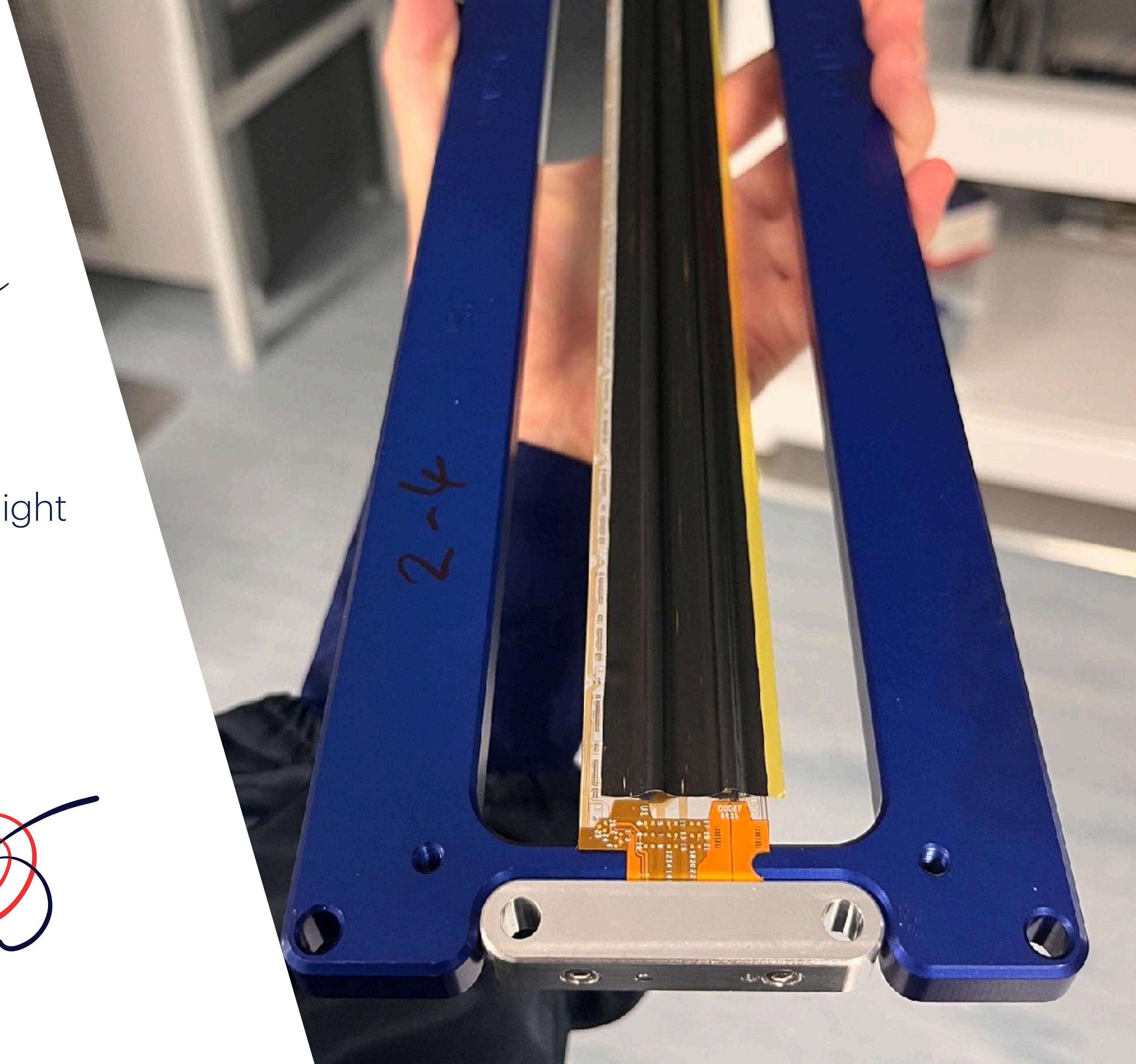


Ultralight UD structures for Mu3e pixel detector

Ashley McDougall, Adam Lowe, Alex Knight
on behalf of the Mu3e collaboration

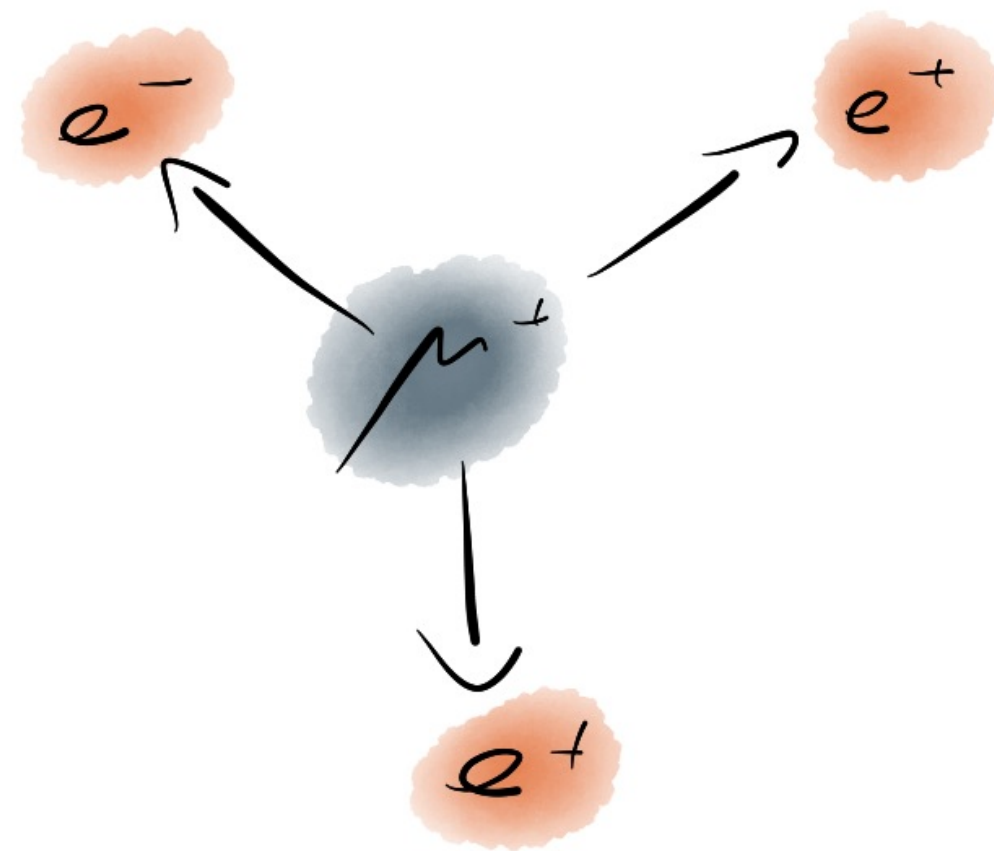
2nd DRD8 Collaboration Meeting
14.10.2025



The Mu3e experiment:

A. McDougall

Signal:



Use PIE5 beam-line at the Paul Scherrer Institute ([PSI](https://www.psi.ch)) near Zurich, CH



Mu3e inside
experimental
hall

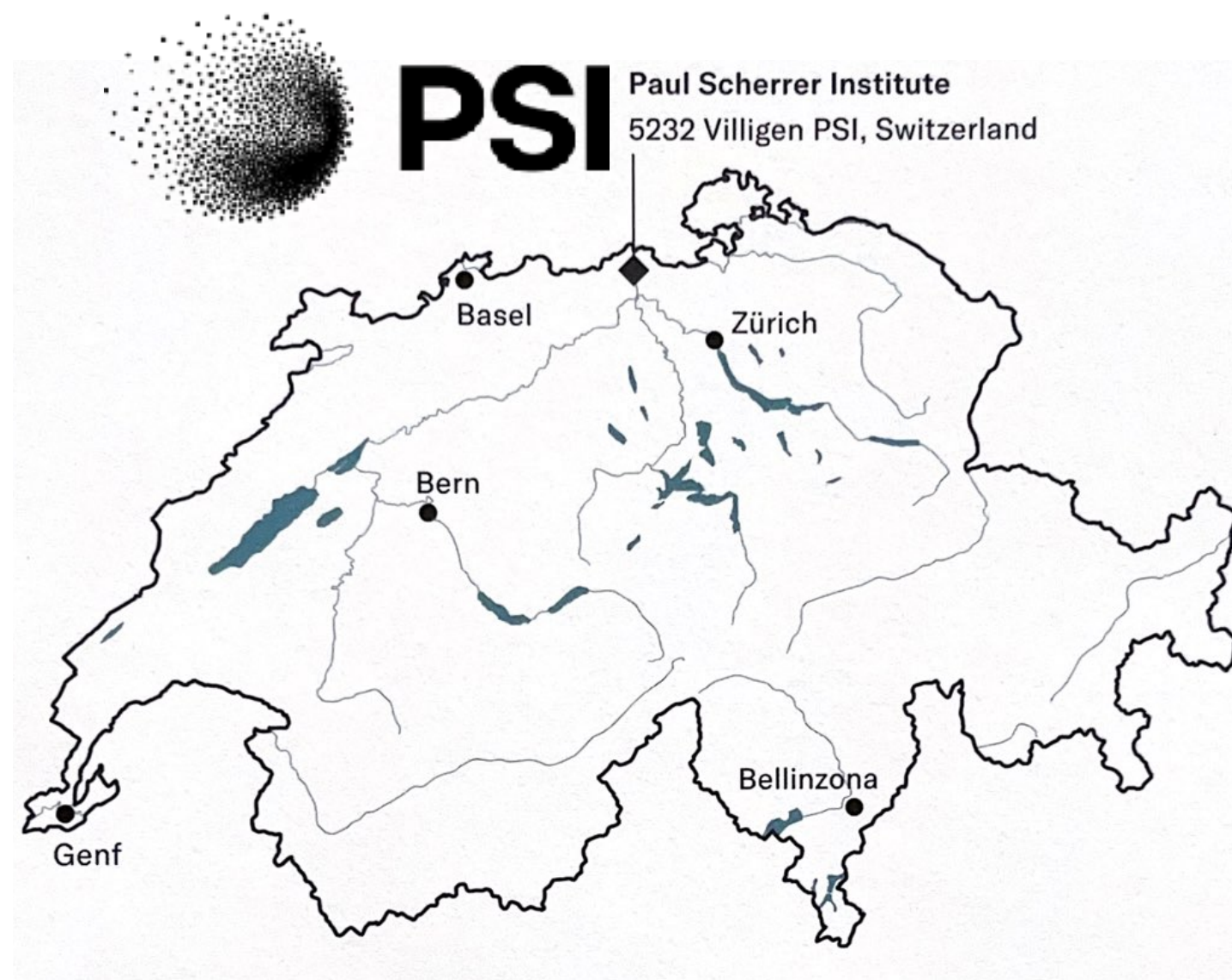
Collaboration $\mathcal{O}(100)$ people from 11 institutes (DE, UK, CH)

Physics data-taking in 2026 (Phase I):

- PIE5 provides muon rates up to **10^8 muons/s** to Mu3e
- Target sensitivity: **$\text{BR}(\mu \rightarrow eee) < 2 \cdot 10^{-15}$**
- 290 days minimum running time required to achieve target

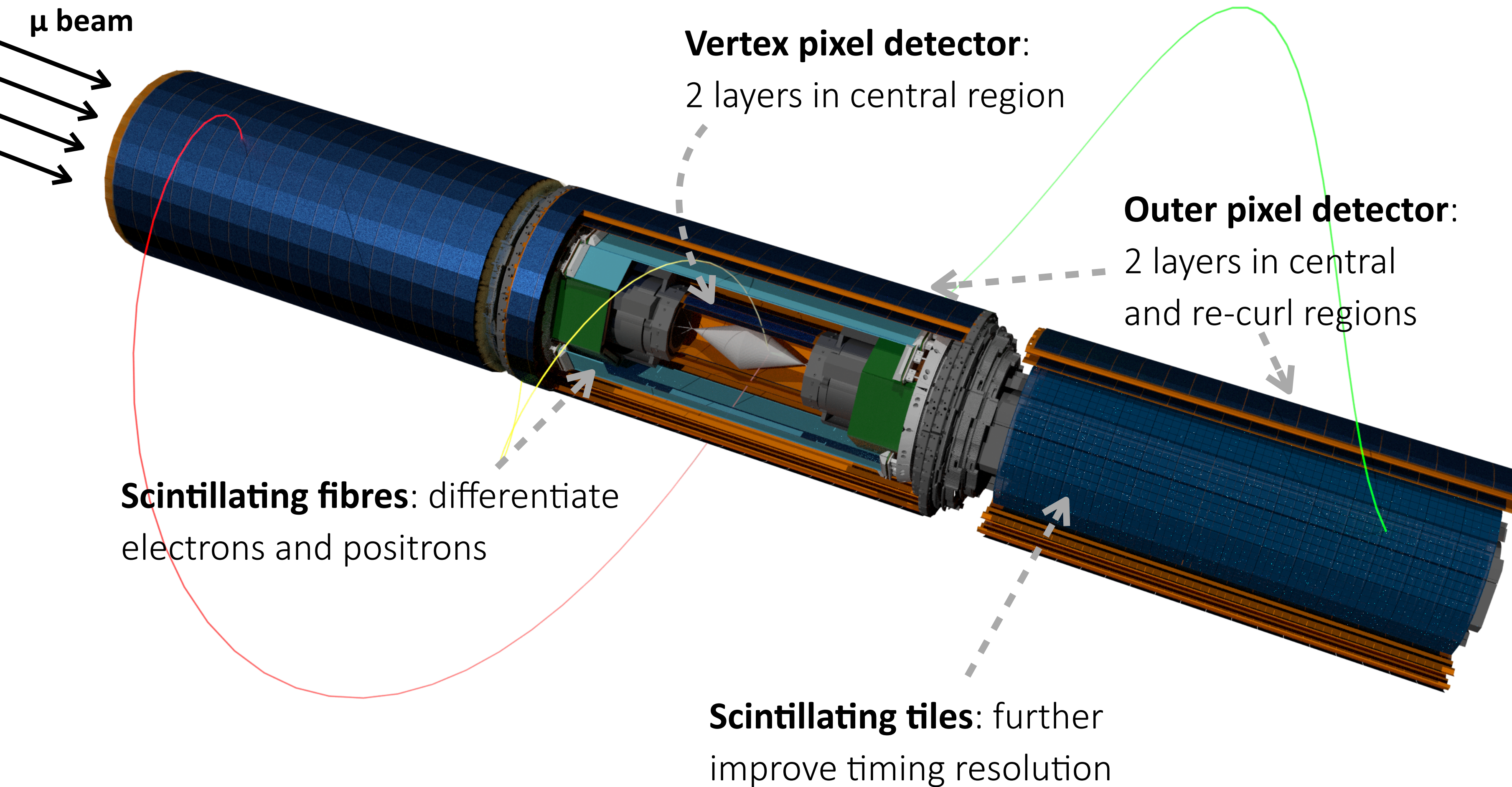
Phase II (> 2029):

- New High Intensity Muon Beam-line (HIMB), delivering up to **10^{10} muons/s**
- Target sensitivity: **$\text{BR}(\mu \rightarrow eee) < 2 \cdot 10^{-16}$**



Detector geometry: **1 central + 2 re-curl regions**

- Homogeneous solenoidal magnetic field $B = 1\text{T}$
- Multiple scattering dominated: Momentum resolution dependant on number of detector layers and thickness



Material budget a key factor!

