



WIR SCHAFFEN WISSEN – HEUTE FÜR MORGEN

Jochem Snuverink :: Paul Scherrer Institut

Automation of accelerator tuning with safety constraints using Bayesian Optimisation

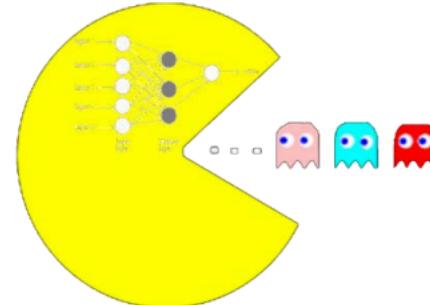
LMU seminar – 28.01.2022

Outline

- PACMAN
- (beamline) optimisation
- optimisation GUI
- Examples PSI
 - SwissFEL
 - HIPA
 - PiE1 - MIXE
- Practicalities & Next steps
- Conclusions



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**EPFL**

- PACMAN (Particle Accelerators & Machine Learning) project
- Swiss Data Science Center (SDSC), the École Polytechnique Fédérale de Lausanne (EPFL), CERN, ETH-Z and PSI
- Particle accelerators are complex facilities that produce and handle large amounts of data
- The project target is to explore the possibilities to use machine learning to improve the performance of particle accelerators
- March 2019 - June 2021

Why automate beamline tuning?

- Time-consuming repetitive task for operators
- (potentially) faster
 - Quick iterations, no dead time
 - Can change many parameters at once
 - Evaluate noise
- (potentially) safer
 - No “human” mistakes
 - Can supervise all safety constraints simultaneously

Optimisation at HIPA and SwissFEL

HIPA

- HIPA beam power (1.3 MW) limited to the beam losses
 - Reduce damage and activation
- Optimisation is now mostly done empirically
- Large potential for automated optimisation and surrogate model construction
 - No accurate and fast physics model available
 - Needs to be *safe*

SwissFEL

- Goal: Optimise the FEL pulse intensity
-> Many Photons = Happy Users
- Challenges:
 - Manual tuning is time consuming & inefficient
 - Use many knobs (~40)
 - Don't drive the machine into the wall...
 - Exponential dependence of FEL output on many, coupled machine parameters



ML experts from ETHZ suggested Bayesian Optimisation

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- The work is supported by the Swiss National Science Foundation under grant 200020_159557

Why Bayesian Optimisation?

Human Optimisation

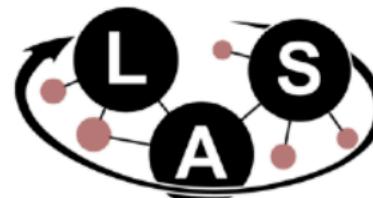


Numerical Optimisation

- Life-long learning
- Experience
- Limited working memory
- (relatively) Slow decisions

- Bulk learning
- Cannot estimate uncertainty
- Juggle many things at once
- Fast decisions

ETH zürich



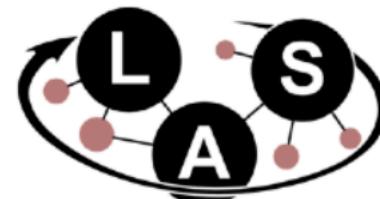
Learning &
Adaptive Systems

Why Bayesian Optimisation?

Bayesian Optimisation

- ~~Life-long learning~~
- ~~Experience~~
- ~~Limited working memory~~
- ~~(relatively) Slow decisions~~
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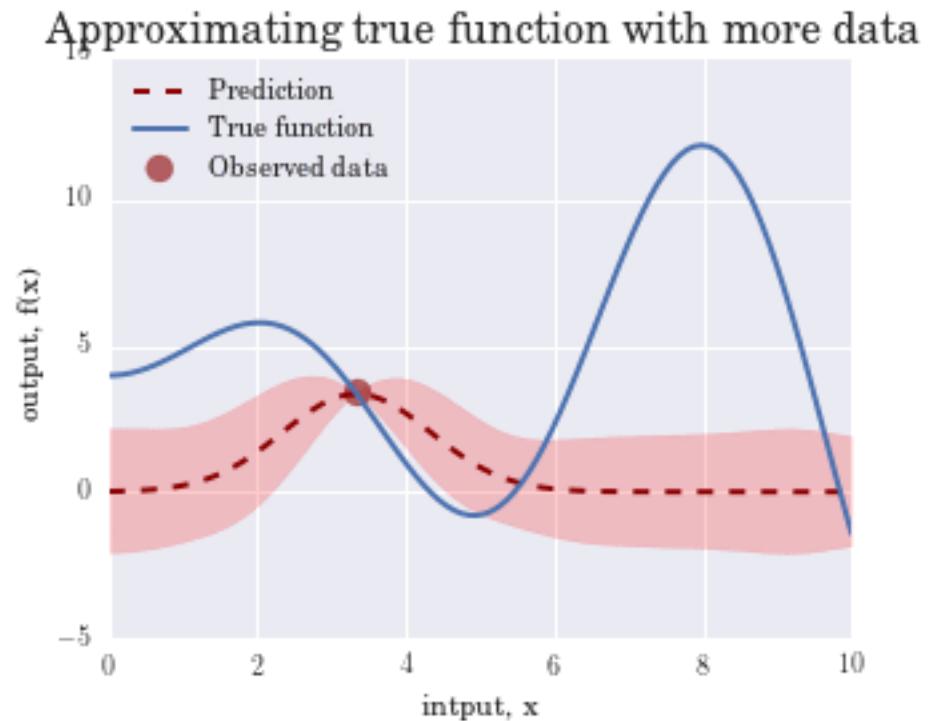
ETH zürich



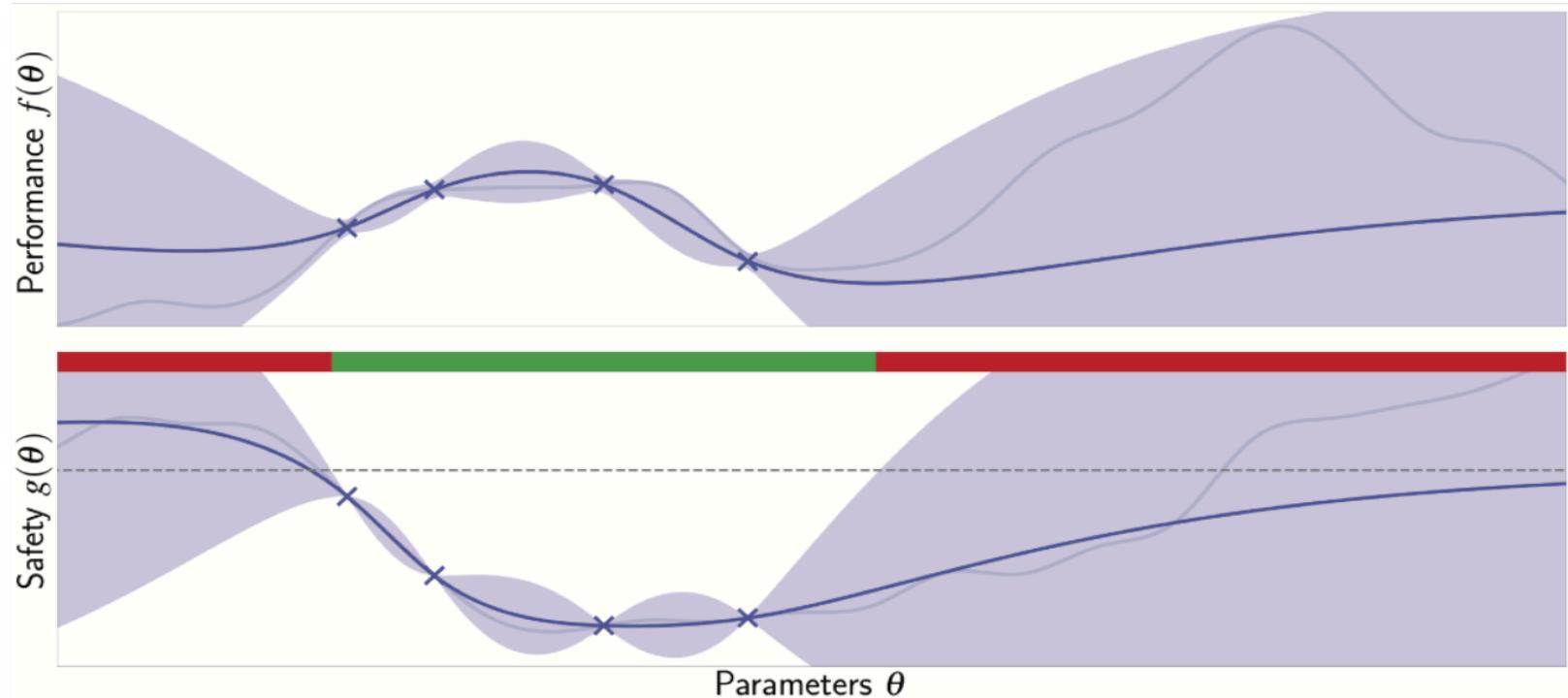
Learning &
Adaptive Systems

Bayesian Optimisation

- Bayesian Optimisation:
flexible, data-driven
approach for global
optimisation with noisy
feedback.
- Fit a statistical regression
model of the data, typically a
gaussian process.
- On each iteration the model
looks for evaluation points
that reduce the uncertainty
of the unknown target
function.

