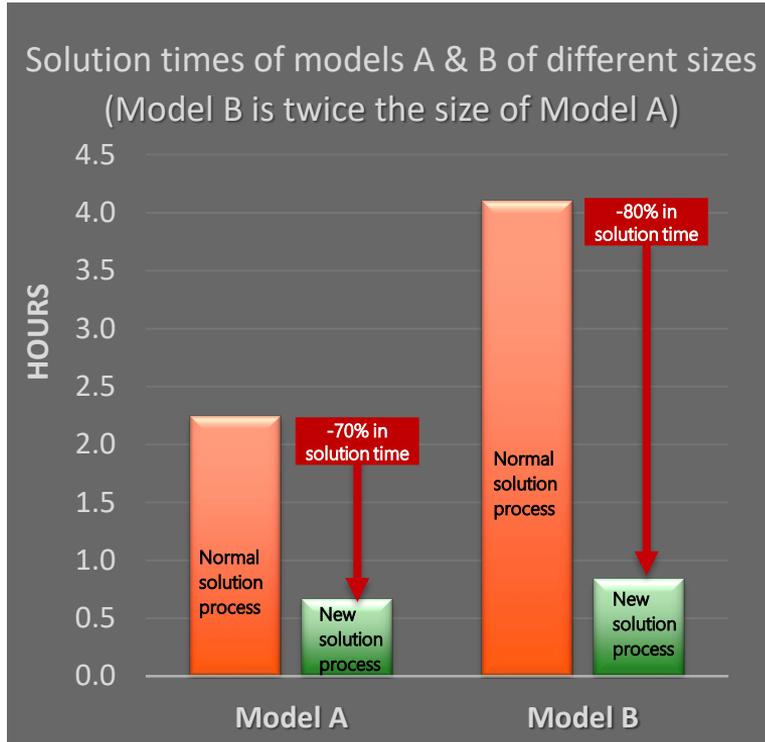
Ayman Hassan :: KTH Royal Institute of Technology

# Acceleration strategies for energy systems models: Insights using the TIMES modelling framework

# Need to deal with increasing complexity in energy systems analysis



# Can we “break” the relationship between matrix size and solution time?



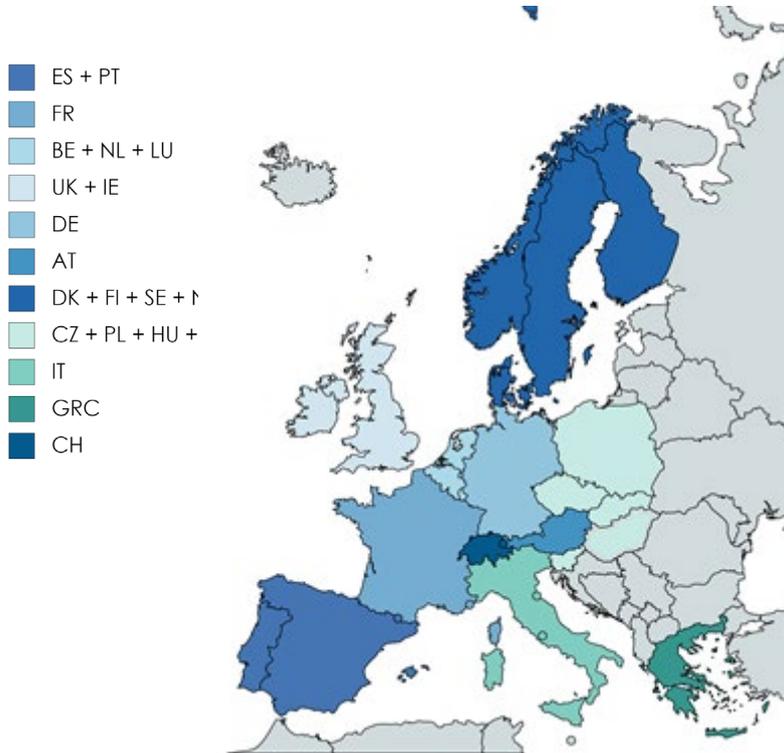
## What do we know about our model matrix?

