# A Silicon Pixel Tracker for future µSR Experiments

# Enabling more precise and efficient investigation of **magnetic** and **superconducting** materials through **vertex reconstruction**

Muon Spin Rotation/Relaxation/Resonance (μSR) is used to measure local magnetic fields within a sample material. Parity violation in muon decay results in an anisotropic positron emission that correlates with the muon's spin direction. Magnetic fields present in the material affect the muon's spin precession, which can be quantified by the positron emission rate.



# HV-MAPS

- High-Voltage Monolithic Active Pixel Sensor
- Embedded readout electronics in deep n-wells within substrate
- Reversely biased substrate for fast charge collection via drift

#### Mupix11 specifications:

- Active area:  $20 \times 20 \text{ mm}^2$  Pixel size:  $80 \times 80 \text{ }\mu\text{m}^2$
- Can be thinned down up to 50 µm (< 7 × 10<sup>-4</sup> X<sub>0</sub>)
  ⇒ Ideal for low momentum particle tracking



# Mupix11 Quad Module



Module with large active sensor area for beam monitoring and µSR detector prototype

#### Specifications:

- 2 × 2 grid of 50 μm Mupix11 sensors
- 25 μm Kapton foil for structural support
- Active area:  $40 \times 40 \text{ mm}^2$
- Sensor spacing: 200 μm





### Scintillator-Based Detector

#### **Principle:**

- Scintillators measure Time-of-Arrival of incoming muon & emitted positron
  - temporal evolution of asymmetry between forward and backward signals

#### **Disadvantages:**

- No position information of muon decay
- Maximal 1 muon per time window of 10 μs
  ⇒ veto logic to filter out pile-up and non-decayed muons
  - $\Rightarrow$  limited acceptance rate of  $\sim 18 \text{ kHz}$



top view



Sensor alignment

Sensor gluing

#### DAQ:

- Minimal, Mu3e compatible DAQ setup
- Optional scintillator input for improved timing



## **Pixel-Based Detector**

#### **Principle:**

- Barrel of inner and outer pixel layer
- Incoming muons and outgoing positrons tracked by pixel sensors
- ⇒ Trajectory ⇒ Stopping position ⇒ Time of arrival
- Optional scintillator tiles to improve time resolution

#### Advantages:

 Vertex reconstruction allows to differentiate between several simultaneous events and their origin



side view

# Detector Prototype

- 4 Quad Module layers:
  - 2 upstream sample 2 downstream
- Sensor cooling options:
  - Air-cooling via fan

14 mm

• Water-cooling of frame and backplate heatsinks

	Sample	holder	
Upstream			Downstream
lavers			lavers



 Expected position uncertainty: Positron ≤ 1 mm (for 100 MeV muons) Muon ≤ 0.6 mm
 ⇒ Increased muon rate by 10 − 100 times

- ⇒ Several smaller samples possible at once
- $\Rightarrow$  Increased observation time of  $\sim 20 \ \mu s$

#### Goals:

- Prove of principle
- Detector characterization & cooling studies
- Resolve 1 mm structures
- Measure upper limit of muon rate increase





7 – 36 mm

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