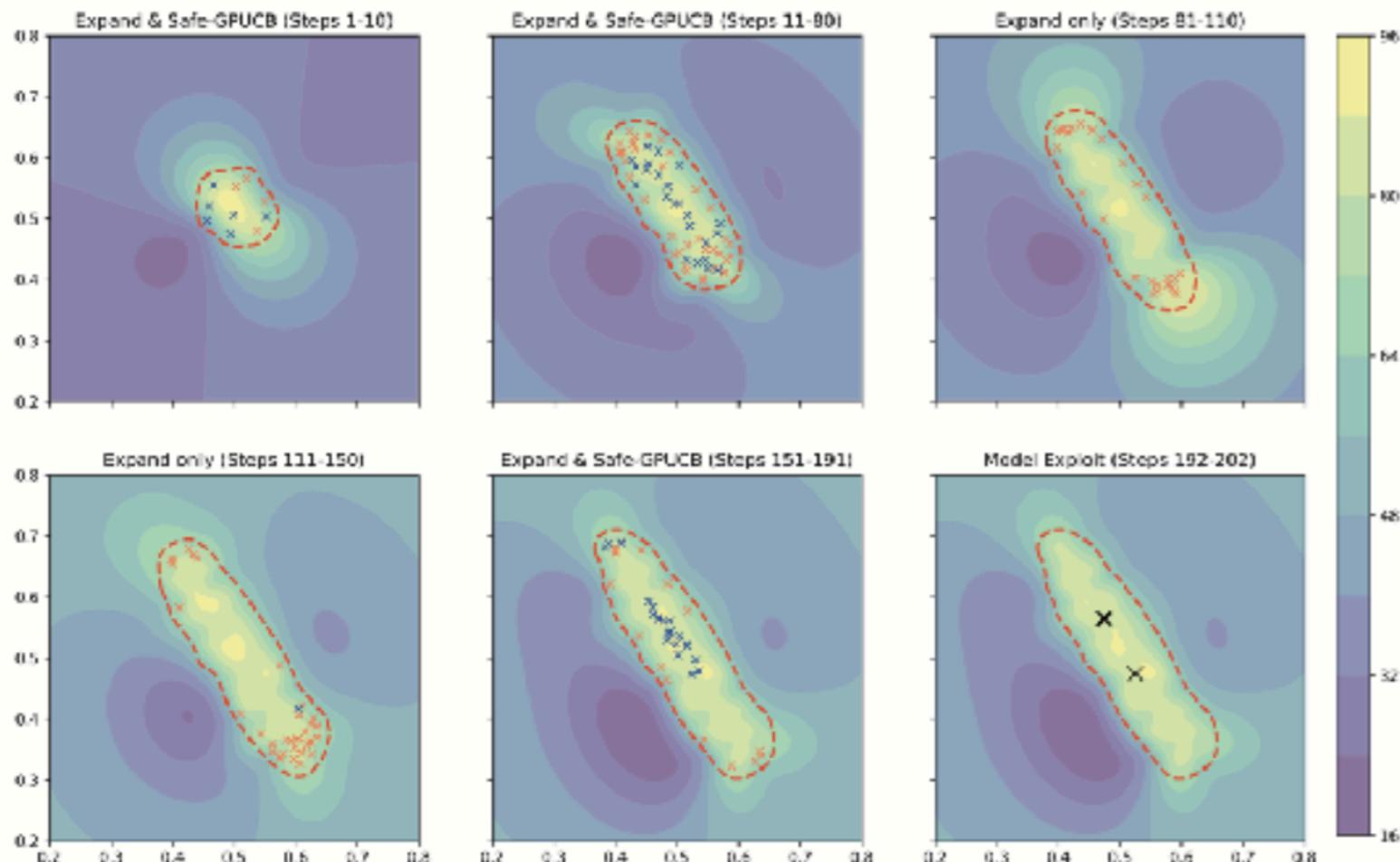


Safe Bayesian Optimisation



- X are evaluation points, for each evaluation point the performance (e.g. FEL pulse energy) is measured and the model is updated
- Additionally, the safety function (e.g. losses recorded by various detectors) is evaluated and its model is also updated → taking into account the uncertainties of the safety function this defines the safe-set marked in green
- Combines both exploration and exploitation