- It is (very) sparse
- Equations and variables are defined over dimensions:
  - Regions, technologies, timeslices, years, ...
- Sub-matrices can be identified in model matrix:
  - E.g. all equations and variables of a particular “region”



Split the model matrix to submatrices and solve them in parallel at different CPUs



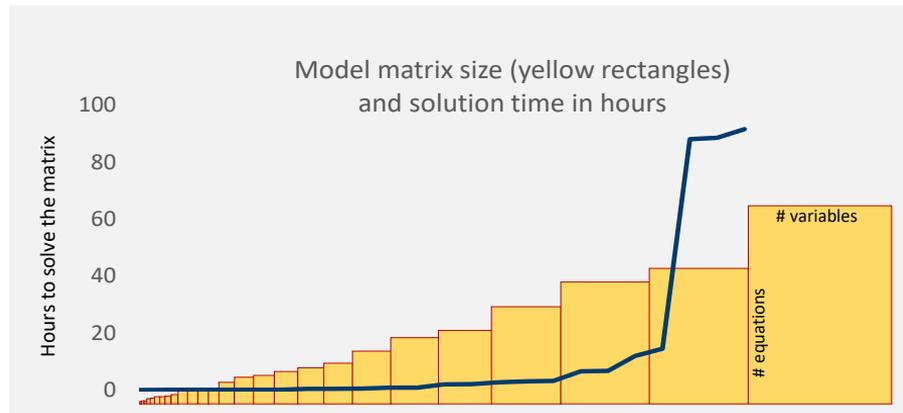


### EUSTEM model of PSI: energy system model for Europe

- Technology rich bottom-up model
- Long term horizon from 2020 to 2080
- **Flexible** region definitions: from 1 to 22
  - default 11 → see map on the left
- **Flexible** intra-annual resolution: from 48 to 8760 timeslices
  - default 288: 4 seasons x 3 typical days x 24h
- Detailed unit commitment algorithm for power plants

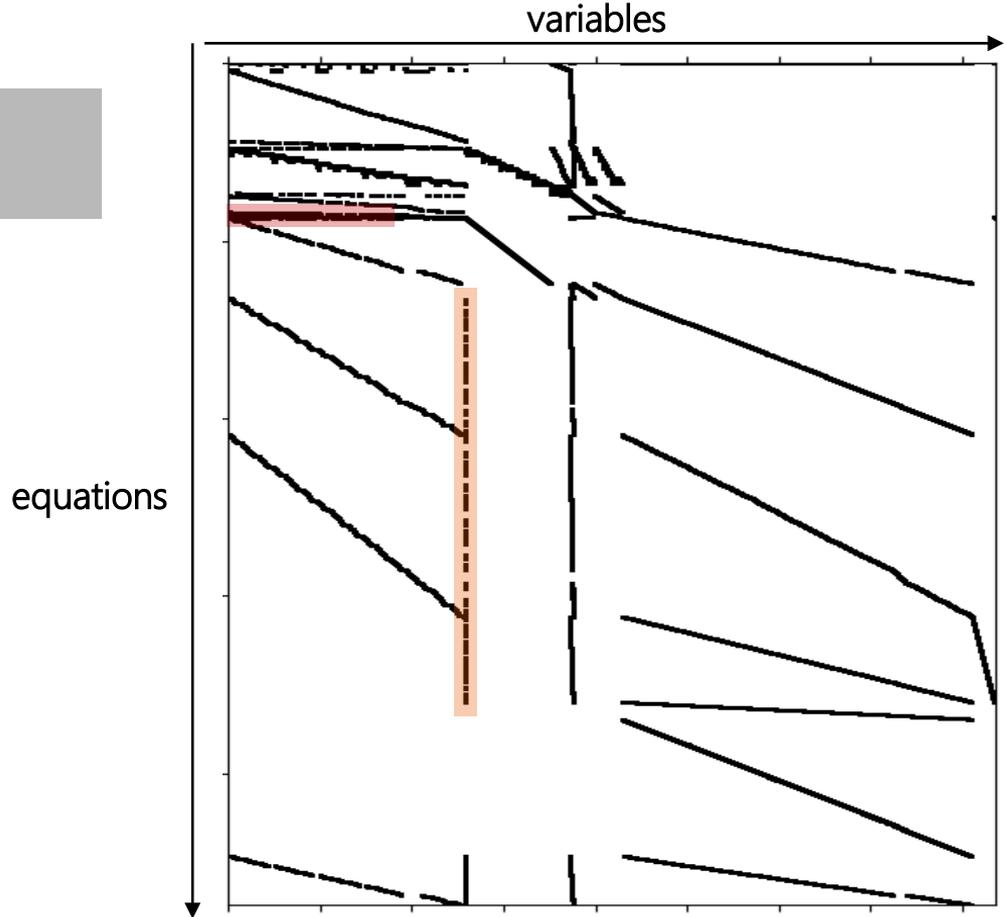
# Creating instances of EUSTEM of different sizes and solution times