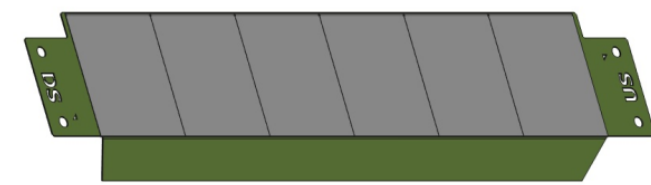
Tracking:

- 50-70 μm thick MuPix11 (Monolithic HV-CMOS) pixel sensors
- Per layer: $\sim 0.1\%$ X/X_0

Cooling:

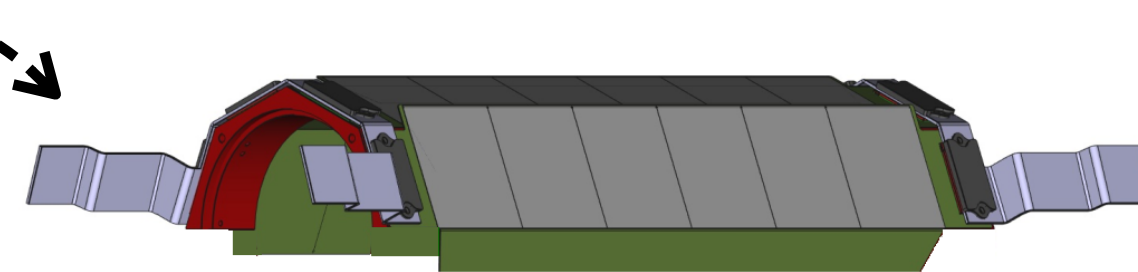
- Use gaseous He cooling (less dense compared to air)
- Flow rate 2 - 16 g/s

Vertex tracker:



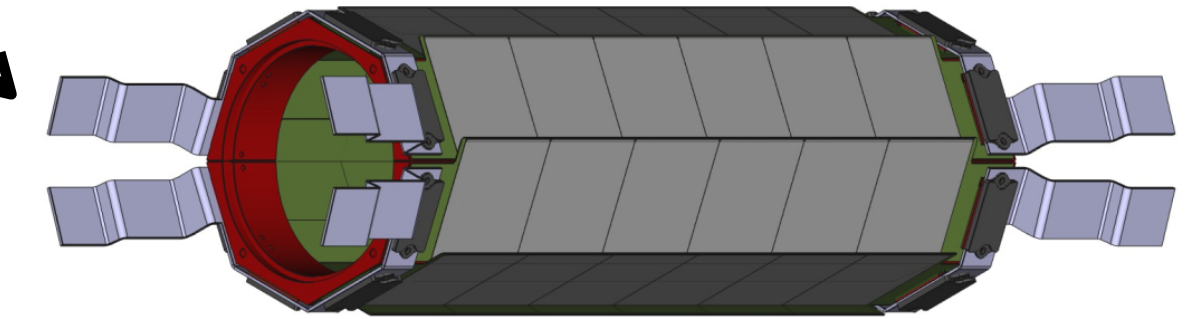
1 ladder = 6 x MuPix11 sensors

Ladder



1 module = 4 ladders

Module



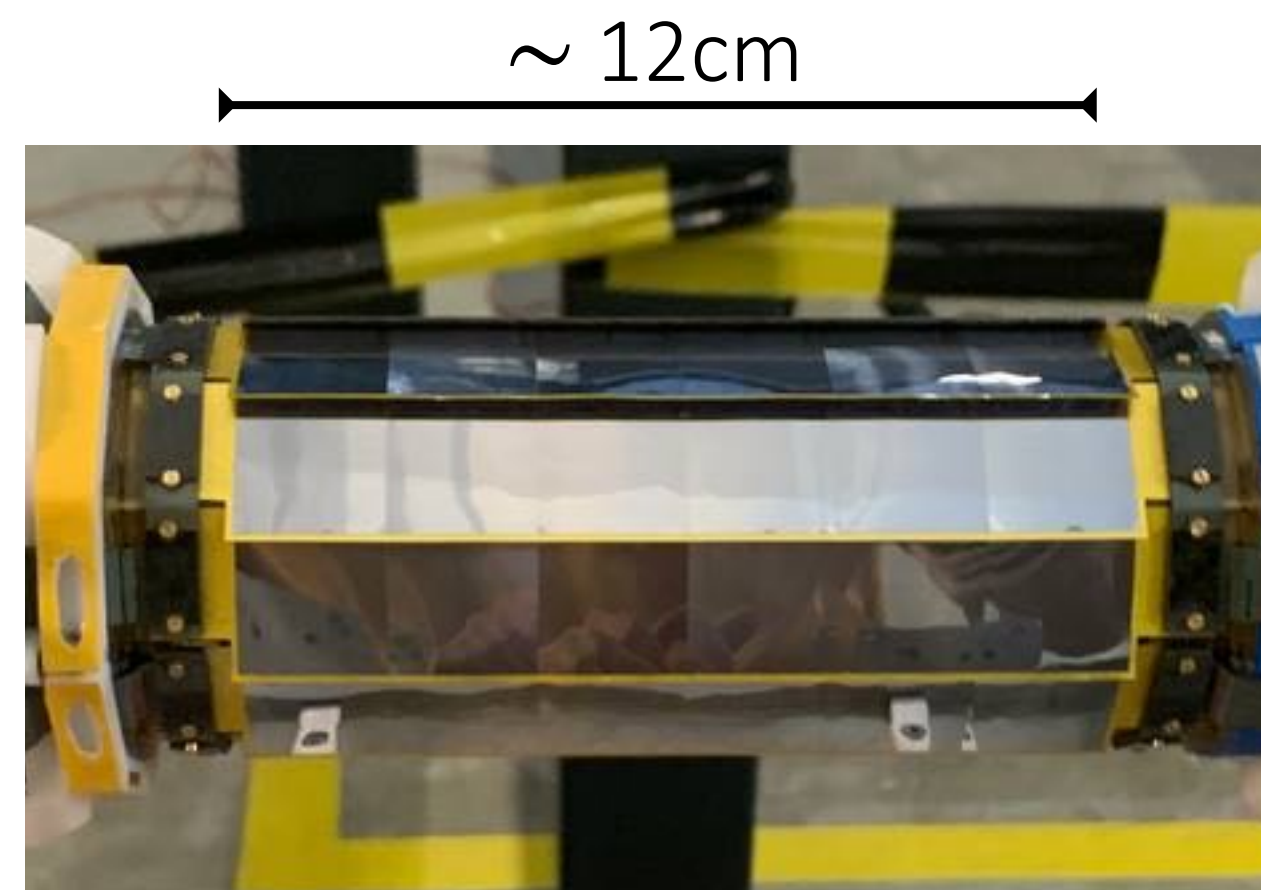
2 modules = 1 layer

Layer

Mechanical stability: primarily
from 3D folded nature of vertex detector

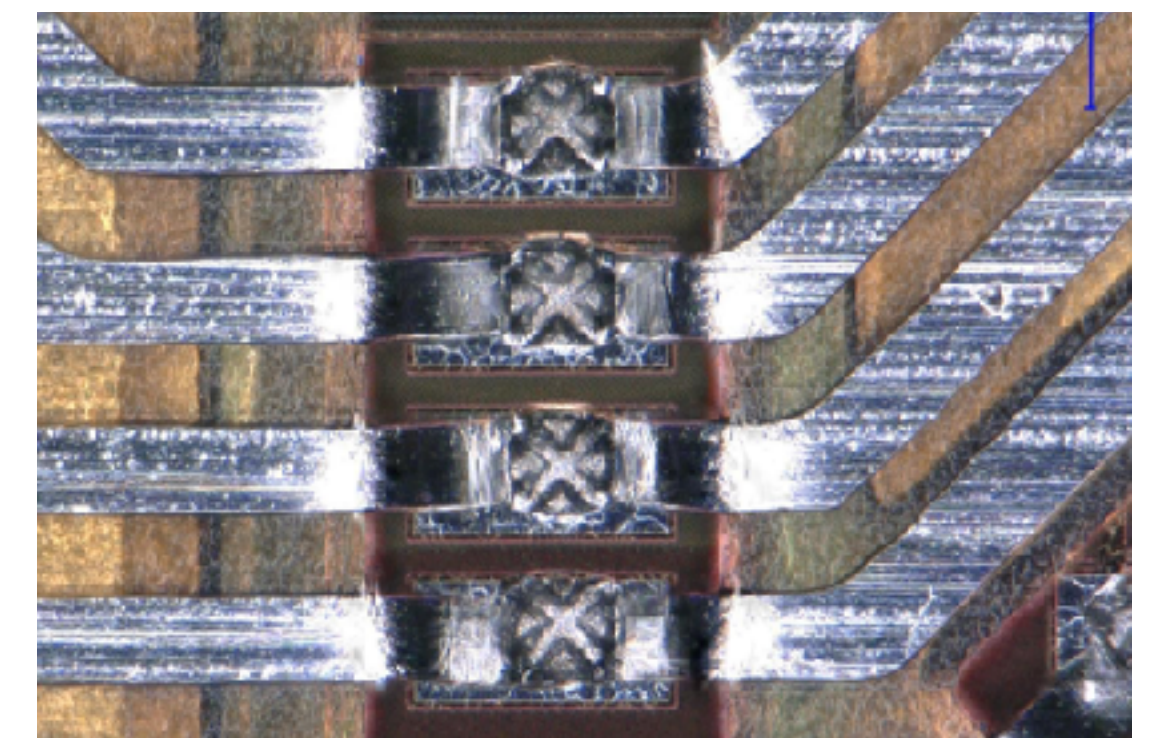
Comprised of:

- MuPix11 pixel sensors (50-70 μ m)
- Alu/kapton high-density interconnect (HDI), $\sim 70\mu$ m
 - Produced by LTU (Kharkiv, Ukraine)
- Electrically connected via spTAB connections



Vertex system ("version 1")
complete and installed in PIE5
for June 2025 beam-time.

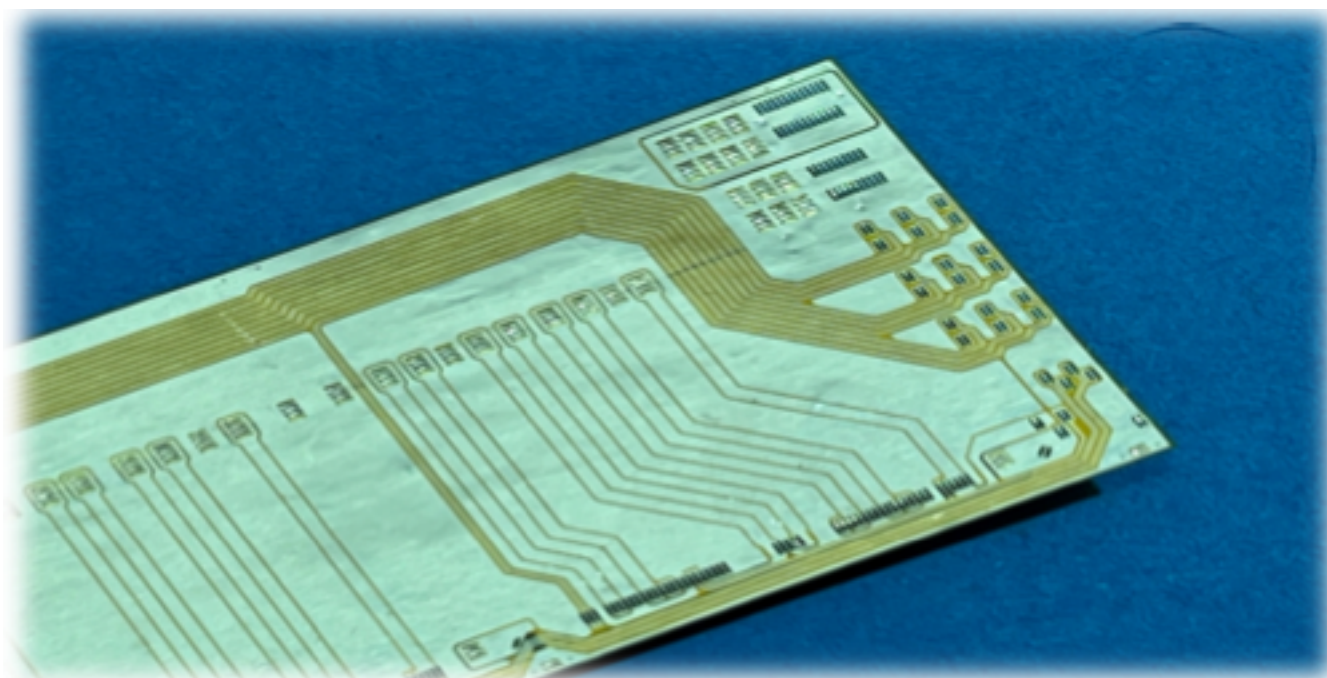
spTAB (single
point Tape
Automated
Bonding):



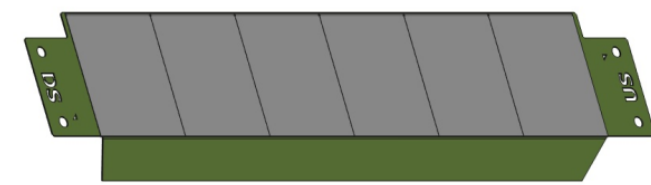
Outer pixel tracker:

- 17-18 x MuPix11 silicon sensors
- + additional mechanical support (stiffener)

HDI:

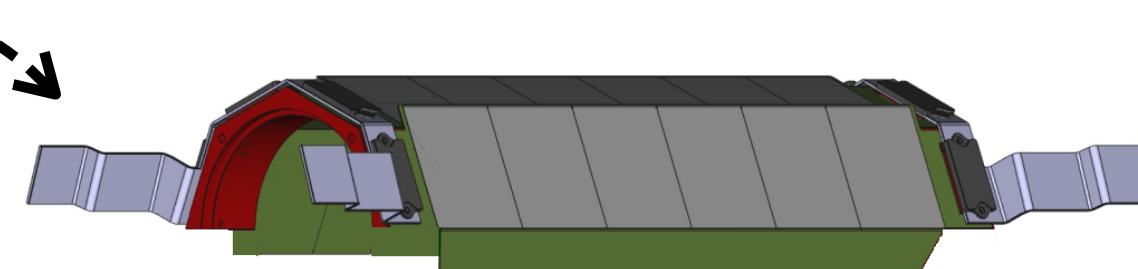


Vertex tracker:



1 ladder = 6 x MuPix11 sensors

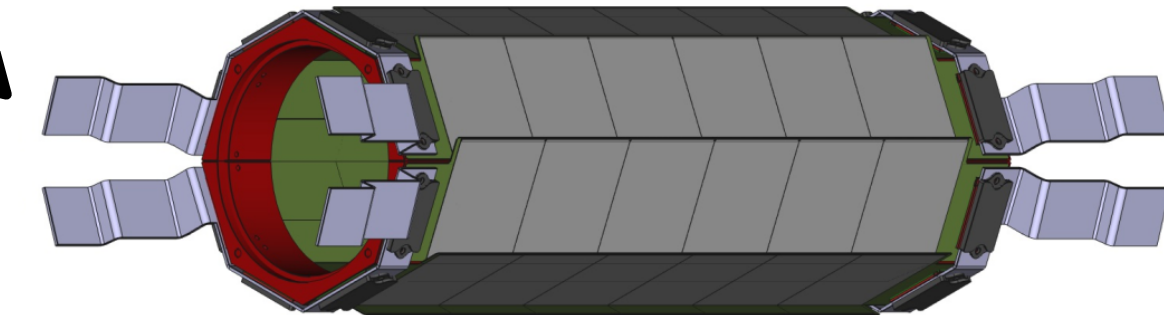
Ladder



Module

1 module = 4 ladders

Mechanical stability: primarily
from 3D folded nature of vertex detector

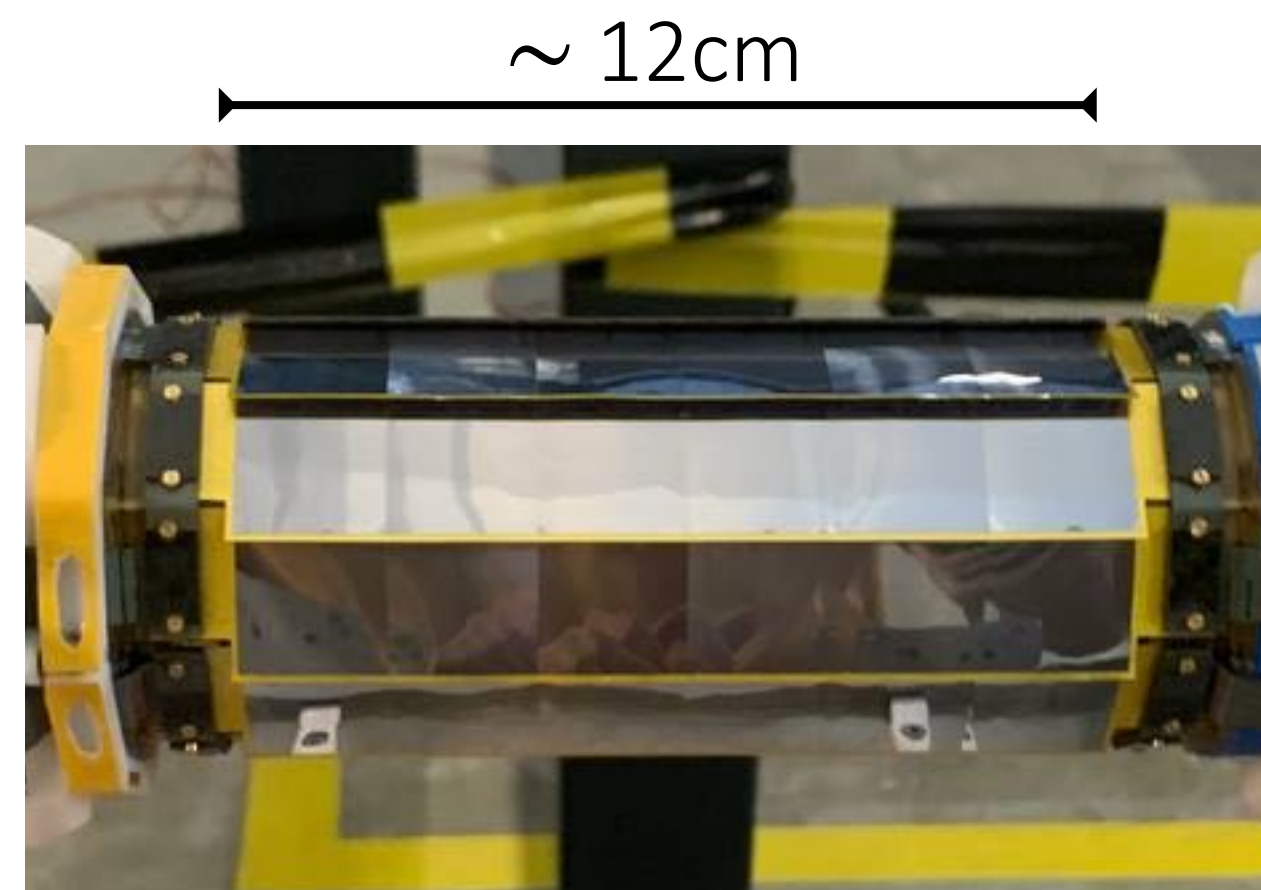


Layer

2 modules = 1 layer

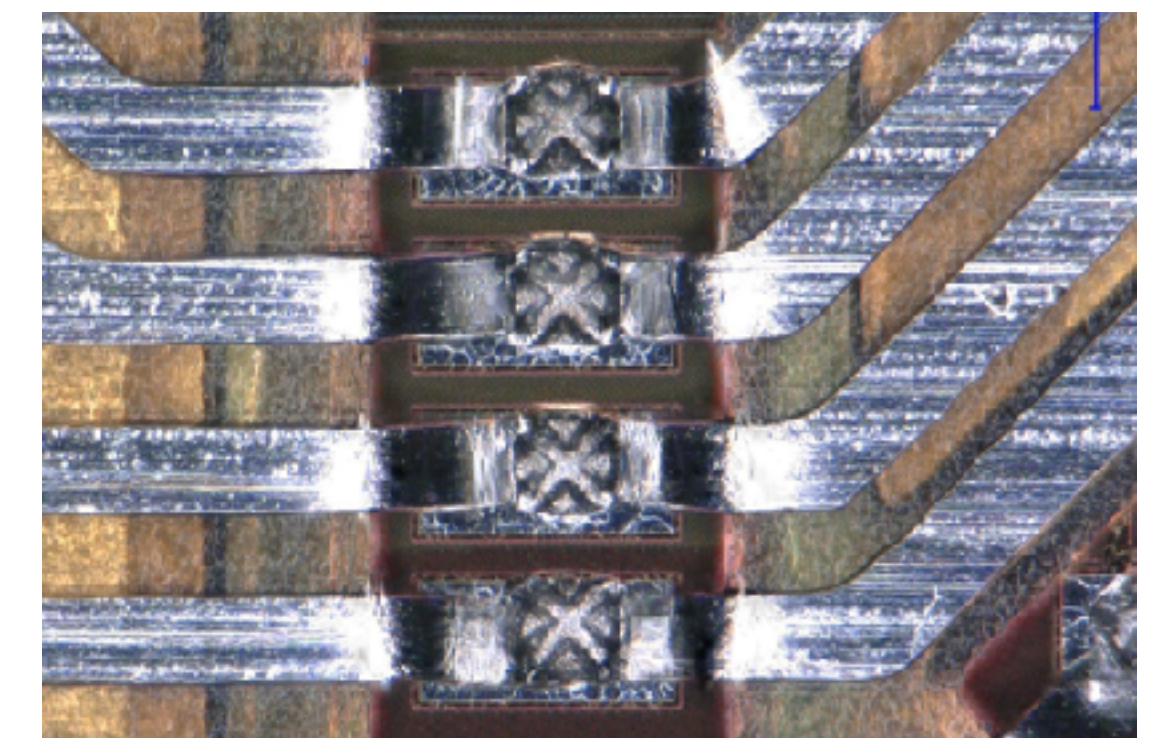
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Vertex system ("version 1")
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spTAB (single
point Tape
Automated
Bonding):



Outer pixel tracker:

- 17, 18 x MuPix11 sensors
- + additional mechanical support (stiffener)

Focus of this talk

Mechanical support provided by either:

Polyimide film:

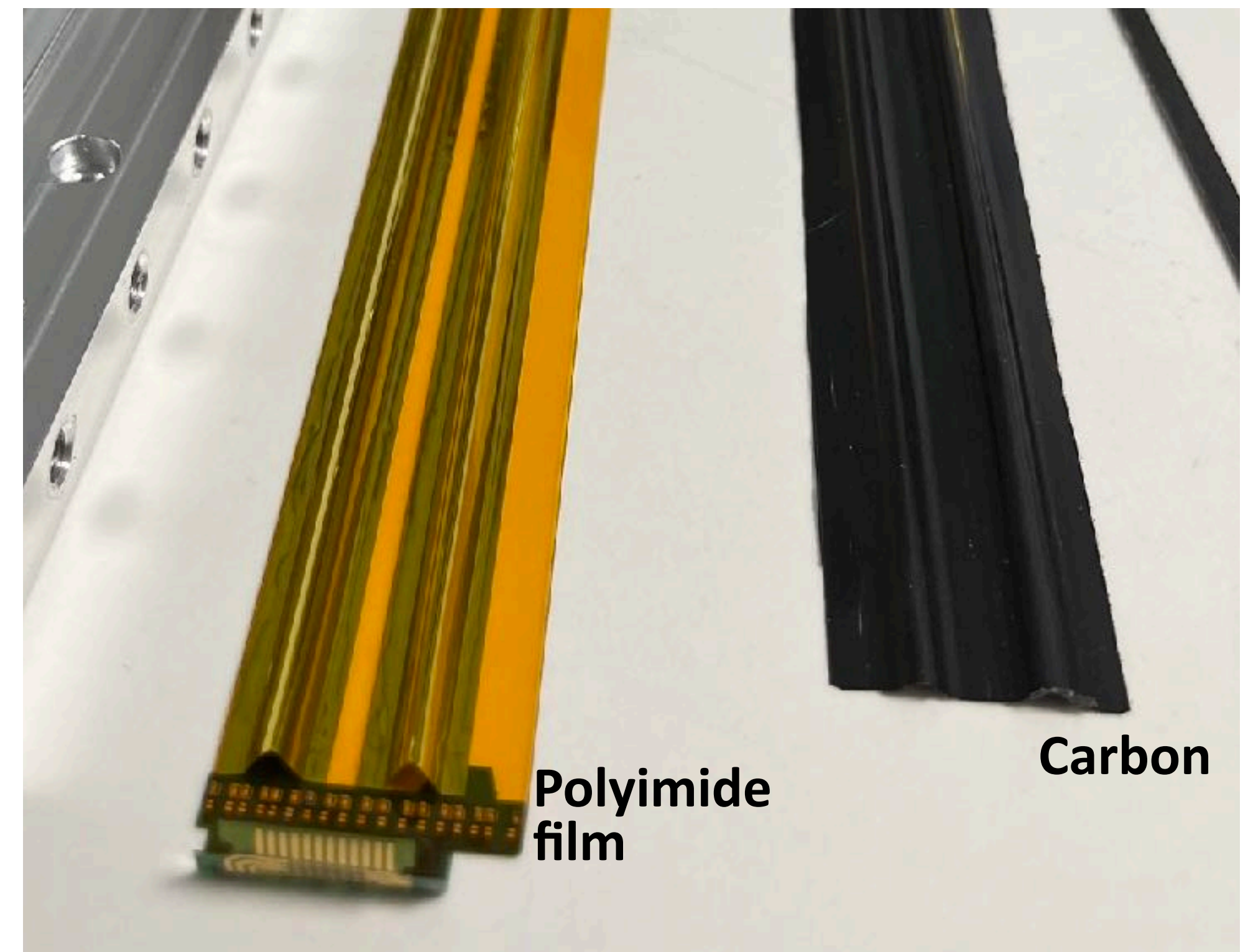
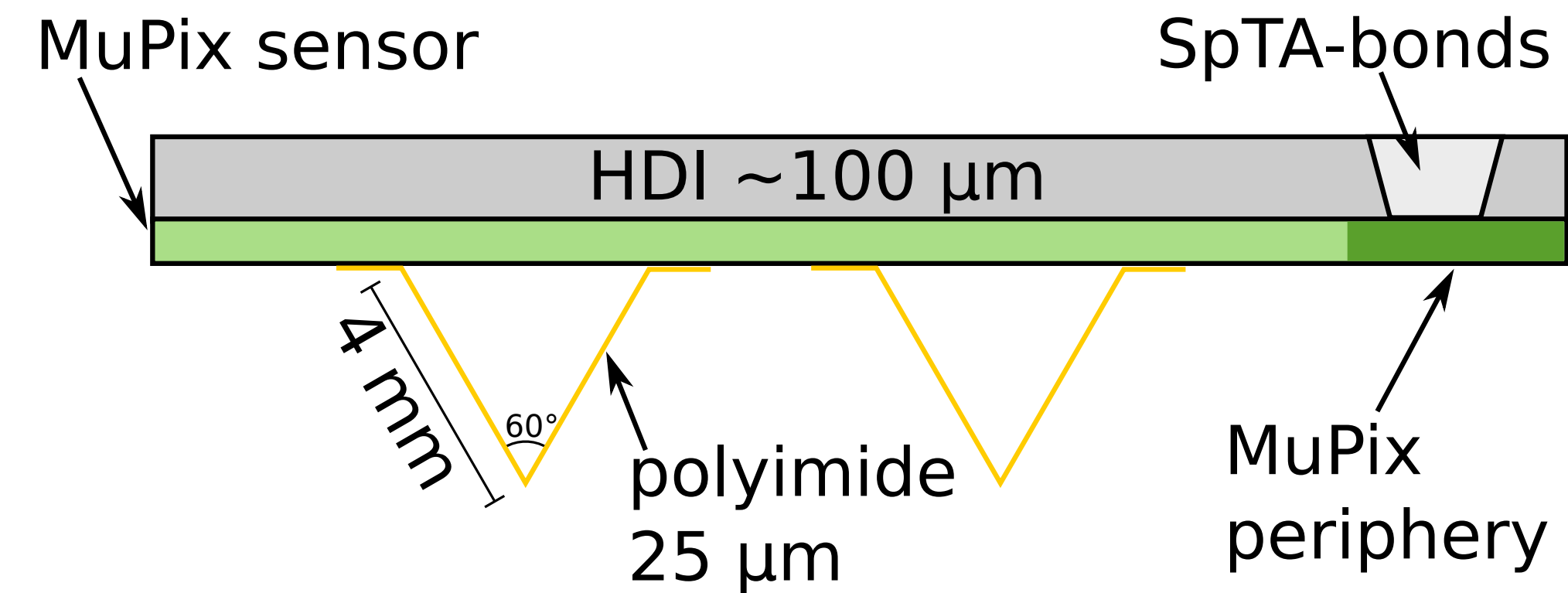
25µm thick folded in two triangles:

- Sensors/bonds mostly still visible underneath
- Quite delicate —> difficulties in transportation
- Barely enough structural integrity for 18 chip ladders

UD fibres (carbon, glass, kevlar):

25 µm uni-directional carbon-fibre, with joined:

- Moulded into double-u shape
- Co-cured polyimide film (8µm) backing - electrically separate two halves
- Very stiff along length (improves yield and transportation)



Fabrication of polyimide stiffeners:

A. McDougall

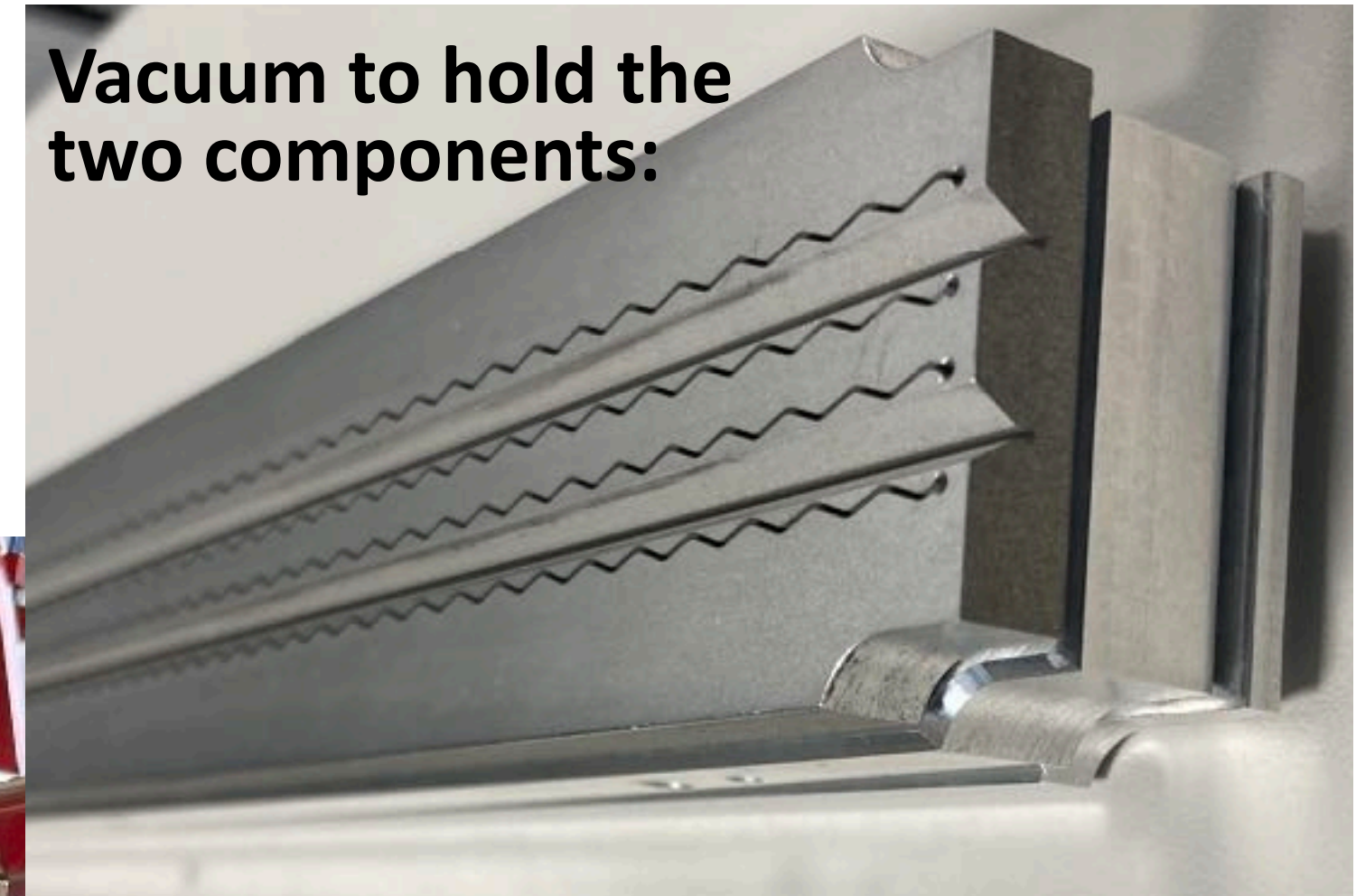
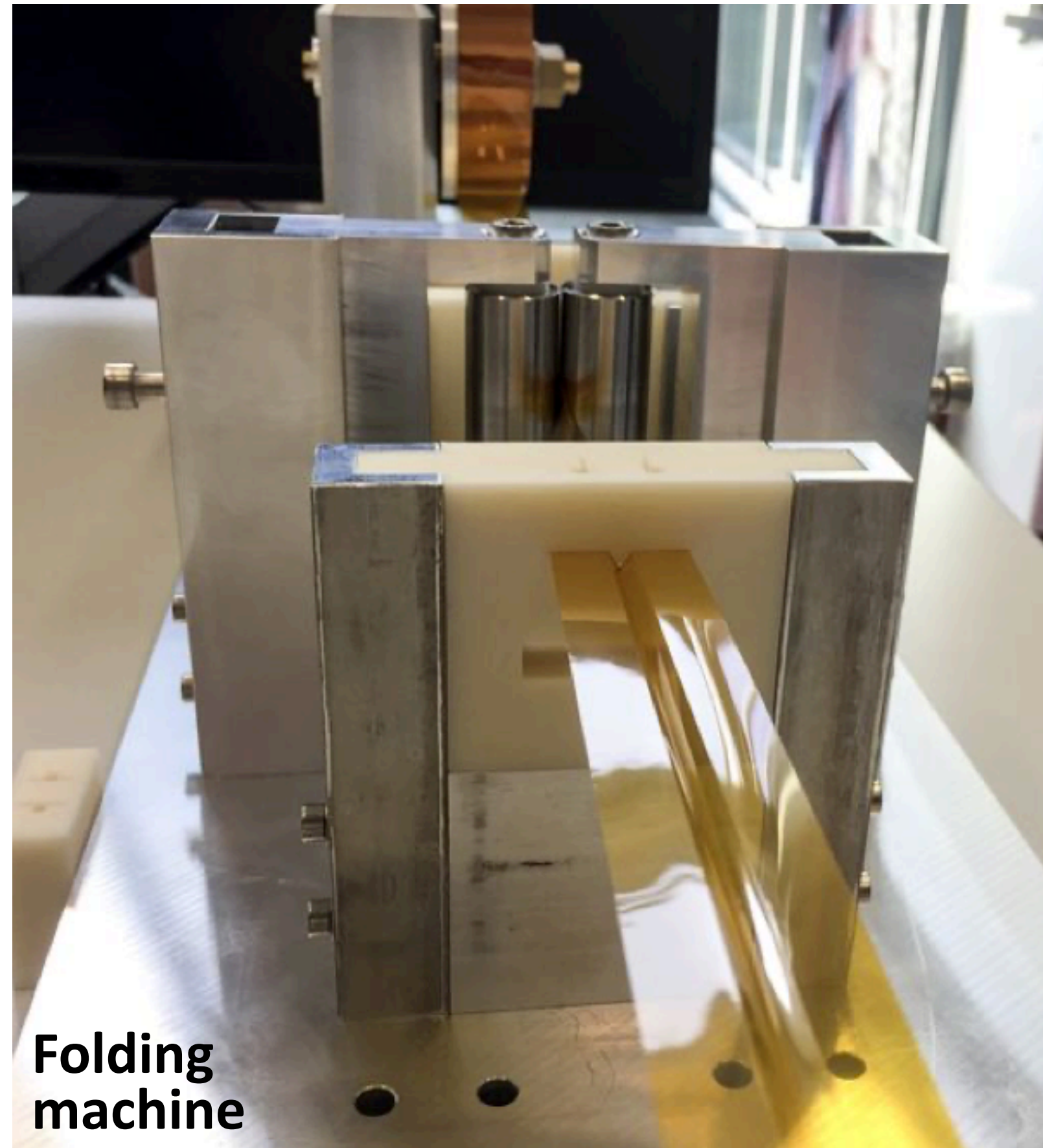


UNIVERSITY OF
OXFORD

25 μ m thick film folded in triangular shape: 2 per ladder

- Thin lines of glue along each of the v-folds
- Folded shape achieved by threading polyimide foil through “folding” machine

**Vacuum to hold the
two components:**



7

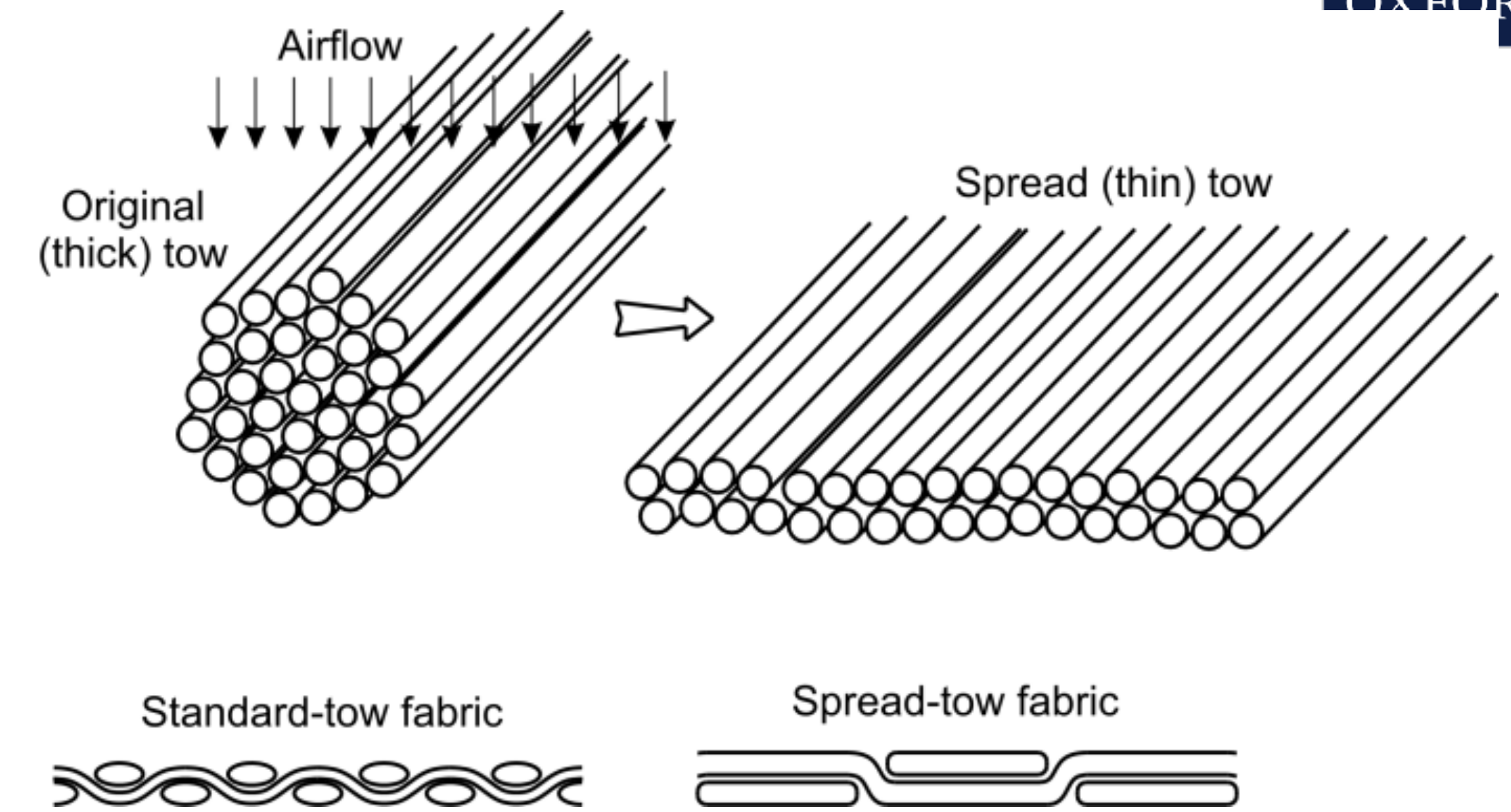
7

Uni-directional single-ply 25 μ m carbon-fibre sheet (40% resin content):

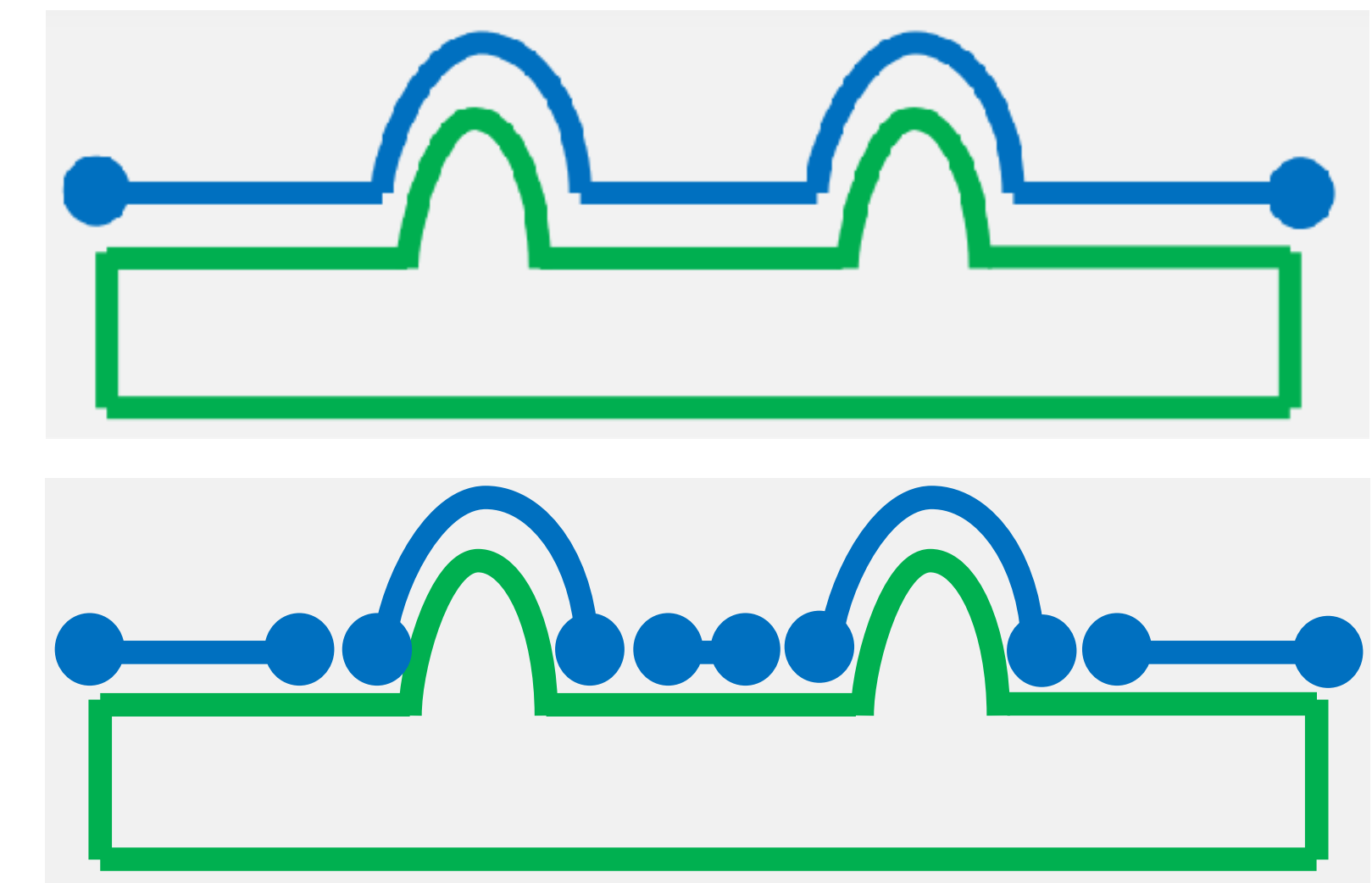
- Tairyl TC33 fibre and SK Chemicals K51 matrix
 - Material developed for sails for America's cup yacht (Allinghi)
 - Usually intended to be woven together

Mu3e design highly non-standard, no industry used case:

- **Spread tow**: results in much thinner ply- due to reduced tow thickness
- **Split-ply** laid together: compliance during warm up/cool down, additional resin to bleed off
- Material cured into double "u" shape, with 8 μ m polyimide film
- Average mass = 0.735 g

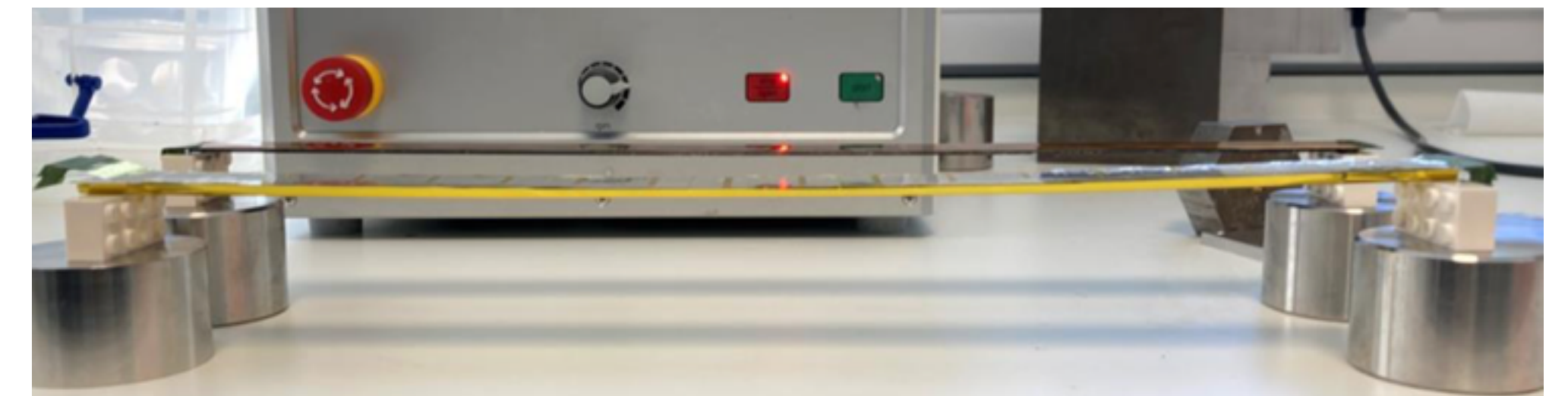
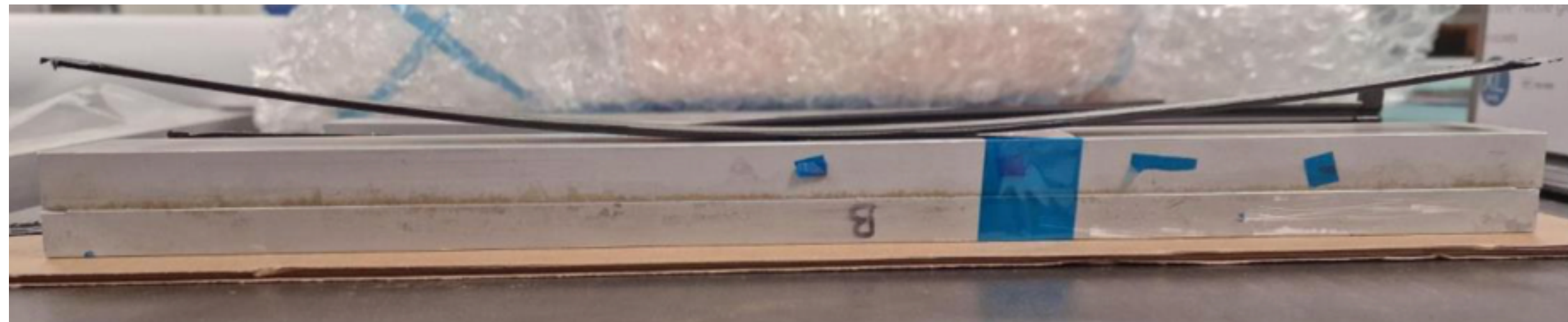