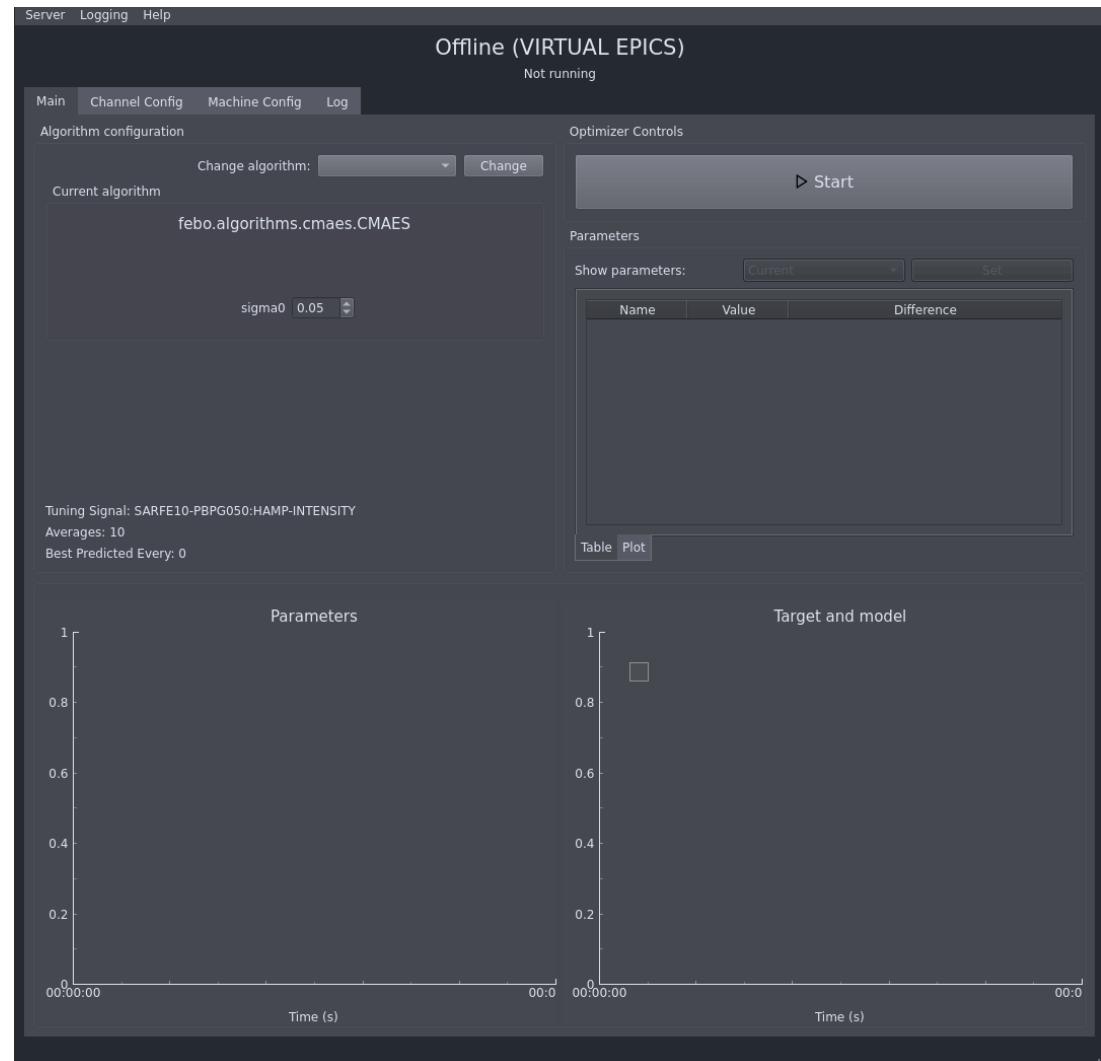
SwissFEL example



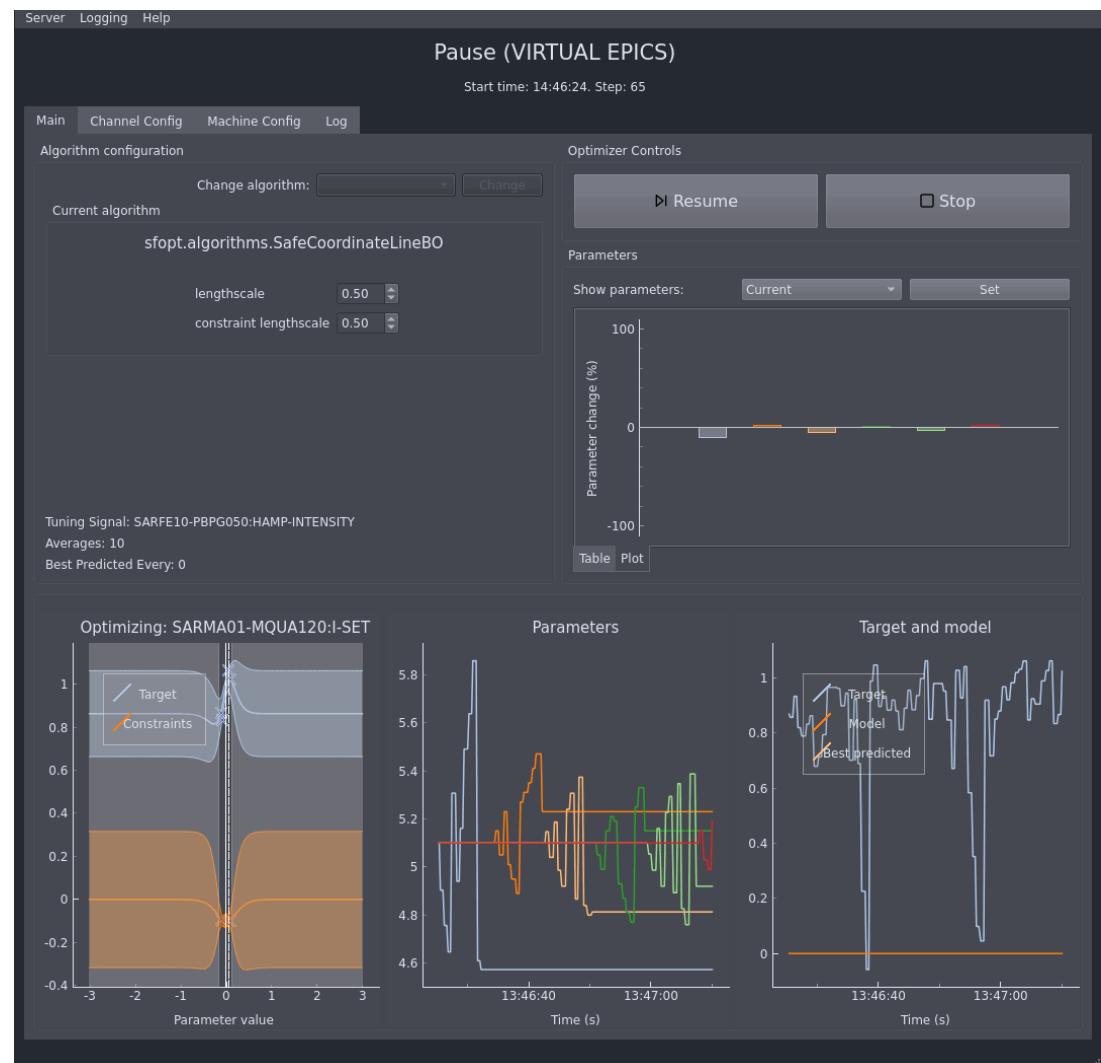
- Orange crosses are expanding steps, blue crosses are exploitation steps, red dashed line marks safe-set boundaries, contour plot shows model of the performance function (modeled with Gaussian processes)

Optimisation GUI

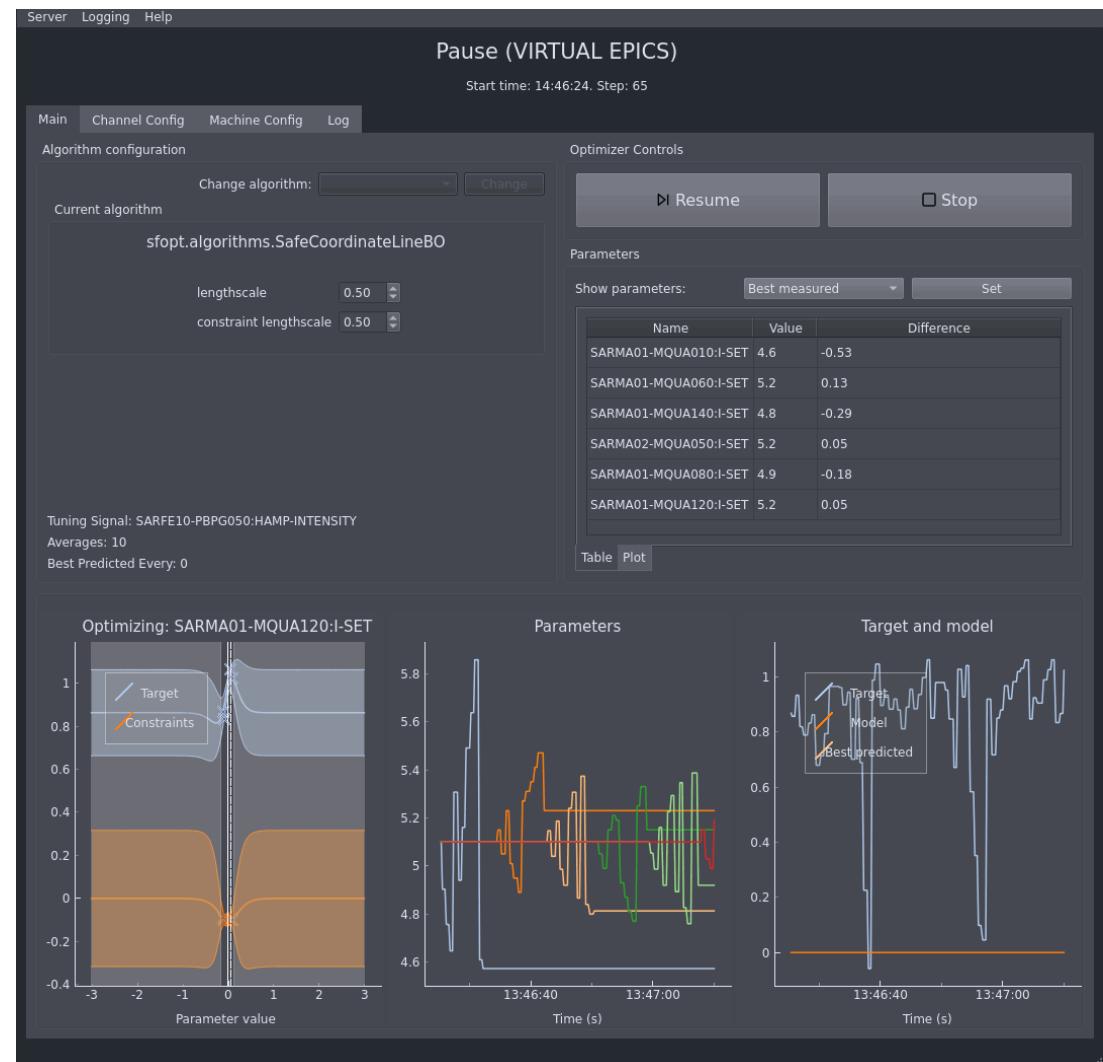
- Server application
 - Python
 - Optimiser runs on a server
 - client GUI through REST API
- Status data in EPICS
- Additional algorithms
 - Extremum seeking (CMA-ES)
 - Nelder Mead (Simplex)
 - Line Scan
 - Easy to implement more
- Few settings
- Machine related beam checks
(e.g. good-flags from the
feedbacks, beam detection)
- Live plotting & analysis
- Accelerator independent
 - used at SwissFEL, HIPA, PiE1



