

# **Physics motivation**

### Charged lepton flavor violation (CLFV)

- LFV observed in neutrino mixing
- Charged LFV not yet observed
- μ decays are clean searches
  (only decay products v, e, γ)



# Physics motivation

### Charged lepton flavor violation (CLFV)

- LFV observed in neutrino mixing
- Charged LFV not yet observed
- μ decays are clean searches
  (only decay products v, e, γ)
- Sensitive to beyond SM loop & contact interactions
- Current Limit of  $\mu^+ \rightarrow e^+e^-e^+$ : <u>SINDRUM</u>: BR < 1 x 10<sup>-12</sup>
- **Goal of Mu3e:** Improve single event sensitivity by 3 to 4 orders to  $< 2 \cdot 10^{-15}$  (<  $10^{-16}$  in Phase II)



- High muon rate needed  $\rightarrow 10^8 \,\mu$  decays/s
- DC surface muon beam at PSI (πE5 beam line)
  - Low momentum, 28 MeV/c
  - Muons stopped on target
  - Decay at rest



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- Signal decay:  $\mu \rightarrow eee$ 
  - Three prompt e<sup>+/-</sup>
  - Common vertex
  - ΣE = m<sub>µ</sub>
  - ο Σ**p = 0**



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  - Decay at rest Ο
- Signal decay: µ→eee
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  - Common vertex 0
  - ΣE = m... Ο
  - $\Sigma \mathbf{p} = 0$ Ο
- Main backgrounds:
  - Internal conversion 0



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  - Σ**p** = 0
- Main backgrounds:
  - Internal conversion
  - Accidental background



Michel e<sup>+</sup> & e<sup>-</sup> from Bhabha or y conversion

## MuPix sensor

### High-Voltage monolithic active pixel sensors (HV-MAPS)

- Monolithic: Detection and readout on the same chip
- In-pixel electronics
- Deep n-well diode
- Charge collection via drift (high voltage)
- Can be thinned to  $\leq$  50  $\mu$ m









#### Time and vertex resolution

- Fast detectors
- High granularity

#### High rate capability

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MuPix sensor

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### MuPix11

- Chip size:  $\sim 20 \times 23 \text{ mm}^2$
- Pixel size: 80 x 80 µm<sup>2</sup>
- time resolution < 20 ns
- Hit efficiency > 99 %





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# Detector design

- 4x **pixel** tracking layers only **→** minimize material
- 1T magnetic field







### **Detector design**

- 4x **pixel** tracking layers only → minimize material
- 1T magnetic field
- Recurl pixel station to get optimal momentum resolution
- Fast scintillating fiber and tile detectors for optimal timing resolution





Signal

Excellent momentum

Max. momentum: 53 MeV/c → resolution is **multiple** 

**Coulomb scattering limited** 

resolution needed

### Low mass pixel detector

### **Detector composition:**

- High-density interconnect (HDI) + HV-MAPS (50 µm thin)
- HDI = Aluminium-based flexprints



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Aluminium vs. Copper

Radiation lengths

 $X_0(Cu) = 12.86 \text{ g/cm}^2 \rightarrow 1.436 \text{ cm}$ 

### From chips to a detector

- 1. Receive **thinned** and **diced** wafers after **plasma etching** from OPTIM (France) on **blue tape** 
  - a. Place wafer on ceramic chuck
  - b. UV curing
  - c. Manual peeling and picking







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- **Time on blue tape** varies due to transport time (needs to be < 2 weeks)
- **Debris** from area between chips can slip below chips
- Observed yield increase over time
  - Better peeling with experience?
  - Thin chips appear to be very sensitive to the peeling procedure
- Burn marks from plasma etching visible
  - No impact on yield observed so far

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# From chips to a detector

- 2. Chip QC
  - a. Manual chip test card at PSI and Heidelberg for the vertex detector
  - b. Automatized testing with probe station in Oxford for outer layers (not yet fully ready)
  - c. Chip QC implemented in MIDAS









## From chips to a detector

### 2. Chip QC

### d. Check contact

Chip in contact with needle, power consumption within specs

### e. IV scan

Necessary depletion voltage can be reached

### f. On-chip voltages

Supply voltage adjustment, amplifier voltage (VSSA) correctly generated on chip

### g. VDAC tests

Test of adjustment of thresholds etc.

### h. Data transmission

Test integrity of high-speed LVDS links (1.25 GBit/s)

### i. Noise scan

Record noise and mask noisy pixels

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### From chips to a detector

- 2. Chip QC
  - **Test duration** ~ 30 to 40 min per chip
    Being optimized for automatized testing: Goal 1 wafer per day (44 chips)
  - k. Yield: ~ 50 % for 50  $\mu$ m; ~60 % for 70  $\mu$ m (very preliminary)

### Main issues:

- i. Mechanical damage
- ii. IV problems (HV short)





### From chips to a detector

- 3. Ladder assembly
  - a. Manual procedure for vertex detector
  - b. Chip placement on assembly chuck using a slider (confined two dimensions)
  - c. Check chip pitch with microscope









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### From chips to a detector