Single ply "normal" & logical approach:

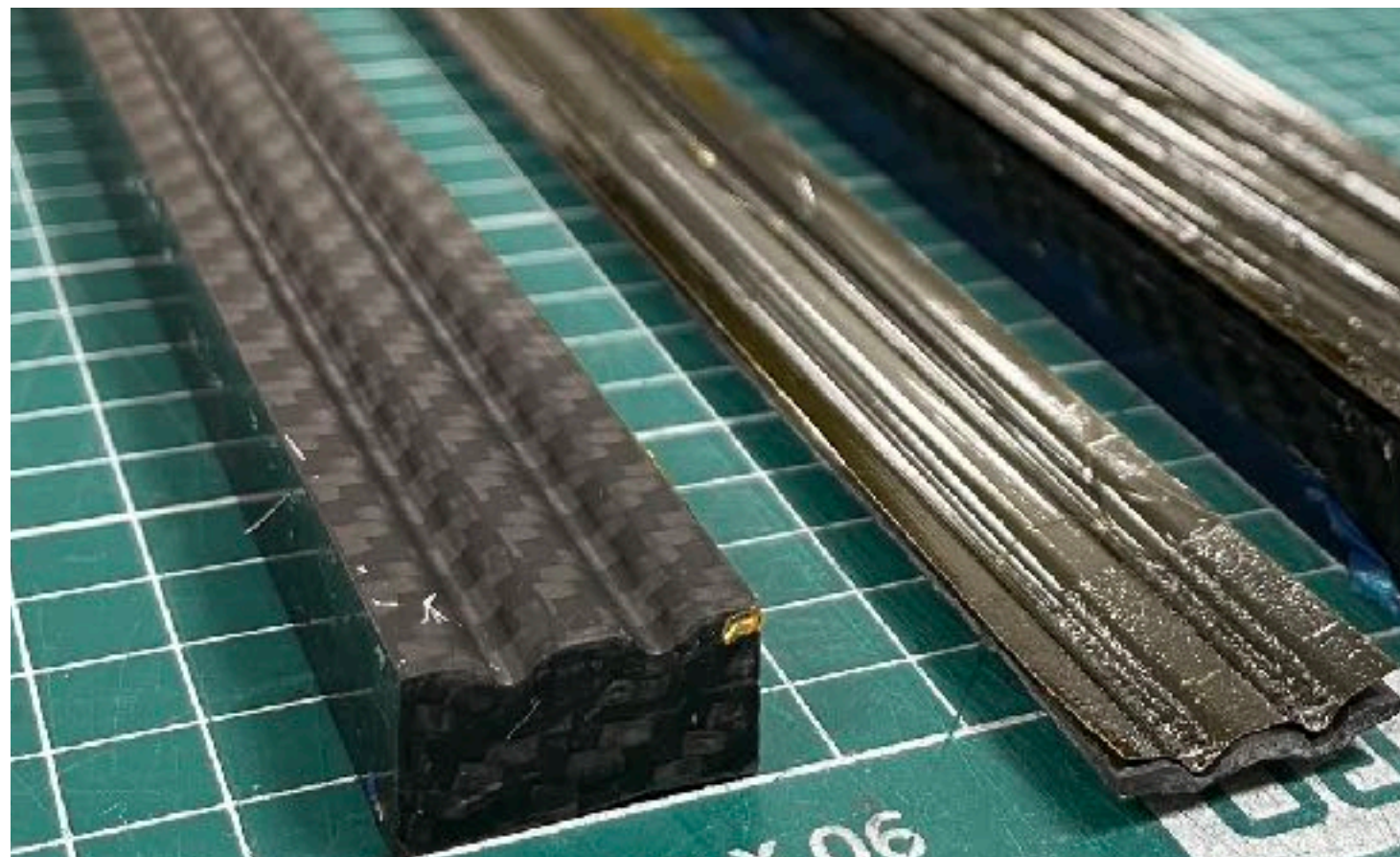


Very difficult material to work with; 'chaotic' fibre pattern:

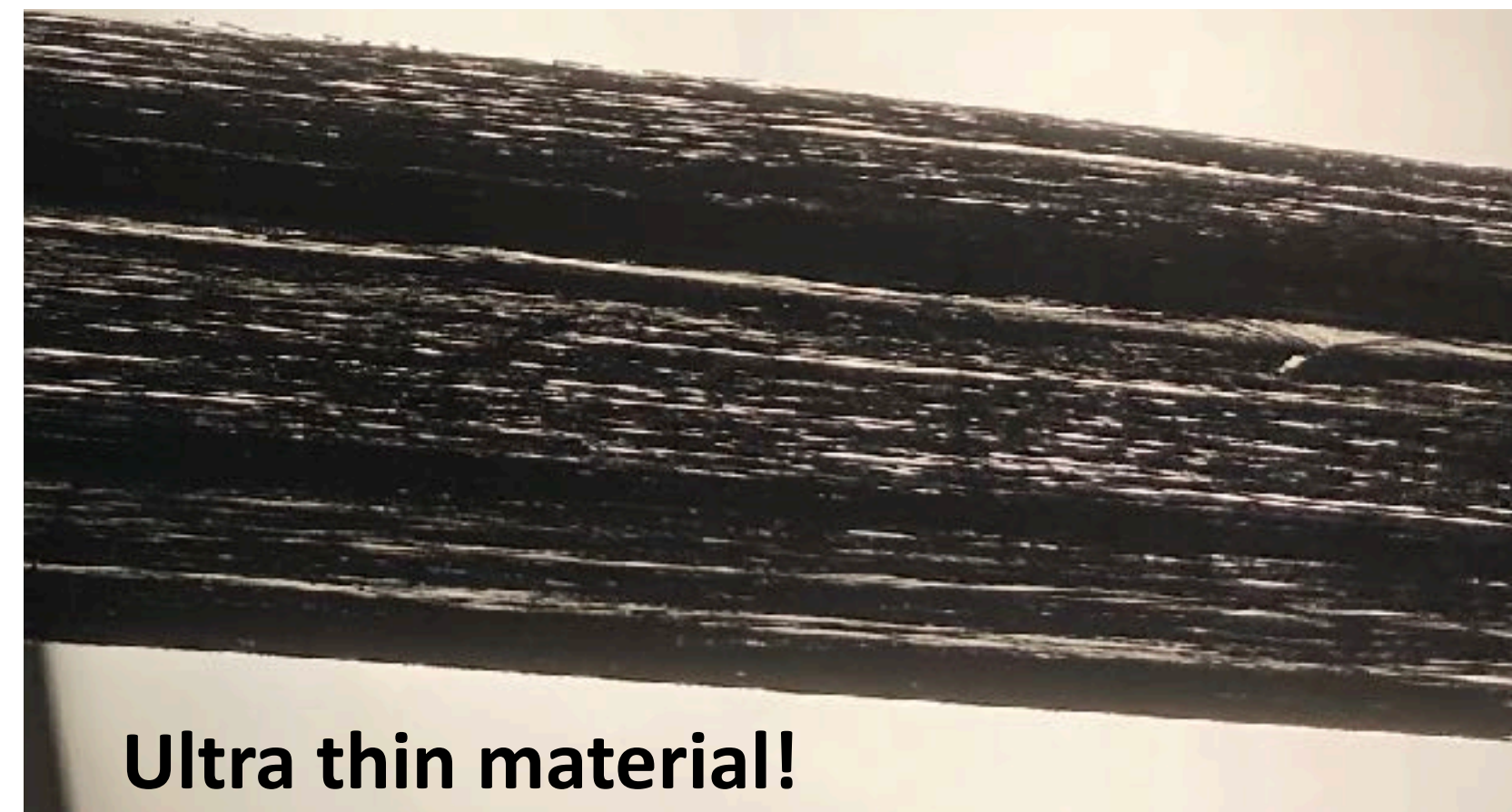
- Lot of development on the fabrication and laminating tooling and techniques (Oxford Physics Mechanical Engineering Workshop + Brick Kiln Composites)
- **Bowing** one of main issues: resolved using carbon-fibre mould tooling
- Polyamide film co-cure: difficult to remove from vacuum bags, often resulted in tearing the film.



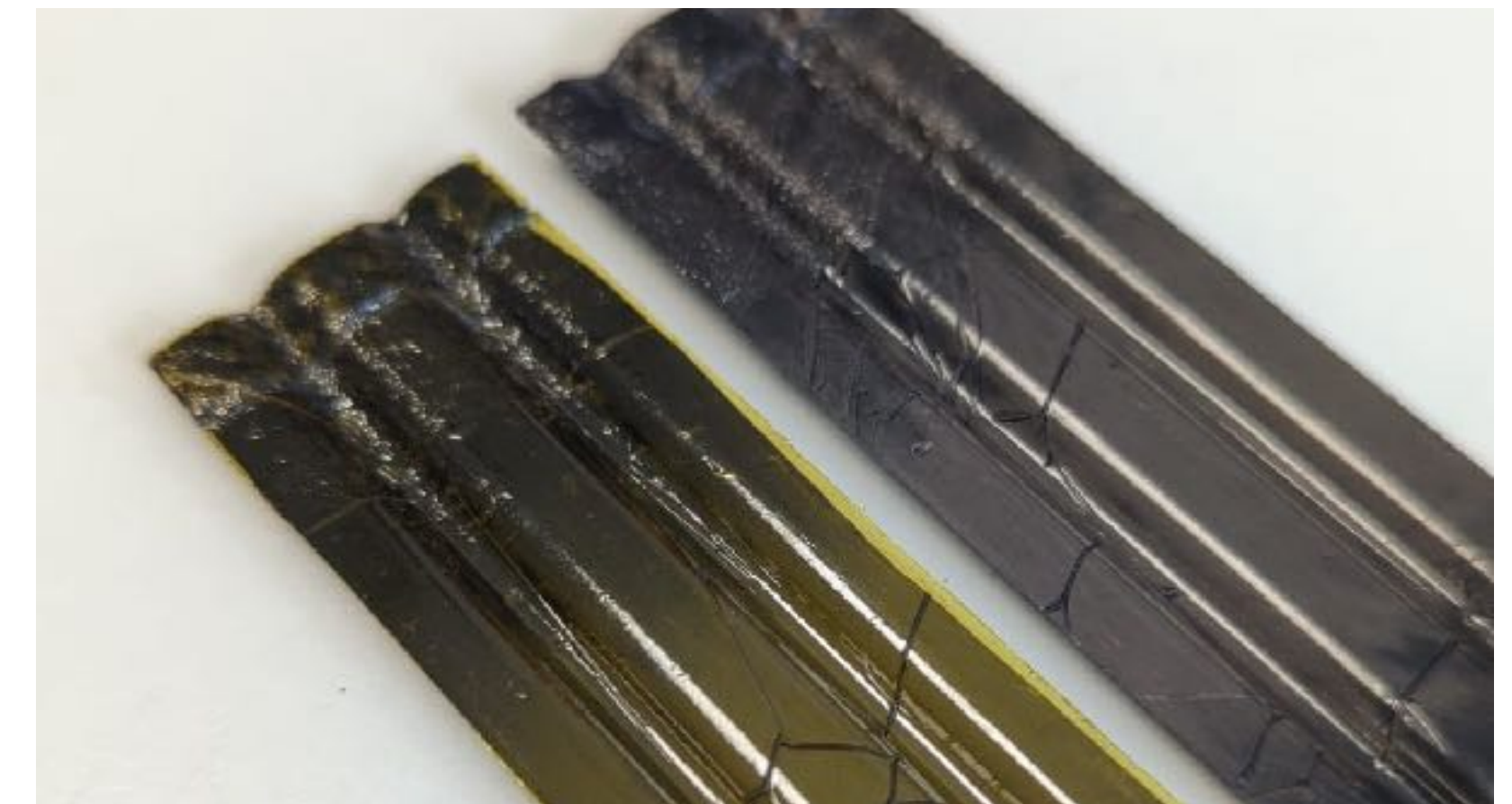
Stiffener comparison: polyimide v carbon-fibre supports



Carbon mould tool



Ultra thin material!





