• Expt set-up

user [name]	stores the name of user in each file
sample [sample name]	stores the name of the sample in each file
title [scan title]	gives the scan the title
$mode \ [bi \text{ or } tas]$	bi for cradles tas for gonios
scan mode [timer or monitor]	determines the scan counting mode

• Motors and Angles

som or a3	returns the value of the sample table
stt or $a4$	returns the position of the detector
phi or sgu	returns the value of the upper gonio
chi or sgl	returns the value of the lower gonio
four	returns all four current angle positions

• Driving and Counting

$ \begin{array}{l} dr \; [motor] \; [value] \\ dr \; [motor1] \; [value1] \; [motor \; n] \; [value \; n] \\ stop \\ co \; [mn \; or \; ti] \; [counts \; or \; seconds] \end{array} $	drives to postion [value] drives all n motors stops all motors and scans count for 'counts' of monitor counts or 'seconds' of time
dr opa [value]	drive sgu and sgl to give out of plane angle='value' (<15°) It is assumed that the instrument is aligned such that: som 0: the upper gonio is parallel to the beam stt 0: the detector is in the direct beam.

• Batch files

batchpath	returns the current path
projectdir [pathName]	changes the path to 'pathName'
batchrun [fileName]	runs the file, found in the path with the name 'fileName'

• Scans

Center scan

cscan [motor] [pos] [step size] [# of steps each side of pos] [count time]

Step scan:

sscan [motor] [start pos] [end pos] [# of steps + 1] [count time]

sscan [motor1] [start pos1] [end pos1] [motor2] [start pos2] [end pos2] [# of steps + 1] [count time]

Cone scan:

[scan type] oma [start pos] [end pos] [# of steps + 1] [count time]

• Centering

peak	Finds the center of your last scan
center	Moves to the center of your last scan
centerref [count time]	Centers the reflection in all of the angles

cell ([a b c $\alpha \beta \gamma$]) prints or (updates) the cell parameters spqrp ([A a a a]) prints or (updates) the space group calctth [h k l] calculate two theta for the given 'h k l' calcang [h k l] calculate all angles for the given 'h k l' calchkl ([stt som sgu sgl]) calculate h k l for the current or (given) angles $ub ([x_{11} x_{12} x_{13} x_{21} x_{22} x_{23} x_{31} x_{32} x_{33}])$ prints or (updates) the ub matrix recoubrecovers previous ub matrix calcub [xxxx] [xxxx] ([xxxx]) calculates a ub matrix using the reflections 'xxxx' from the reflection list, see reflist2 or (3) reflections can be used • Reference reflections reflist prints the current list of reflections refclear clears the list of reflections refdel [xxxx] delete the reflection with the ID 'xxxx' from list refhkl [xxxx] [h k l] change the hkl values of reflection 'xxxx' to 'h k l' refadd idx [h k l] add a reflection to the list with index 'h k l' refadd ang ([stt som chi phi]) adds the current or (given) motor positions *refadd idxang* [h k l] ([stt som sgu sgl]) adds the current or (given) motor positions for reflection with index 'h k l' refang [xxxx] ([stt om chi phi]) adds the current or (given) motor positions at position 'xxxx' refsave [fileName] saves the reflection list to 'fileName' refload [fileName] loads a stored reflection list from 'fileName' index the current reflection list with refindex the current ub matrix where indices are rounded to the next integer

• Instrument set-up

list [motor] gives all info and commands associated with a motor

• To restart six

At the command line: >> killsics >> startsics >> exit Log back in...