- 3. Ladder assembly
  - a. Manual procedure for vertex detector
  - b. Chip placement on assembly chuck using a slider (confined two dimensions)
  - c. Check chip pitch with microscope
  - d. Apply glue in quincunx pattern on chip
  - e. Put on HDI
  - f. Align by hand under microscope
  - g. Apply weights
    - + glue curing

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=5.896 mm =2.767 mm\*2 Glue dots on MuPix







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### From chips to a detector

### 4. Ladder QC

- a. Basically repetition of chip QC protocols
  - i. Plus detailed signal transmission scan and recording a hit map using a <sup>90</sup>Sr source
- b. Performed with complex vertical slice (also during pre-production), not on a simplified readout chain → Due to missing personpower
- c. Lost a lot of time on debugging
- d. Gained a lot of experience on the final hardware
- e. Main problem:
  - Data readout via μ-twisted pair cable
    (a MUST due to limited space for services)
    - Hardware problems, worse data transmission with first batch
  - ii. LVDS-related DAC settings needed to be optimized
    - ➡ Longer signal lines compared to chip QC
    - ➡ Large parameter space



Vertical slice of Mu3e pixel readout inside magnet

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BoSSL PCB connecting µ-twisted pair cables (22 pairs) with the end-piece flexprint of the vertex detector



### From chips to a detector

- 5. Module assembly
  - a. Manual procedure
  - b. Ladders glued together via Kapton flap
  - c. Electrical connections via interposer pin connector to end-piece flexprint
  - d. Self-supporting half-shell structure
  - e. Handling of modules is surprisingly easy





## From chips to a detector

- 6. Barrel assembly
  - a. Modules are **mounted on a specific tool** to the full vertex detector outside the experiment
  - b. Vertex detector is inserted between the beampipes as one unit





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Layer 1 module mounted only on one side

# The outer pixel layers



• **Automated** chip placement on gantry



Automated chip placement tooling on the Oxford gantry. 18 chips are placed with a chip gap of 40 µm.

# The outer pixel layers

- Automated chip placement on gantry
- Alignment of components via **precise tooling** (not fully by hand as for vertex detector)



Positioned chips on chuck (left). HDI in ring frame (pre-aligned) with glue deposited in quincunx pattern.

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# The outer pixel layers

- Automated chip placement on gantry
- Alignment of components via precise tooling (not fully by hand as for vertex detector)
- Additional mechanical support using v-folds
  - Past baseline: Kapton-based v-fold
  - o Current baseline: Carbon stiffener (25 μm)
    - + 8 µm co-cured Kapton layer (el. isolation)
    - ➡ Low material budget with maximum stability

Carbon stiffener for a Mu3e outer pixel ladder. You can look at a real prototype after the talk.









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    - ➡ Low material budget with maximum stability
- Chip and ladder QC:
  - Chip QC on probe station in Oxford (automated)
  - Ladder QC in thermal test box (using simplified readout board, not full QC)
  - All processes to be verified within this year



Carbon stiffener for a Mu3e outer pixel ladder. You can look at a real prototype after the talk.

# Lessons learned (an incomplete list)



- Thin monolithic silicon chips require careful/trained handling
  - Clean work (gloves, dust free environment or proper cleaning)
  - Clearly defined working steps 
    production protocols/checklist (also for experienced colleagues)
- Benefits from **early stage prototyping** (even if geometry is not fully finalized)
  - Many smart design improvements can be triggered early enough
  - Go through every working step (even the ones which appear to be simple)
- Transfer knowledge between production sites
- Modular design in as little flavours as possible
  - Think about yield and spares
  - Design ladders/modules in a smart way  $\Rightarrow$  Goal: No multiple flavours of interfaces
- Verify functionality of **all non-standard components** already way before (pre-)production

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We did not adequately follow these guidelines

# Summary

- After four years of serious prototyping Mu3e went into production phase this year
- Vertex detector production ongoing
  - Full vertical slice proved functionality 0
  - Getting ready for cosmic run in autumn 2024 Ο
- Outer layer pre-production prepared
  - Currently establishing chip and ladder QC procedures Ο
- Building my own Mu3e-like detector?
  - Current detector ladder design transferable to different detector Ο geometries (modularity)
  - Cu-based HDIs with wire bonds can replace our Al-based ones when 0 material budget is not that crucial ( $\geq 0.15 \% X_0$ ) (standard components wherever possible)
  - Less compact design (e.g. for services) avoids most problems we had Ο
  - Currently no chip vendor for MuPix sensors anymore 0
  - But: Our ambitious detector design is viable. Ο

### Don't be afraid of crazy ideas!

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# Back up

### Low mass pixel detector

### From HDIs and sensor chips to a detector

- 1. MuPix chips are **qualified** in probe card
- 2. MuPix chips are aligned on assembly tool
- 3. MuPix chips are glued on the HDI and bonded to a ladder



Ladder



Manual MuPix probe card



Glue dots on a MuPix chip



spTAB connections from HDI to the MuPix chips

### Low mass pixel detector

### From HDIs and sensor chips to a detector

- 1. MuPix chips are **qualified** in probe card
- 2. MuPix chips are **aligned** on assembly tool
- 3. MuPix chips are **glued** on the HDI and **bonded** to a **ladder**
- 4. Ladders are glued to each other forming half-shell modules
- 5. 4 modules mounted as two barrel layers forming the vertex detector





Silicon heater mock-up module