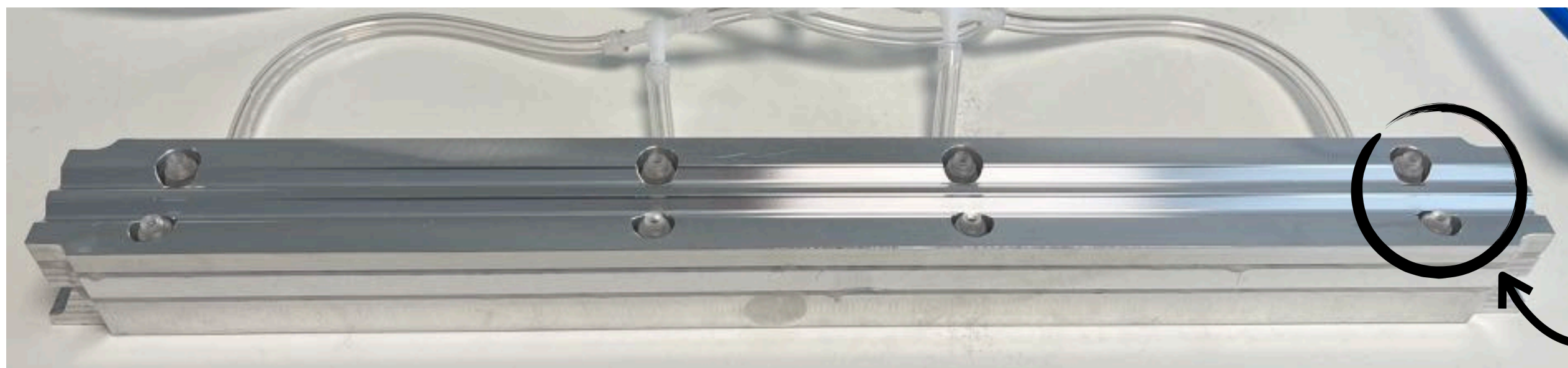
Observed issues with kapton stiffener attachment:

- Due to flexibility of material, had to put pressure along the whole stiffener to ensure good contact for glue curing
- Tooling was bowed so caused silicon to break

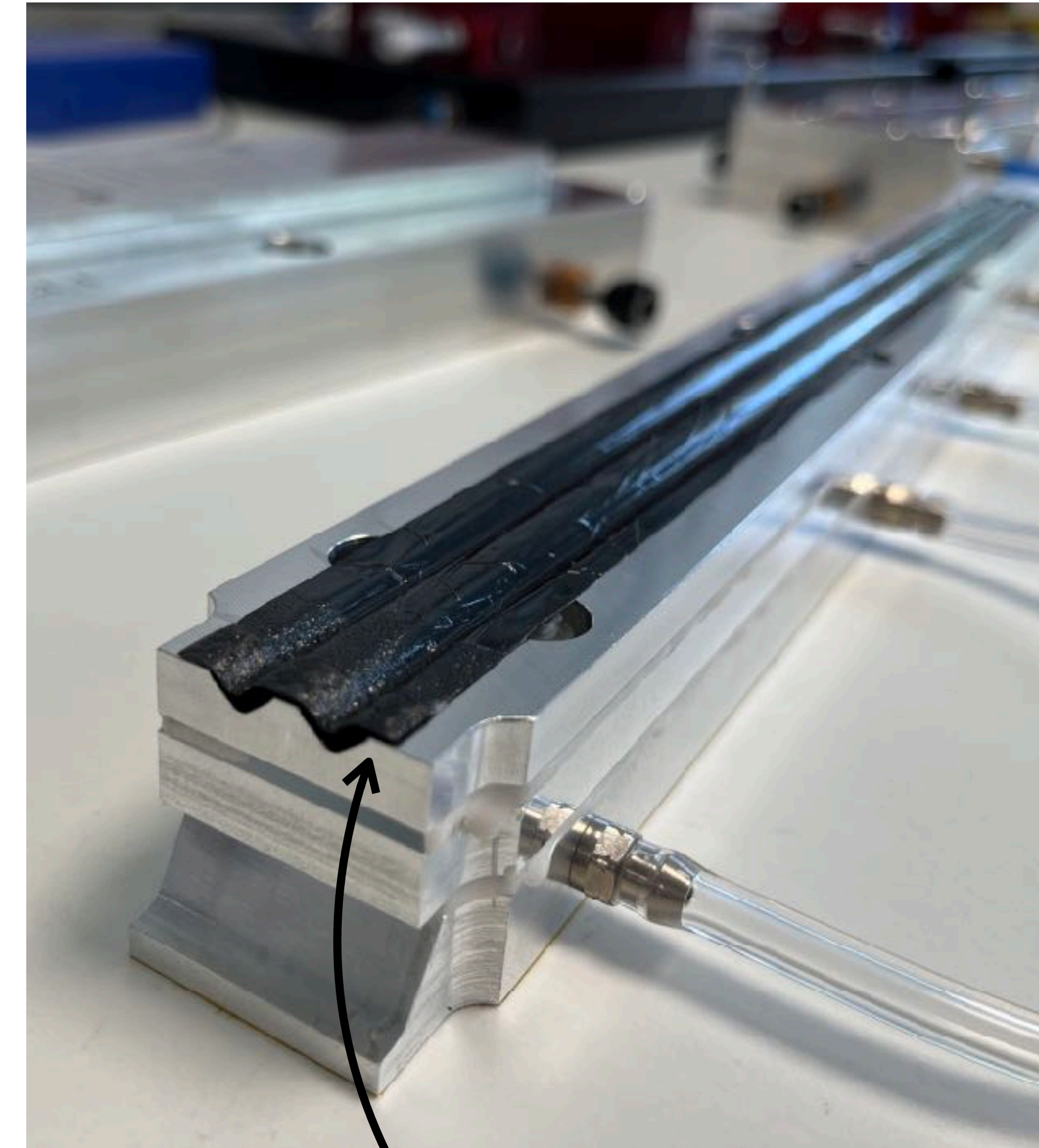
Carbon-fibre stiffener:

- Much stiffer; don't need as many points of contact to be held together sufficiently well

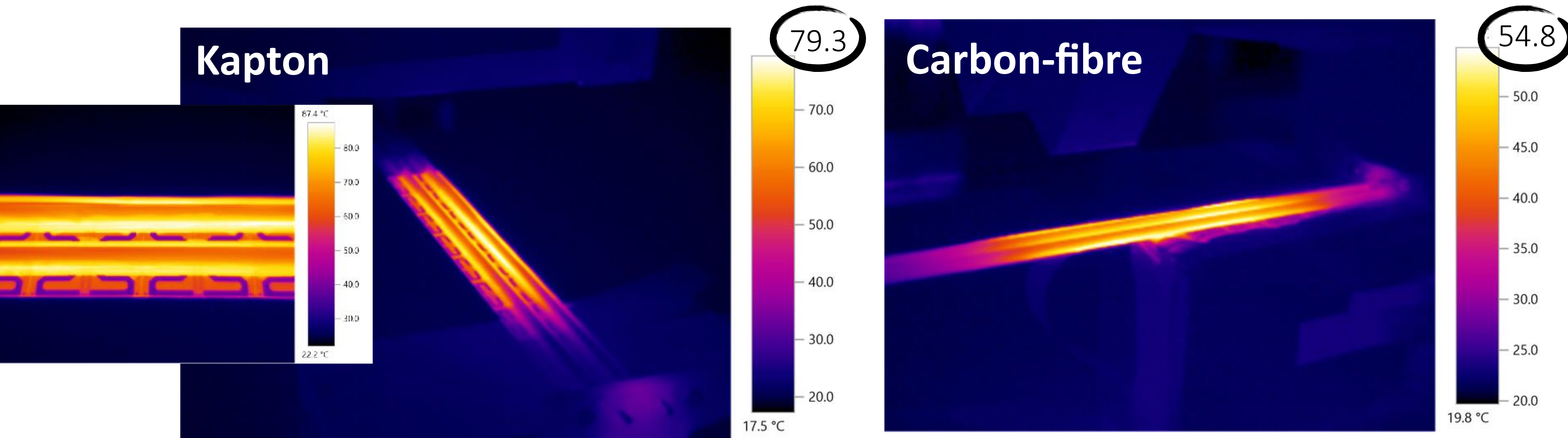
Tool to pick-up the carbon-fibre stiffener:



8 suction cups



Side-profile of stiffener



Measure **heat dissipation along ladder** when sensors are powered:

- Carbon-fibre better conductor than kapton: better at dispersing heat along the ladder length
- Carbon ladder reached much lower peak temperatures

Electrical performance with carbon-fibre supports:

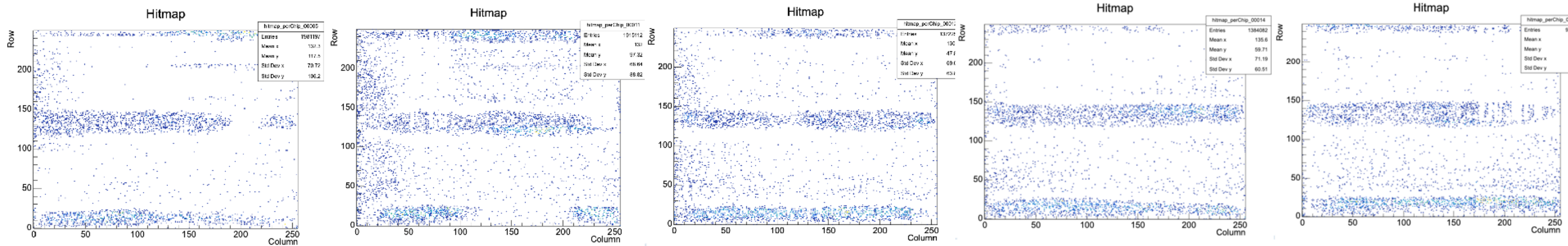
A. McDougall

When taking data with nominal ladder design, observed very high levels of noisy pixels:

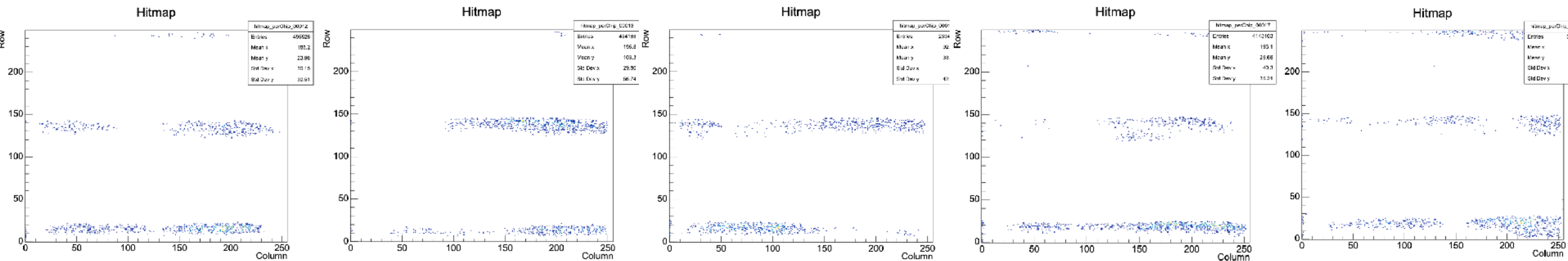
- Likely due to carbon-fibre being glued to back (biased) side of pixel sensor



ThHigh @ 116, HV -30V

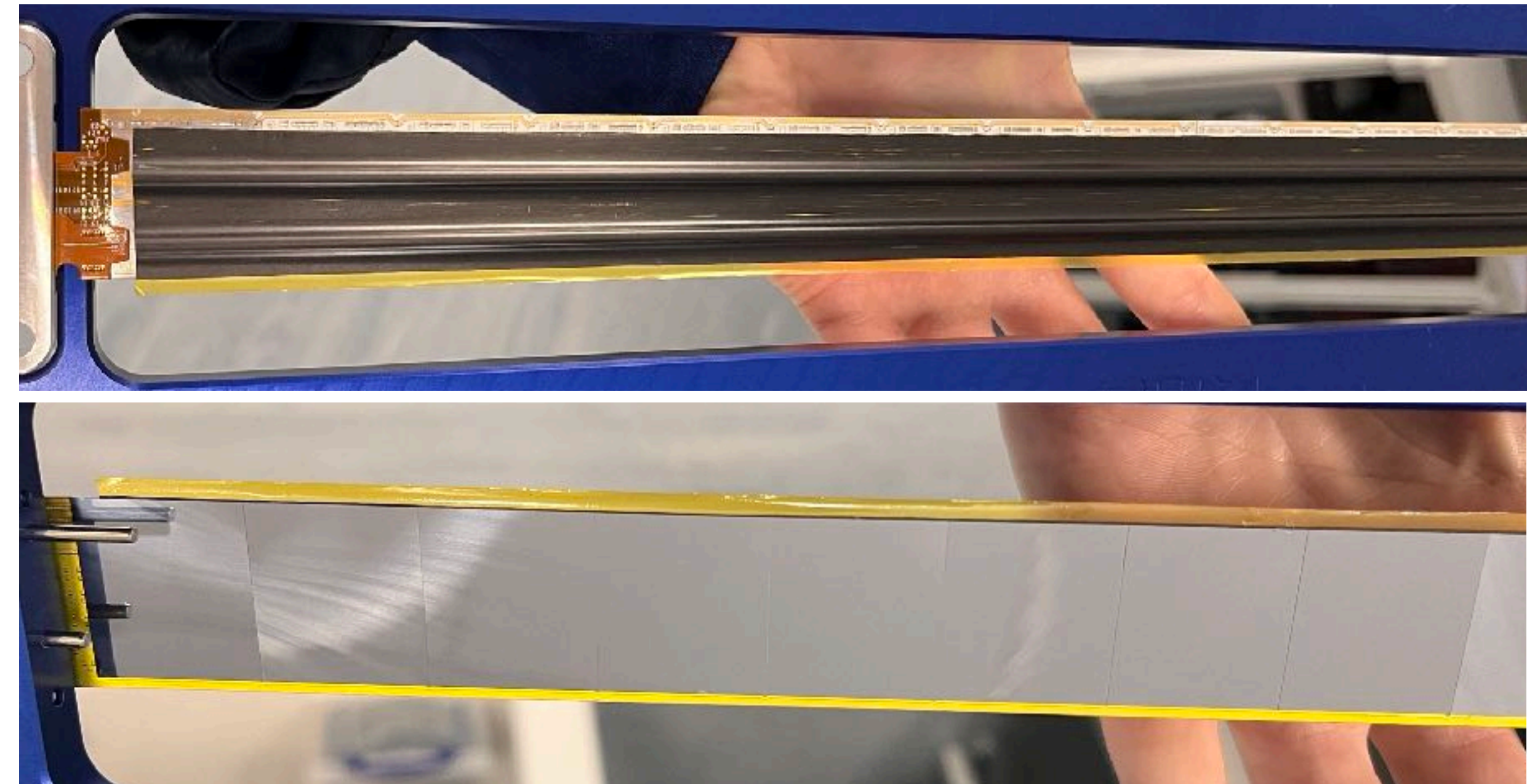
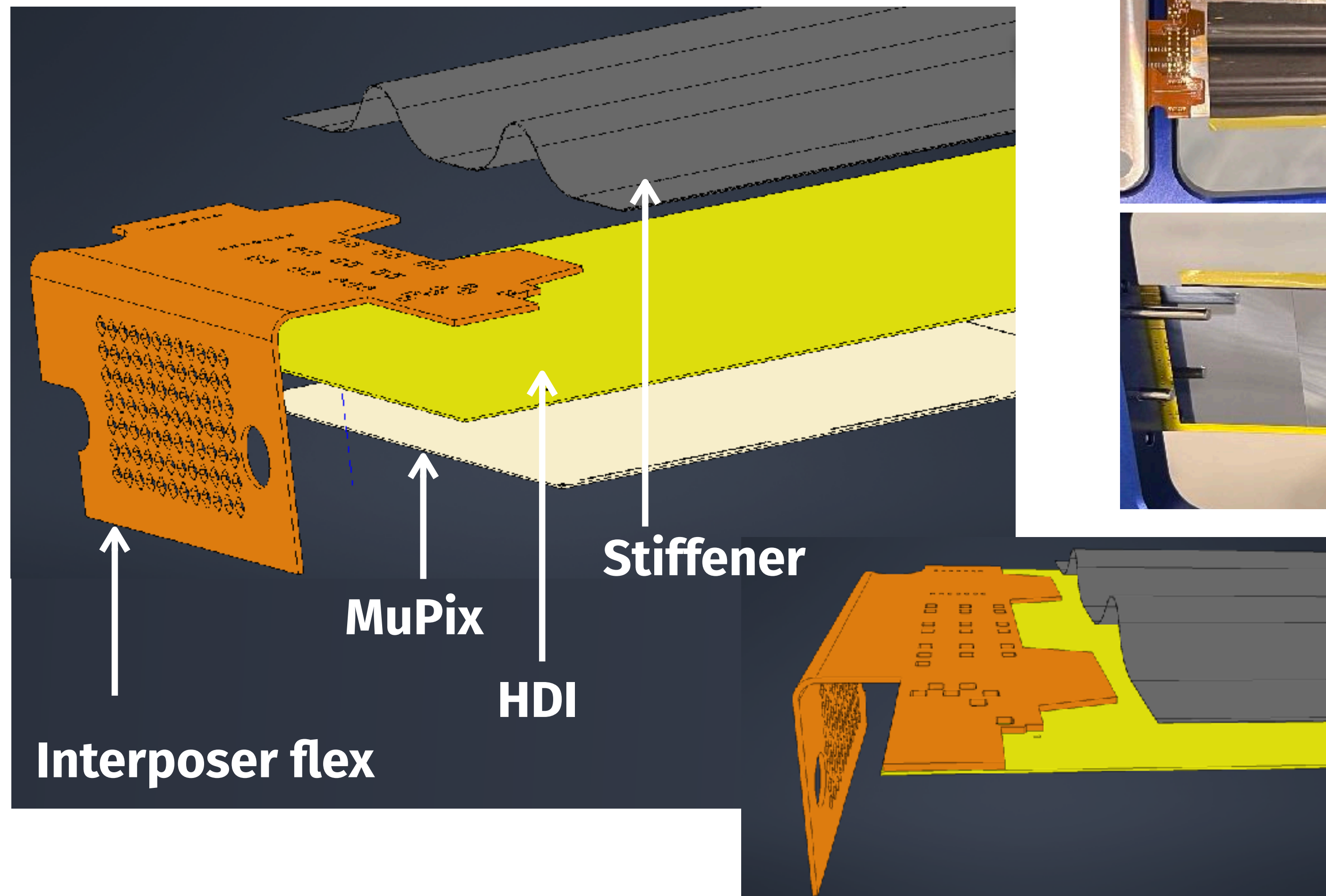