Instance name (timeslices_regions)	Equations (million)	Variables (million)	Non-Zeros (million)	Solution time (hours) (solver time only)*
48_1	0.2	0.2	1.1	0.003
48_2	0.4	0.3	2.1	0.007
...	...	...	...	...
288_11	12.3	8.4	75.5	2.2
288_22	22.8	15.6	138.8	4.1
...	...	...	...	...
672_22	52.7	36	320.5	88.1
...	...	...	...	...
2016_11	85.7	58.1	525.6	91.6



\* Solution times obtained on a PC with:  
GAMS version: 31.1.1  
Solver: CPLEX/Barrier w/o crossover  
CPU: 1 Intel Xeon Gold 6152  
Parallel threads for CPLEX : 22

# How the model matrix $A$ of EUSTEM looks



EUSTEM algebraic representation:

$$\begin{aligned} \min \quad & \mathbf{c}^T \mathbf{x} \\ \text{subject to} \quad & \mathbf{A} \mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \geq 0 \end{aligned}$$

←

- Each dot is an equation coefficient in  $A$
- Very sparse matrix
- Coefficients occur in "blocks"
- "Linking" variables and constraints visible

1 `set blocks number of blocks /bl1*bl35/;`

Specify how many blocks (i.e. CPU nodes) will be used for solving the model

2 `set blockassignment(blocks,allyear,all_reg,ALL_TS)`

```

/
  bl1.(2020).(EST).(#all_ts)
  bl2.(2020).(NOR).(#all_ts)
  bl3.(2020).(STH).(#all_ts)
  bl4.(2020).(UKI).(#all_ts)
  bl5.(2020).(WST).(#all_ts)
  ...
  bl31.(2050).(EST).(#all_ts)
  bl32.(2050).(NOR).(#all_ts)
  bl33.(2050).(STH).(#all_ts)
  bl34.(2050).(UKI).(#all_ts)
  bl35.(2050).(WST).(#all_ts)
/;
```

Define the blocks across main dimensions of equations and variables of the model (in this example, each block refers to a particular time period and region)

Block *bl35* contains all equations and variables defined for year *2050* and region *WST*

Using *.stage* to assign each variable to the one of the blocks; first block should be numbered as 2

3

```
var_act.stage(all_reg,v,all_year,p,all_ts) = sum(blockassignment(blocks, allyear,all_reg,all_ts), ord(blocks) + 1);
var_comnet.stage(all_reg,allyear,c,all_ts) = sum(blockassignment(blocks, allyear,all_reg,all_ts), ord(blocks) + 1);
var_comprd.stage(all_reg,allyear,c,all_ts) = sum(blockassignment(blocks, allyear,all_reg,all_ts), ord(blocks) + 1);
```

4

```
var_obj.stage(all_reg,obv,cur) = 1;
var_cap.stage(all_reg,allyear,p) = 1;
```