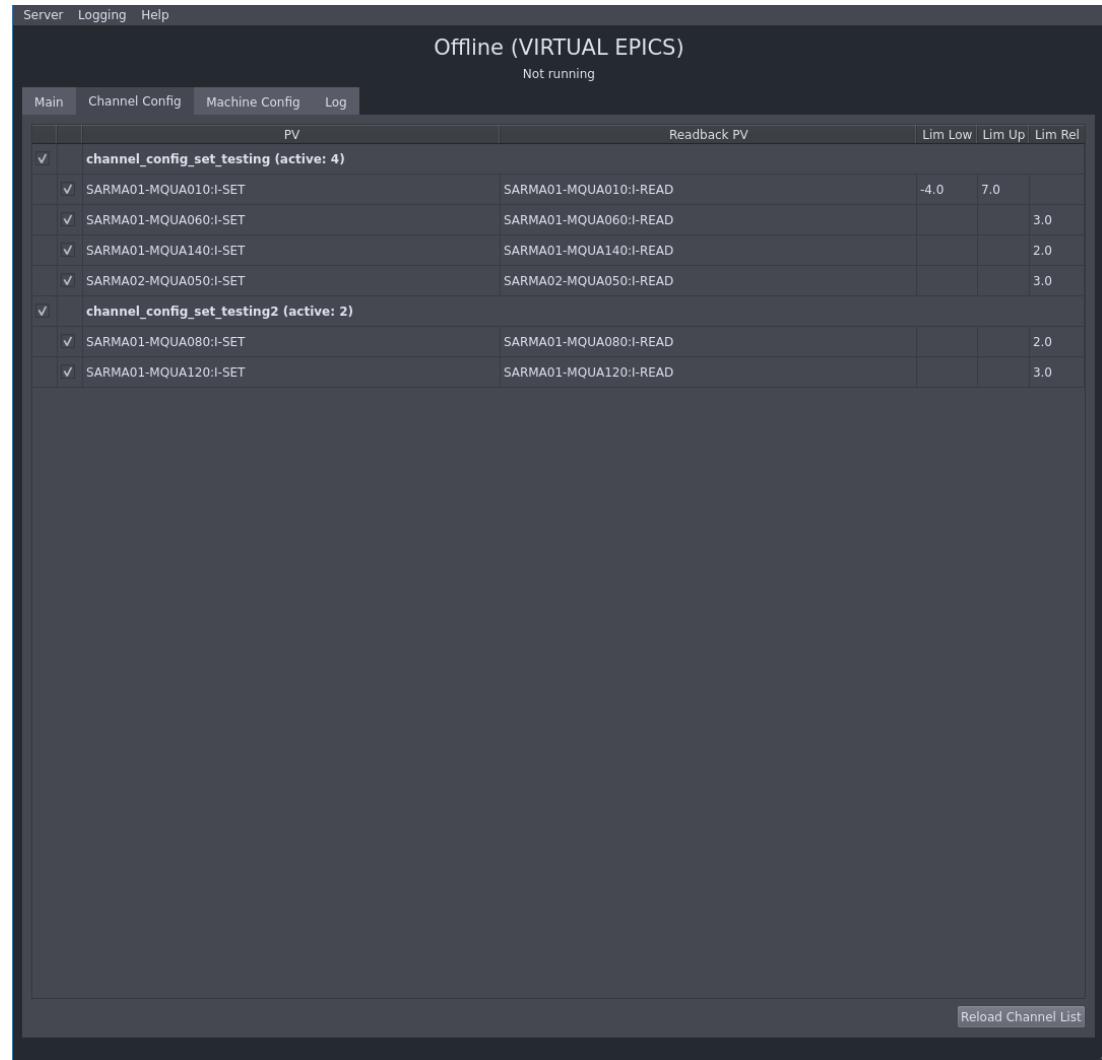
- Possible to pause
 - Load different results
 - Set machine to these states
- Resume



- Another example:
CMA-ES
- virtual mode (“virtual EPICS”) available
for testing



- Easy selection of the parameters (channels) to tune during the optimisation.
- Individual limits can be set for each channel
 - machine check
 - optimisation constraint



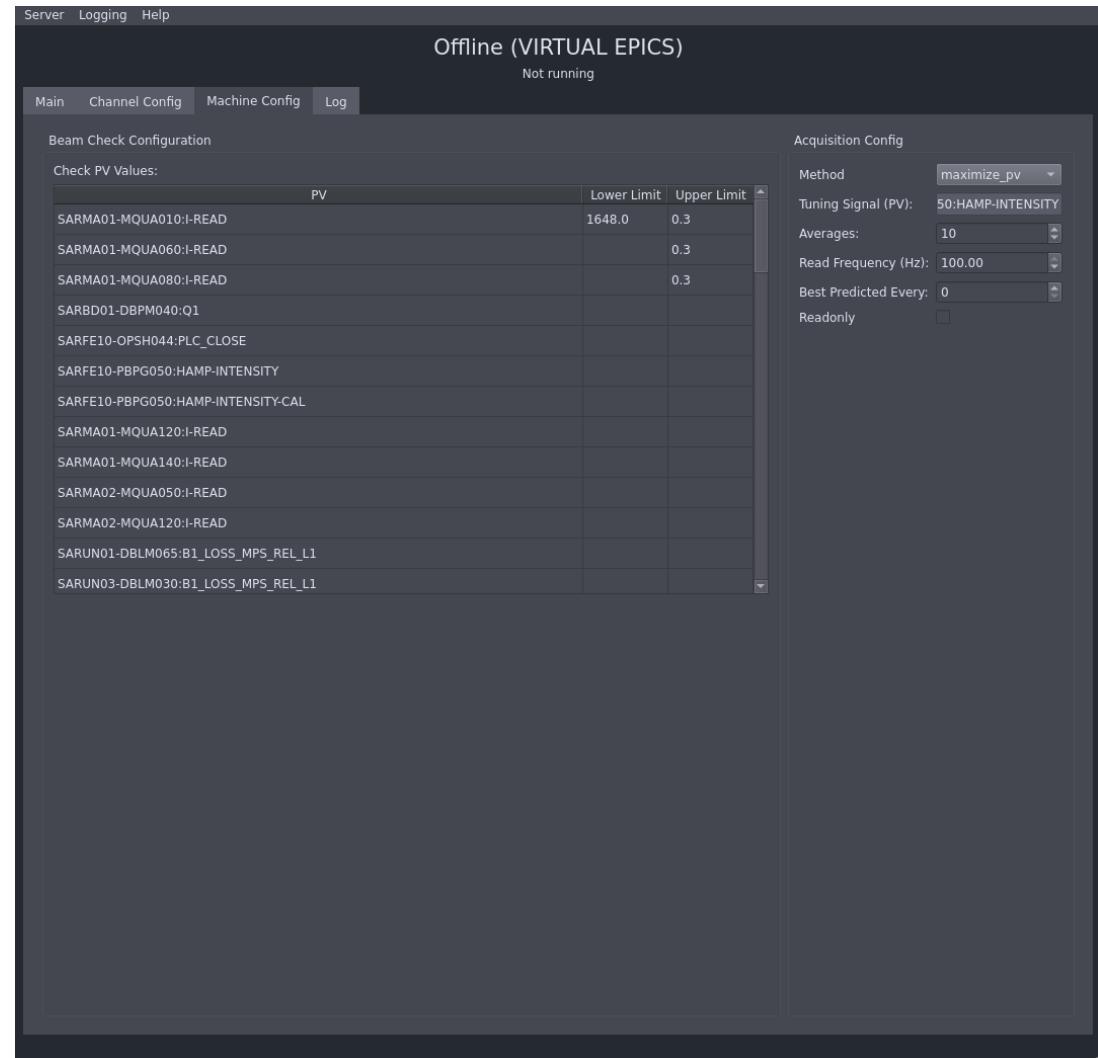
The screenshot shows a software interface titled "Offline (VIRTUAL EPICS)" with the status "Not running". The top menu bar includes "Server", "Logging", and "Help". Below the menu is a tab bar with "Main", "Channel Config" (which is selected), "Machine Config", and "Log".