ThHigh @ 130, HV -30V

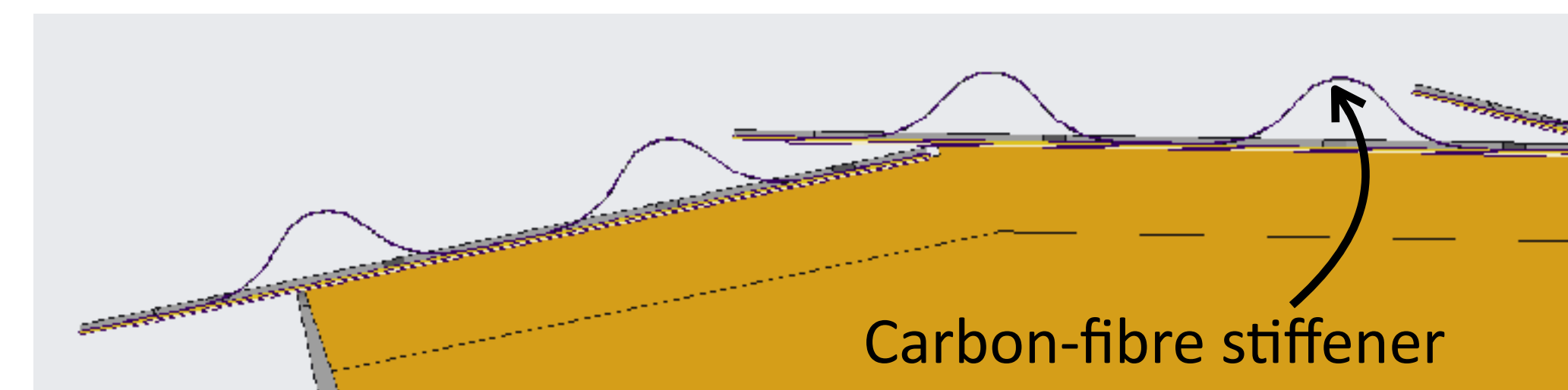


Place stiffener on other side of ladder:

- 25 μ m carbon-fibre + 8 μ m kapton
- Kapton glued to HDI surface



Side on view of the module:

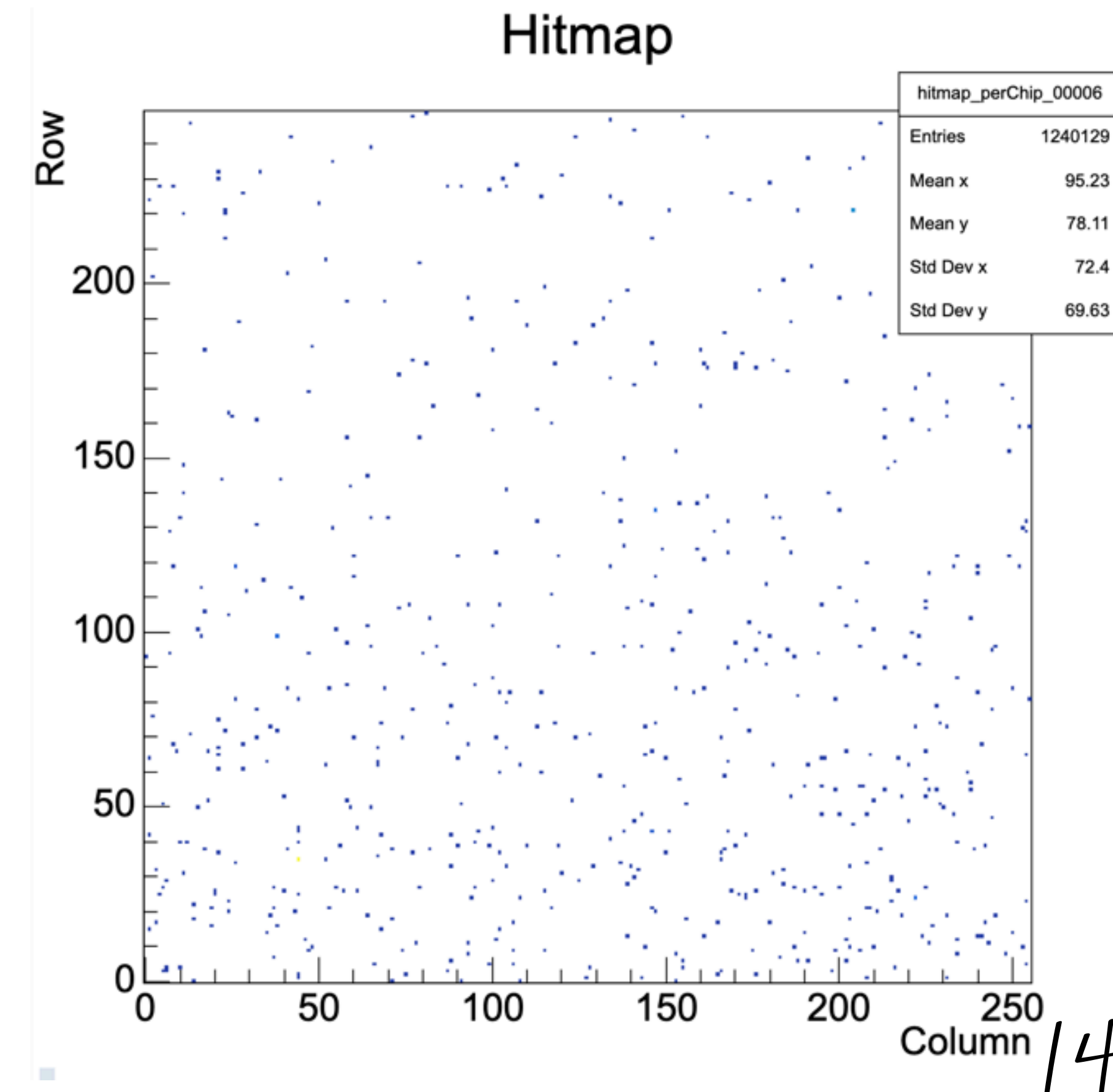
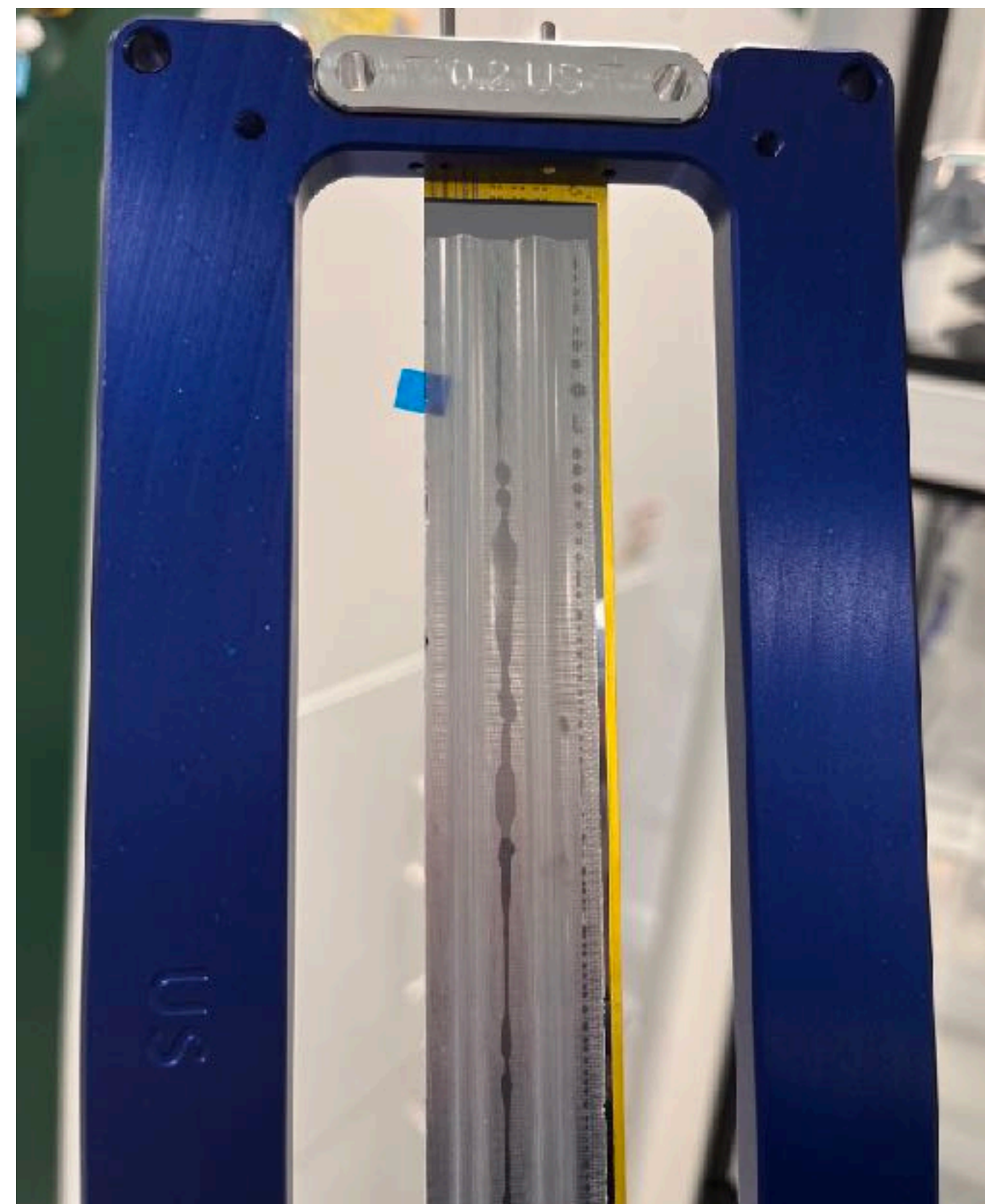
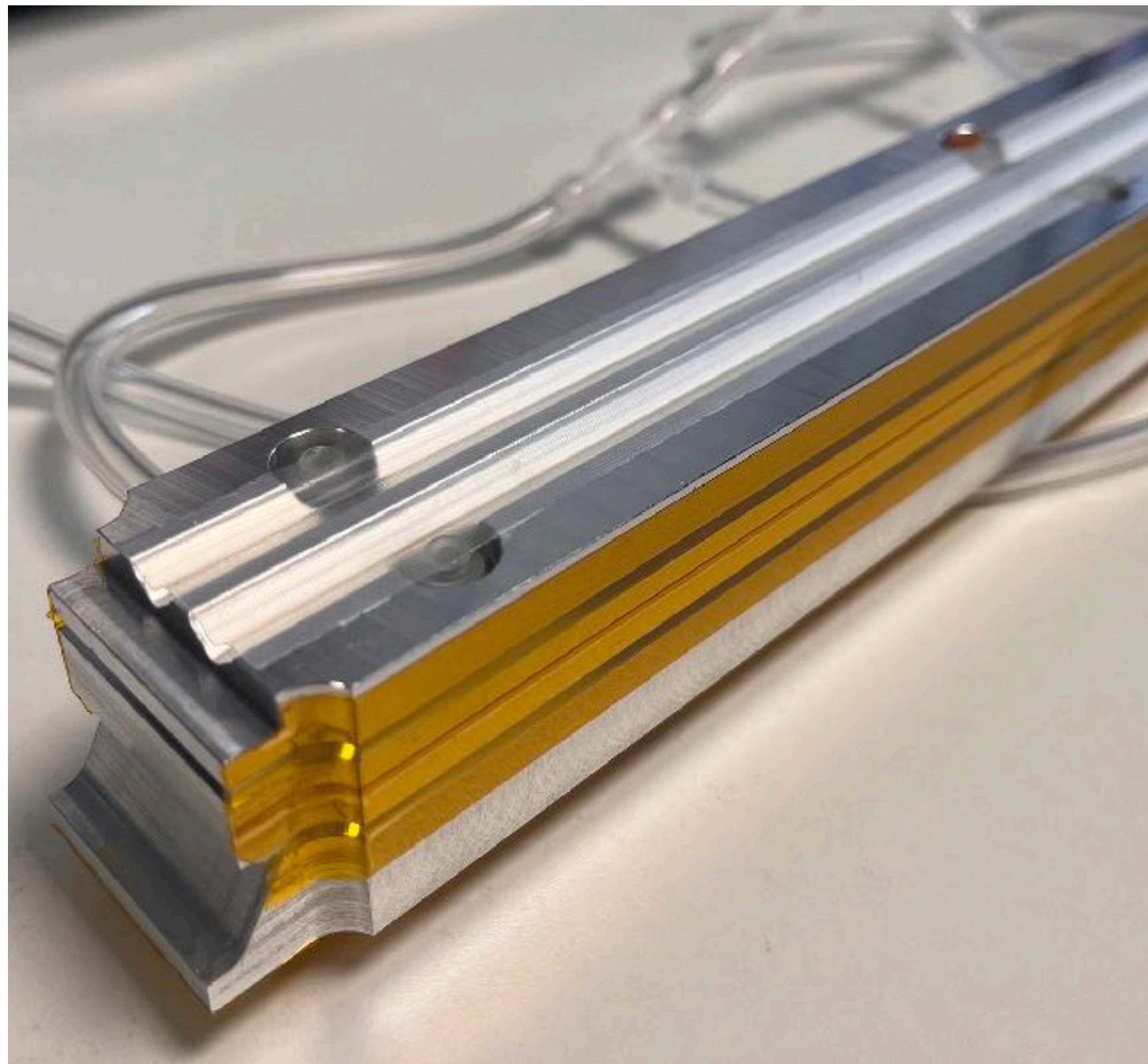