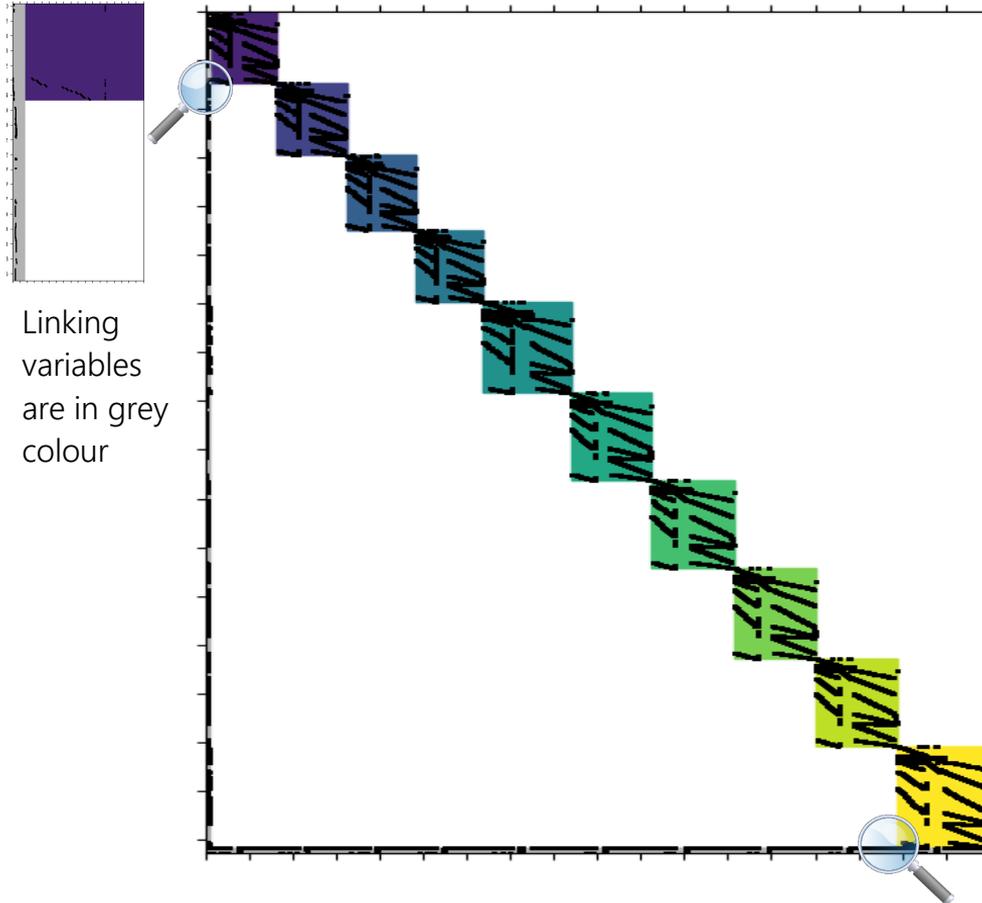
Variables existing across several blocks are “linking variables” and assigned to *.stage* = 1

- e.g. objective or capacity variables “living” many years, in a block decomposition based on “years” dimension

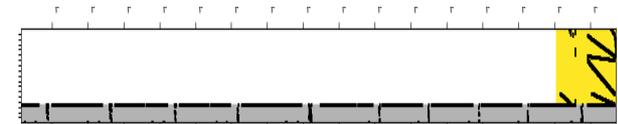
Same for equations, by setting *.stage* = number of block+1.

- equations having only “linking variables” are assigned to *.stage* = 1
- equations that contain variables from >1 blocks are assigned to *.stage* = cardinality(blocks)+1

# How the model matrix $A$ of EUSTEM looks **after** annotation



- Each dot is an equation coefficient in  $A$
- Variables and equations are organised into distinct blocks, which are revealed to solver via the *.stage* attribute
- These blocks can now be solved in parallel at different CPUs



Linking equations are in grey colour

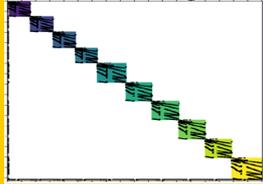
# Split the annotated matrix and solve it with PIPS-IPM solver in HPC

Workflow picture adapted from a BEAM-ME internal presentation by Fred Fiand (GAMS)