The main area displays a table of channels under the heading "Channel Config". The table has columns for "PV", "Readback PV", and "Lim Low", "Lim Up", "Lim Rel". There are two sections listed:

- channel_config_set_testing (active: 4)**
 - SARMA01-MQUA010:I-SET (Readback PV: SARMA01-MQUA010:I-READ, Lim Low: -4.0, Lim Up: 7.0, Lim Rel: 3.0)
 - SARMA01-MQUA060:I-SET (Readback PV: SARMA01-MQUA060:I-READ, Lim Low: , Lim Up: 3.0, Lim Rel: 2.0)
 - SARMA01-MQUA140:I-SET (Readback PV: SARMA01-MQUA140:I-READ, Lim Low: , Lim Up: 2.0, Lim Rel: 3.0)
 - SARMA02-MQUA050:I-SET (Readback PV: SARMA02-MQUA050:I-READ, Lim Low: , Lim Up: 2.0, Lim Rel: 3.0)
- channel_config_set_testing2 (active: 2)**
 - SARMA01-MQUA080:I-SET (Readback PV: SARMA01-MQUA080:I-READ, Lim Low: , Lim Up: 2.0, Lim Rel: 3.0)
 - SARMA01-MQUA120:I-SET (Readback PV: SARMA01-MQUA120:I-READ, Lim Low: , Lim Up: 3.0, Lim Rel:)

At the bottom right of the table area is a button labeled "Reload Channel List".

- Beam limits are checked before moving to the next step
 - Stability conditions
- Possible to investigate and go back to each previous step



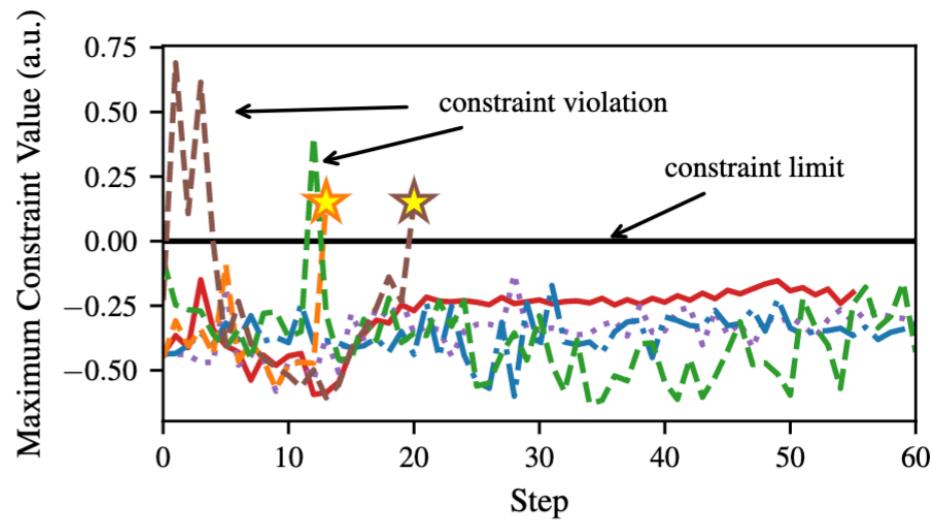
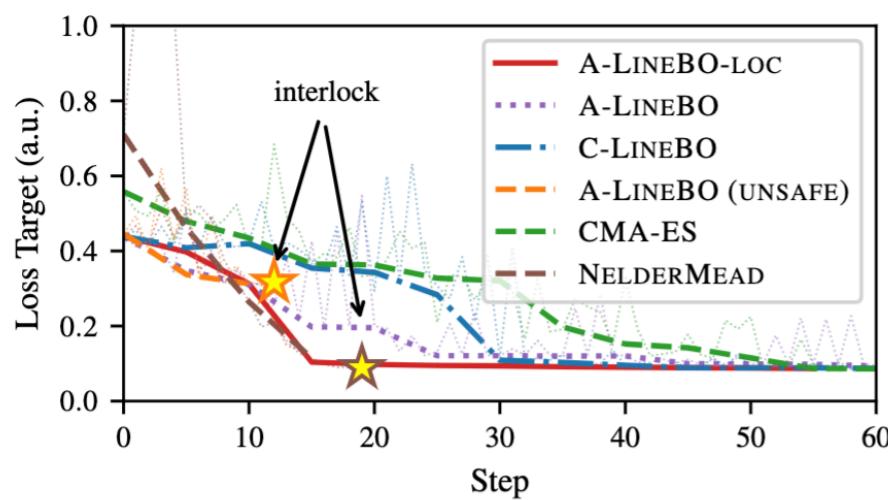
Results

Variants

- Variants:
 - C(oord)-LineBO: Find each parameter target optimum individually.
 - A(scent)-LineBO: Move each parameter to find the “best-direction” and then search for the best point in that direction.
 - *-Loc: “Localised” Maximum step size is 10% of the available range.
 - CMA-ES: Similar to swarm optimisation.
 - Does not have safety constraints.
 - Standard well developed global optimisation evolutionary algorithm.
 - Used here as baseline to compare the rest of the method

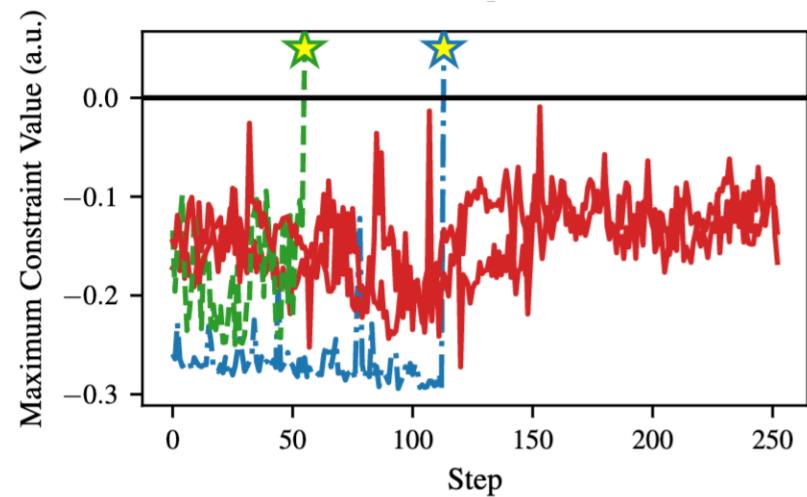
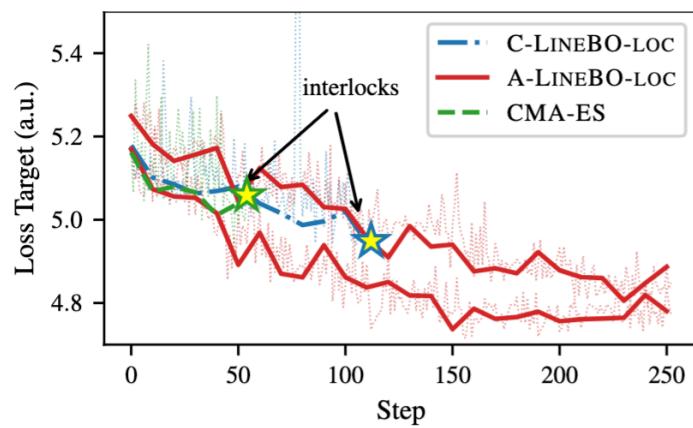
- Objective: Minimize combined losses (M4HIPA:VERL:2)
 - weighted average of 60 loss monitors
- Tuning Parameters: 5-16 Quadrupole Magnets
- Constraints: About 200 loss monitors with individual warning levels
- Beam checks:
 - Beam on
 - Orbit feedbacks stable
- Effective control rate: ~ 5 seconds / step