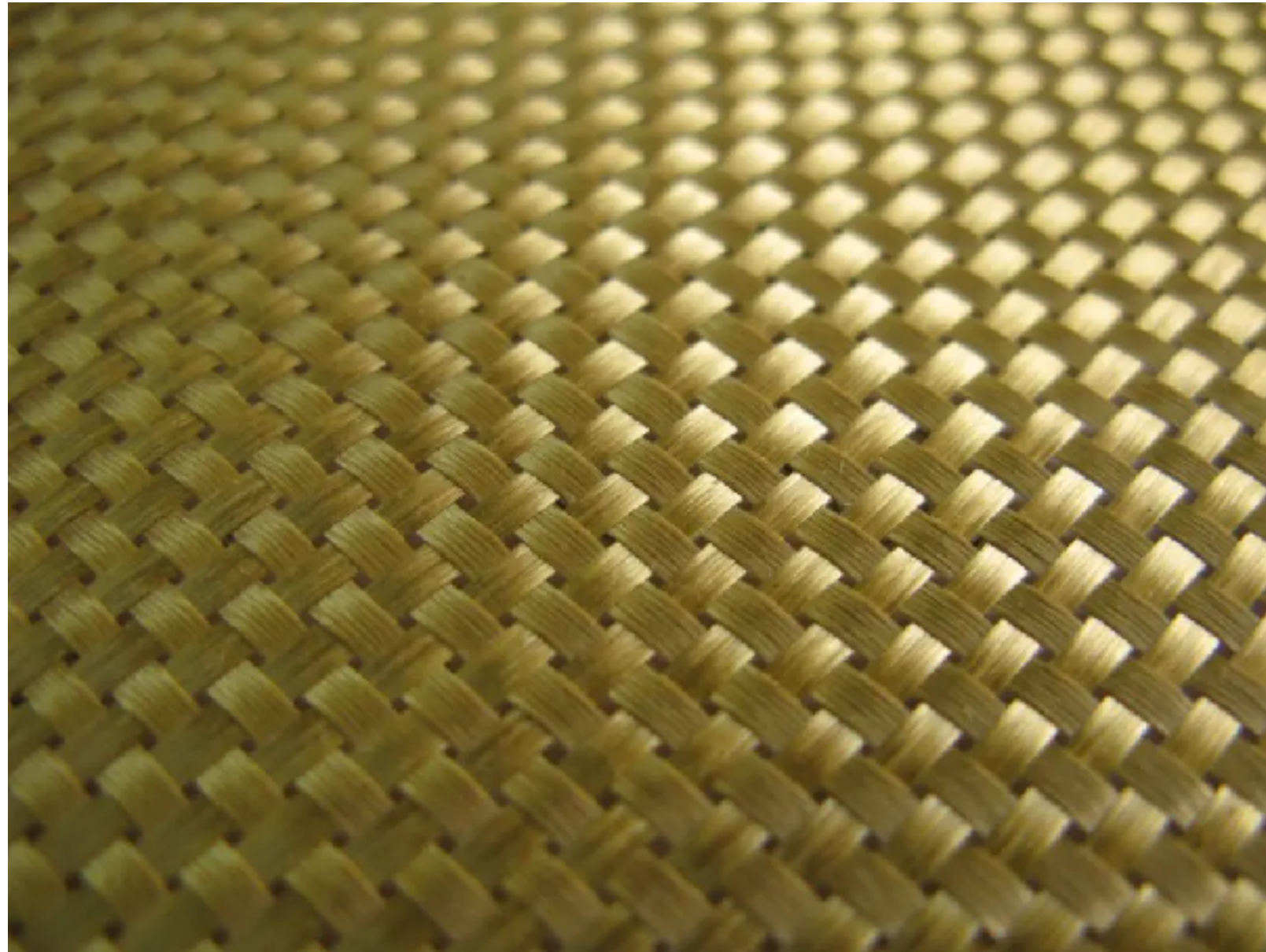
Alternatively to carbon-fibre, **stiffener made from glass fibres** (insulating material):

- First try with 60GSM ($\approx 60\mu\text{m}$) material, to see if same fabrication procedure viable (cross-weave instead of UD)

Production observations:

- Slightly bowed
- Material is quite flaky
- Difficulty picking up with “pick-up” tool (geometry)
- No issues with noisy pixels observed



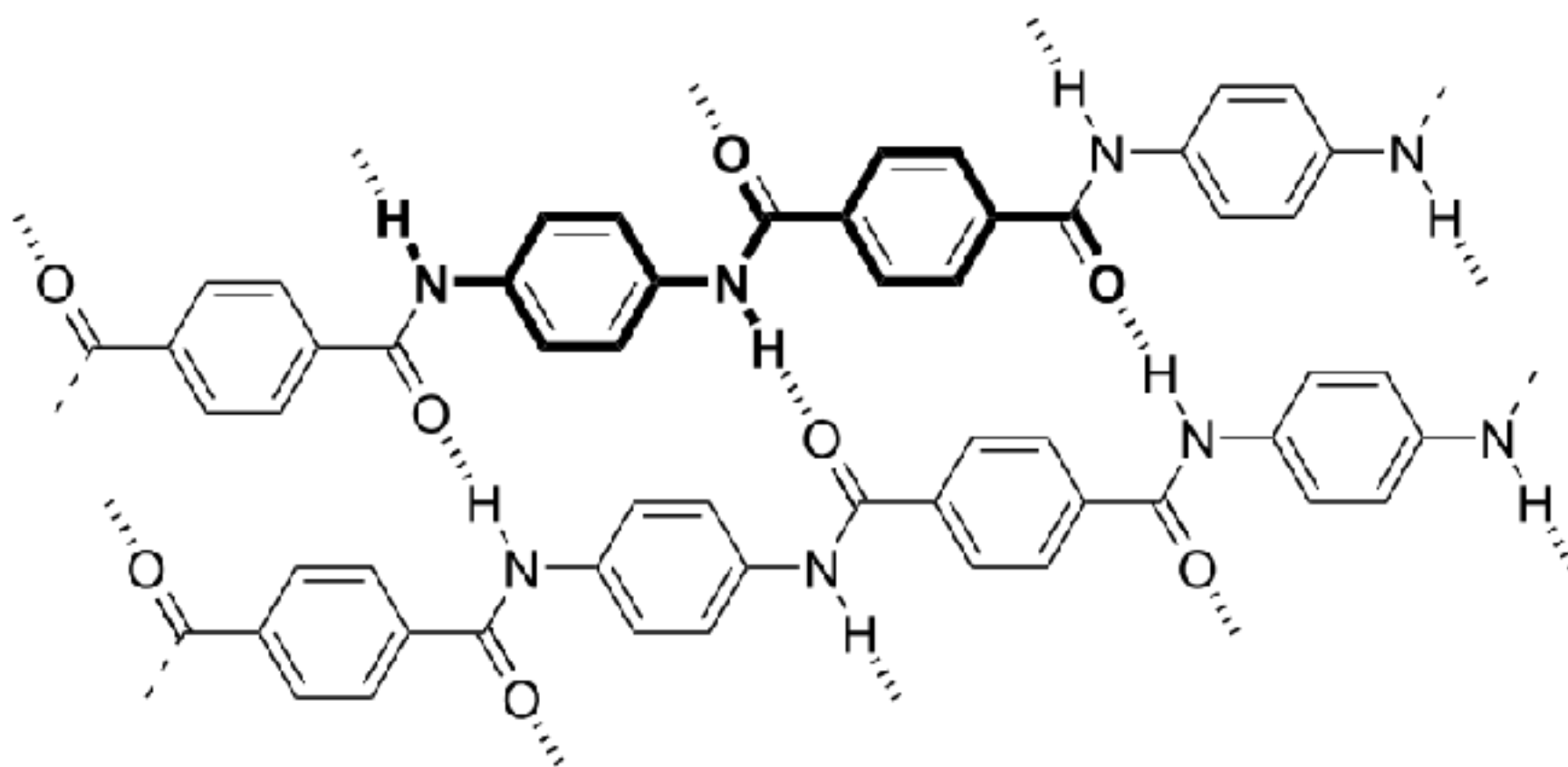


Properties:

- Material: Aramid (aromatic polyamide fibres), presence of **aromatic rings** of six carbon atoms
- Insulating material
- Available at **10µm** (thinnest possible option we've seen)

Strategy:

- 10 m² of material has been ordered (plenty for validation tests)
- Need to verify flatness requirement, and if any bowing occurs during manufacturing
- Continue with kapton co-cure
- Results to come!



Fabrication procedure for outer pixel layers:

A. McDougall

Entire ladder production for the outer pixel tracker in Oxford cleanroom

Ladder —> module —> layer:

- 17 (18) x MuPix11 sensors in layer 3 (4)
- 4 ladders per module
- 6 (7) modules in layer 3 (4)

Total per station: 52 ladders (912 sensors)

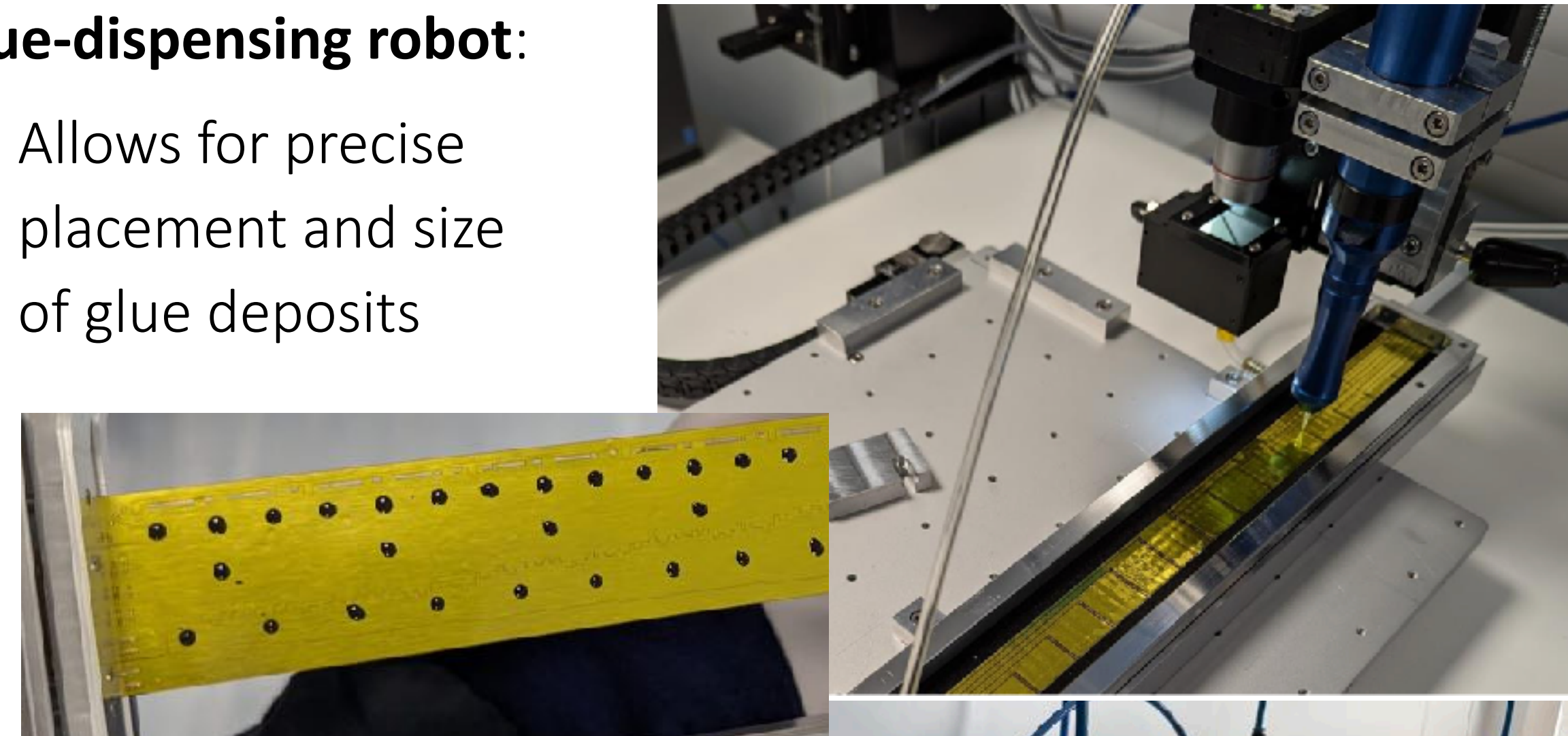
Automate ladder building procedure as much as possible:

- Robotic **gantry used for placement of chips**



Glue-dispensing robot:

- Allows for precise placement and size of glue deposits



Vacuum assembly tooling for correct placement of components onto ladders:



Mu3e on the cutting edge of ultra light-weight pixel tracking detectors!

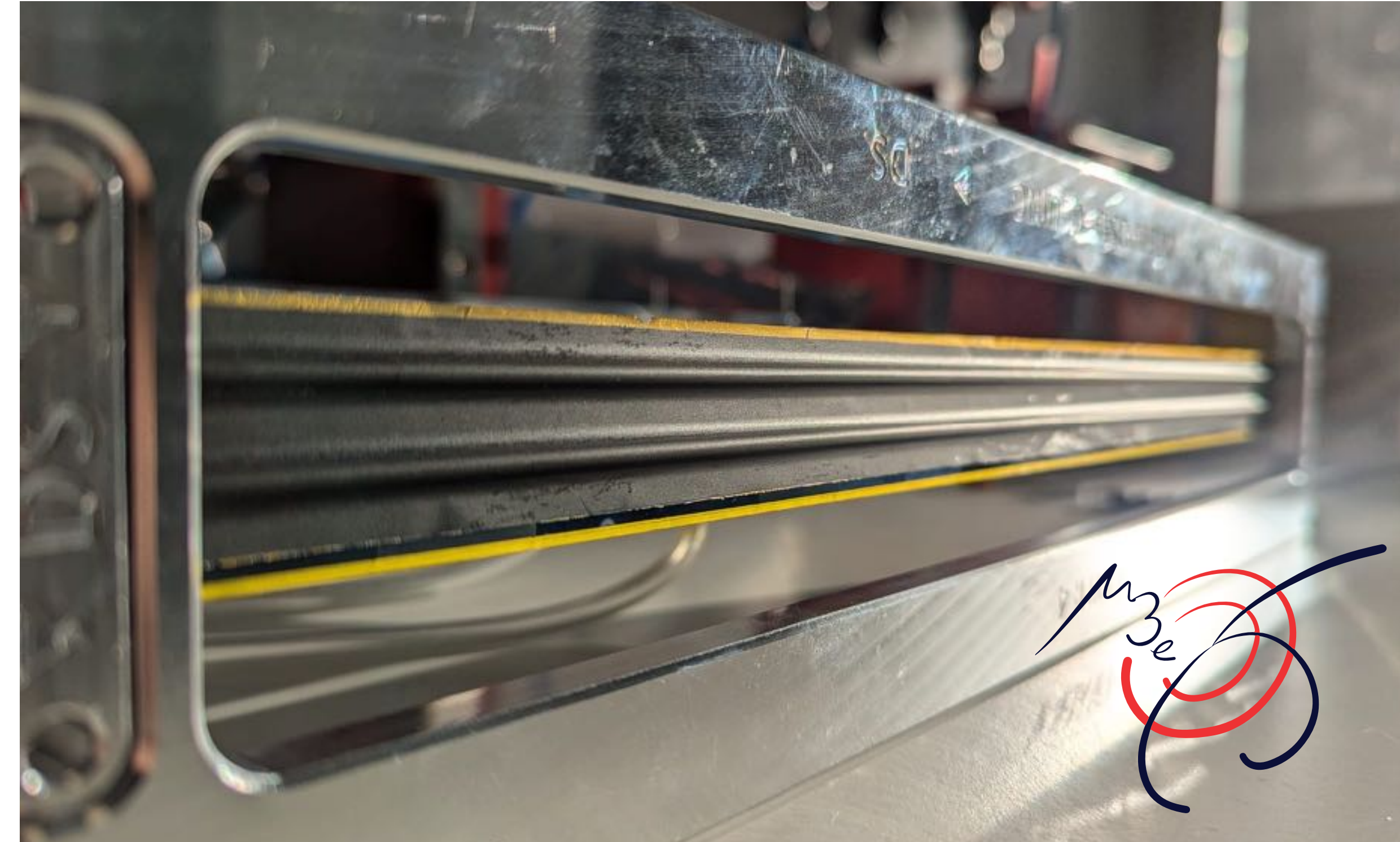
- Each ladder ~ 2 grams! Despite being over 30 cm long.

Investigations into choice of stiffener material:

- Polyimide film, UD carbon-fibre, glass fibres, UD kevlar all been studied.
- Carbon-fibre demonstrates favourable properties: thermally, stiffness, handleability; some noise issues observed
- Kevlar thinnest possibility @ $10\mu\text{m}$!

Production of outer pixel ladders on-going.

Expect physics data-taking to commence in 2026!



Stay tuned ... !

[[Mu3e collaboration](#)] | [ashley.mcdougall@physics.ox.ac.uk]

[adam.lowe@brickkilncomposites.com] | [[Brick Kiln](#)] 17