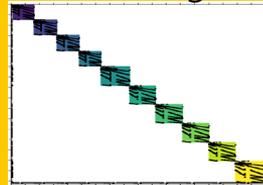
GAMS

Jacobian.gdx



SCP/FTP transfer

Jacobian.gdx



gmschk (to split jacobian)\*

Jacobian\_0.gdx

Jacobian\_1.gdx

Jacobian\_35.gdx

gmspips (to solve with PIPS)\*\*

Solution.gdx

SCP/FTP transfer

Solution.gdx

PIPS is a suite of parallel optimisation solvers developed at Aargon

PIPS-IPM is a parallel interior point solver for LPs and convex QPs, further improved in the BEAM-ME project by Zuse Institute Berlin (ZIB)

The decomposition in PIPS-IPM is based on the Schur complement:  
 - but the computation of the Schur complement is not parallel

Process solution

execute\_loadpoint  
Solution.gdx

\* gmschk -t -X -g «%gams.sysdir%» 36 jacobian.gdx

\*\* srun -n «%number\_tasks%» gmspips 36 jacobian.gdx «%gams.sysdir%»

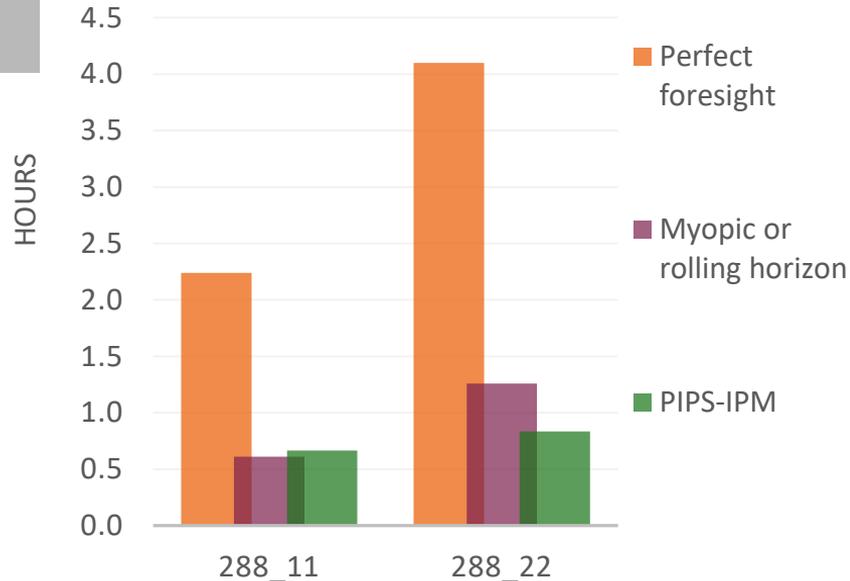


“Nothing worth having comes easy.”

– Theodore Roosevelt

- Annotation of the model must comply with PIPS-IPM requirements:
  - Max number of total linking variables and equations
  - Max number of linking variables and equations per block
  - Avoid dense links of blocks and opt for 2-links (consecutive)
  - To avoid overhead in CPU communications blocks need to be many and of the same size
- PIPS-IPM is being improved in presolve and scaling methods
- PIPS-IPM is being equipped with hierarchical calculation of Schur Complement to handle models with strong linkages

## Solution times of two EUSTEM instances



Instance	Equations	Variables	Non-Zeros
288_11	12.3 mio	8.4 mio	75.5 mio
288_22	22.8 mio	15.6 mio	138.8 mio

- Not all instances of EUSTEM could be solved by PIPS-IPM
- Investigation of model to eliminate redundancies that could increase linking constraints
- Different annotations examined to comply with PIPS-IPM limitations
- Instance 288\_11 was solved on 7 nodes on JSC supercomputer with 77 blocks in model matrix
- Instance 288\_22 was solved on 10 nodes on JSC and also had 77 blocks in model matrix
- PIPS-IPM can solve large scale energy systems models **without changing** their mathematical problem (e.g. like myopic runs or typical model aggregation techniques over time and space do)

## My thanks go to:

- Daniel Rehfeldt (ZIB)
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- Thomas Breuer (JSC)
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## More info:

[http://www.beam-me-projekt.de/beam-me/EN/Project/project\\_node.html](http://www.beam-me-projekt.de/beam-me/EN/Project/project_node.html)