- Low Intensity with manually detuned machine
- 5 parameters



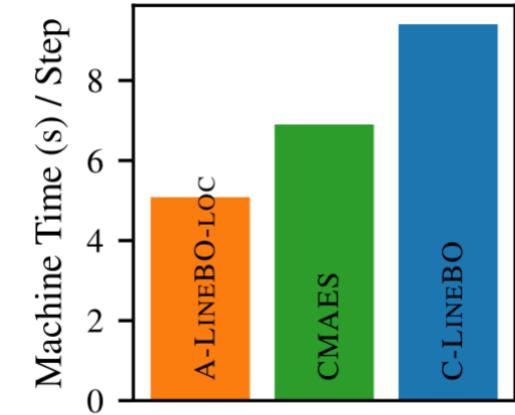
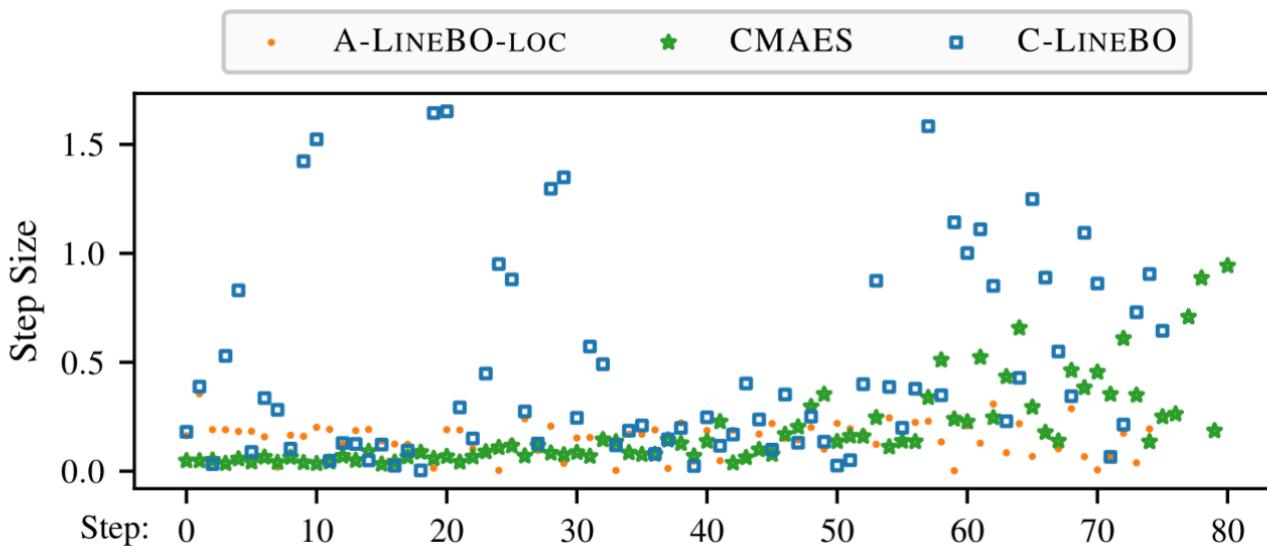
- safe variants competitive
- non-safe methods create interlocks (violate constraints)
 - proves constraints are working

- High intensity
- 16 parameters

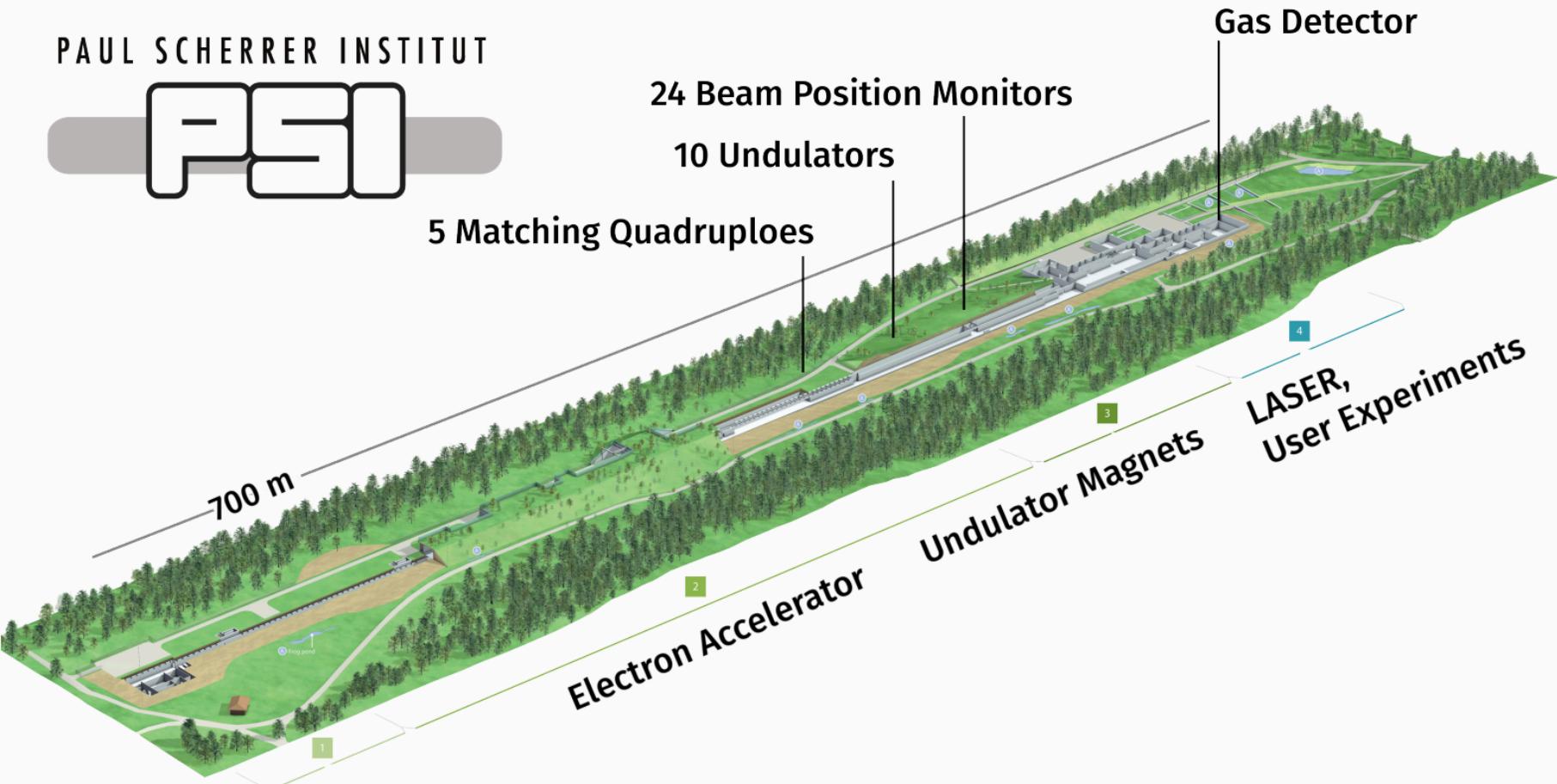


- Also competitive and safe at high current

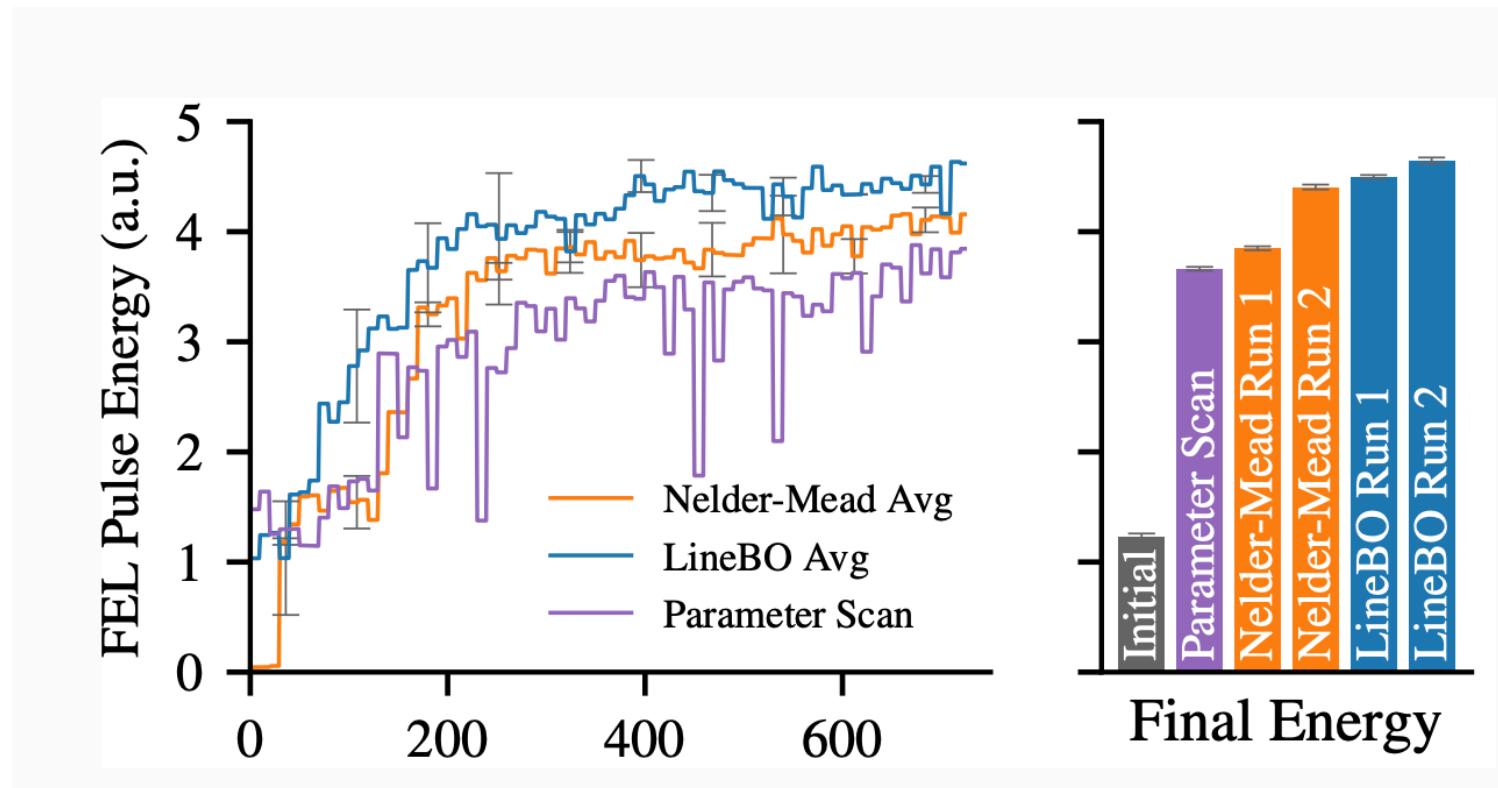
- Localised option (Maximum step size is 10% of the available range)
 - faster to set
 - at HIPA we don't set parameters instantly
 - quicker for feedbacks to stabilise
 - similar solution



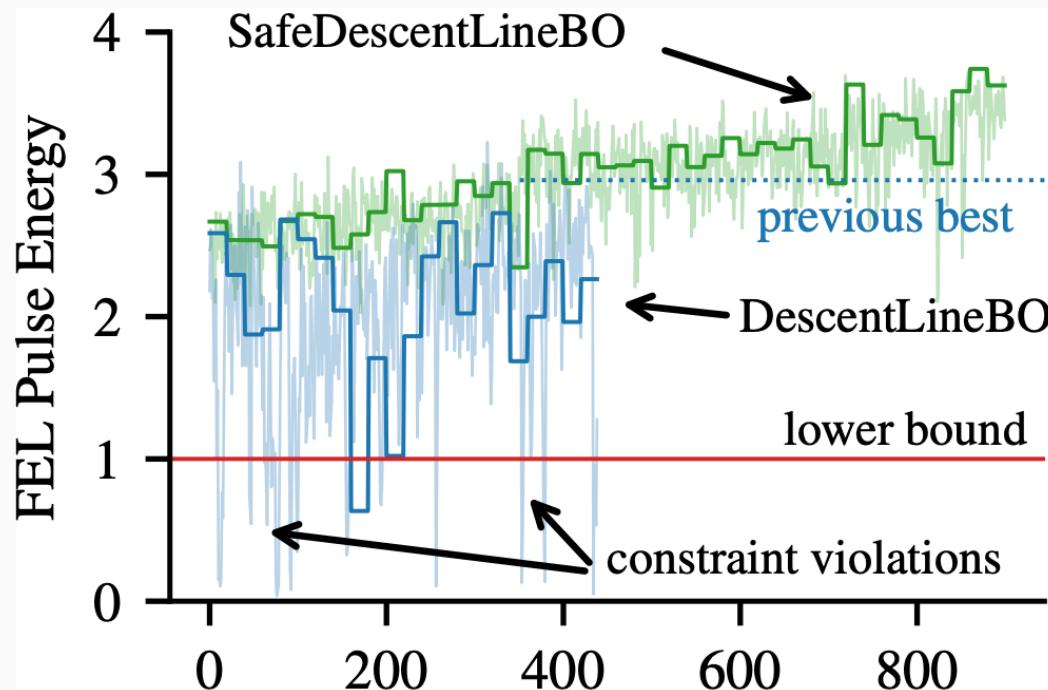
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- Objective: Shot by shot FEL intensity
- Tuning Parameters (39): Quadrupole Magnets, Beam position, Undulator settings
- Constraints:
 - Lower bound on intensity
 - Loss monitors
- Effective control rate: ~ 0.5 seconds / step



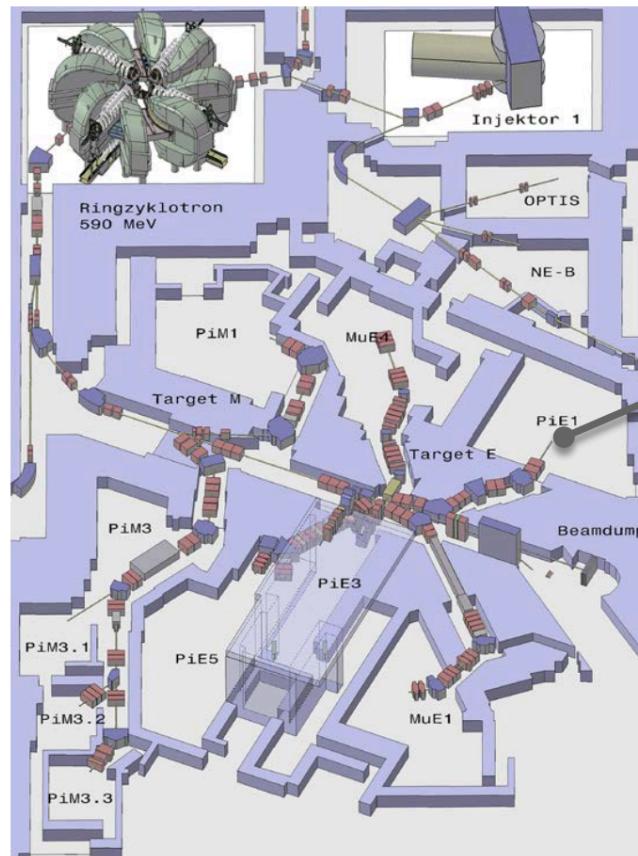
- Bayesian Optimisation shows best result



- Constraint on minimum energy improves average and even optimum

MIXE - PiE1

- Elemental composition analysis with negative muons
 - non-destructive and depth sensitive
 - Implant muons at different depths by selecting muon energy



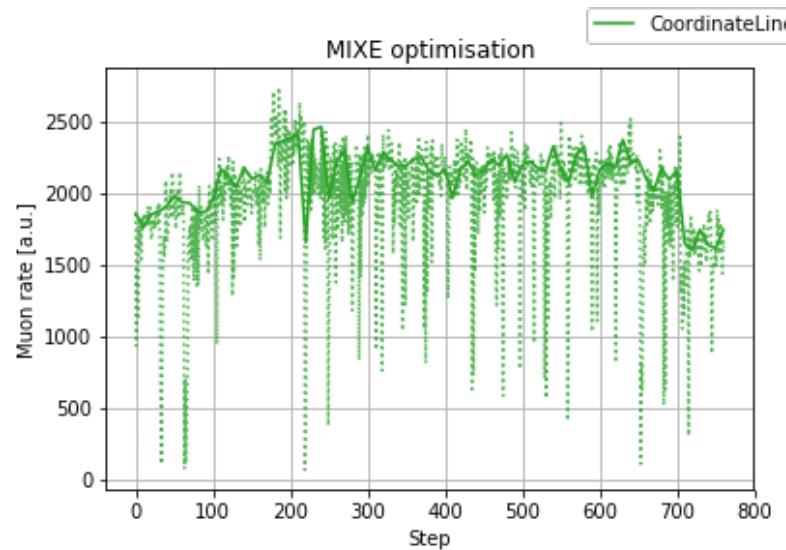
Courtesy Alex Amato

MIXE - PiE1

- probe scanned at several layers
 - different muon momenta about every hour
 - —> tuning manually every hour(!)
- Objective: muon rate (ZPIE1CNT:INP3)
 - average rate —> reduce exploration
- Parameters: 20 quads, magnets and spin rotator (same as in setpoint)
 - 'ASY51:SOL:2', 'ASL51:SOL:2', 'ASK51:SOL:2', 'SPIN2:SOL:2', 'QSN54:SOL:2',
'QSN55:SOL:2', 'QSN56:SOL:2', 'QTH51:SOL:2', 'QTH52:SOL:2', 'QTB51:SOL:2',
'QTB52:SOL:2', 'QSL51:SOL:2', 'QSL52:SOL:2', 'QSL53:SOL:2', 'QSL54:SOL:2',
'QSE51:SOL:2', 'QSE52:SOL:2', 'QSN51:SOL:2', 'QSN52:SOL:2', 'QSN53:SOL:2'
- Constraints: none
 - Could set a minimum muon rate as constraint
- Machine checks
 - Beam on (MHC4 current monitor > 1800)

MIXE - PiE1

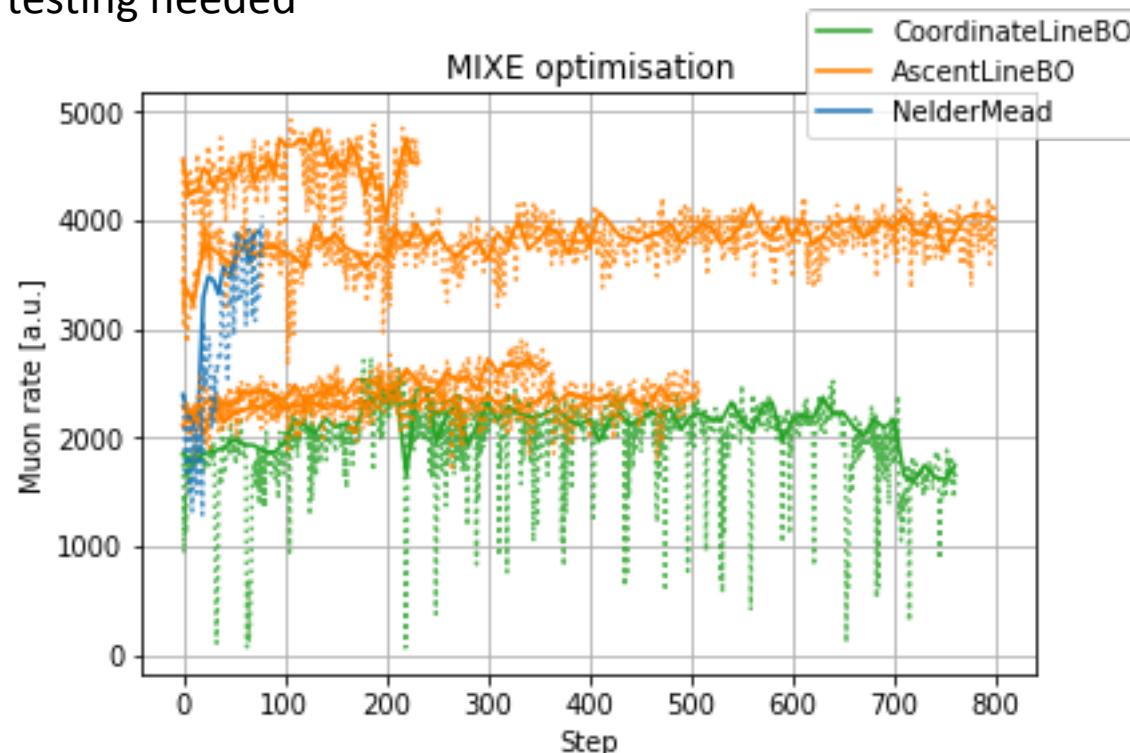
- Tested 13 December 2021 w Lars Gerchow
- First try: CoordinateLine (one parameter line scan)



- Slow noisy progress
 - Too many evaluations per line scan
- Sometimes signal went down
 - Noise parameters might have set wrong
 - Too much exploration?
- CoordinateLine slow with many parameters that are not orthogonal

MIXE - PiE1 - AscentLine

- AscentLine (multiple parameters at once)
 - Steady constant increase, even small increases after one hour
 - Note that expected muon rate dependent on muon energy
 - NelderMead also promising result
 - More testing needed



Practicalities

- Every problem unique
 - Algorithms and parameters should be benchmarked for optimal results
- Results stored
 - Analysis framework available (Jupyter notebook)
- Similar tools exist (OCELOT - DESY, SLAC)
- Possible improvements
 - Installation tricky
 - More automatisation
 - Operator is still needed
 - More robust
 - CPU usage and memory usage large
 - especially for long optimisation runs

Example configuration - PiE1

- api

 - pie1.yaml

```
sfopt.environment:
  tuning_signal_pv: ZPIE1CNT:INP3
  outlier_level: 3.0
  outlier_detection: true
  num_repetitions: 10
sfopt.interface:
  set_max_trials: 600
  set_tolerance: 0.05 # sets tolerance of difference of SOL to IST value
  frequency: 10.0 # machine read/set interval time
sfopt.checks:
  min_value_pvs:
    MHC4:IST:2: 1800.
```

 - algorithm_ascent-linebo.yaml

```
algorithm(gp:
  beta: 1.
  noise_std: 40.0
  kernel: rbf
  scale: 4000.0
  bias: 40.0
  lengthscale: 0.3
algorithm.constraint_gp:
  beta: 1.
  noise_std: 0.1
  kernel: matern52
```

 - algorithm_neldermead.yaml

```
algorithm.nelder_mead:
  contraction_factor: 0.8
  initial_stepsize: 0.1
  restart_threshold: 0.0
  adaptive: True
```

- config

 - channel_config_set.txt

```
pv,lim_low,lim_high,lim_rel,wait_const,wait_linear,wait_min,wait_max,active,step_size
ASY51:SOL:2,,,0.5,,,,,1,
ASL51:SOL:2,,,0.5,,,,,1,
ASK51:SOL:2,,,0.5,,,,,1,
SPIN2:SOL:2,,,10.0,,,,,1,
QSN54:SOL:2,,,2.0,,,,,1,
```

Next steps

- Experiments planned end April (HIPA startup commissioning phase)
 - Systematic algorithm comparison
 - MIXE First two weeks of May

Conclusions & References

- Ready to use powerful automated tool
 - Very flexible
 - https://gitlab.psi.ch/ext-kirschner_j/swissfel-opt
- Results shown on several beamlines
- More tests in planning at PiE1 - MIXE
- Please contact me if interested

- Papers:
 - Tuning Particle Accelerators with Safety Constraints using Bayesian Optimization -
Phys. Rev. Accelerator and Beams (2022)
 - [Bayesian optimisation for fast and safe parameter tuning of SwissFEL - FEL 2019](#)
 - [Adaptive and Safe Bayesian Optimization in High Dimensions via One-Dimensional Subspaces - ICML 2019](#)
- Presentation:
 - [Bayesian Optimization for Safe & Efficient FEL Tuning at SwissFEL & Loss Optimisation at HIPA , N. Hiller, OWLE seminar \(2020\)](#)

Many thanks to

- Jaime Coello de Portugal (ex-GFA)
- Johannes Kirschner (ETHZ)
- Lars Gerchow (NUM)
- Nicole Hiller (GFA-operation)



CMA-ES Algorithm

- Covariance Matrix Adaptation – Evolution Strategy.
- Similar to swarm optimization.
- Does not have safety constraints, we used a very small step size.

